## **CRTP PERFORMANCE OVER IEEE 802.11**

## FOR VOIP APPLICATIONS

by

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# A PROJECT SUBMITTED IN PARTIAL FULFILLMENT OF THE REQUIREMENTS FOR THE DEGREE OF MASTER OF ENGINEERING

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## ABSTRACT

The deployment of IEEE 802.11 WLAN networks and Voice-over-IP (VoIP) systems in offices and homes has surged in recent years, and will likely continue its growth. Due to its wireless nature, 802.11 networks still trail its wired equivalents in bandwidth and transmission rates. On the other hand, Voice-over-IP and other real-time applications are very capable of consuming bandwidth and overwhelming networks that are unable to handle their rapid-succession traffic streams. The wireless network bandwidth limitations therefore set the stage as a bottleneck, and can greatly impact the perceived quality of VoIP connections.

In this report, the effectiveness of RTP header compression (cRTP) and silence suppression (SS) applied to typical Voice-over-IP traffic over 802.11 wireless networks is investigated through integrated simulations. Both IEEE 802.11 distributed coordination function (DCF) and point coordination function (PCF) networks are examined, with results showing that PCF distributed systems are more suitable toward real-time traffic such as VoIP. The reduction in packet count and packet sizes result in better perceived connection quality through shorter end-to-end delays and reduced packet loss. Correspondingly, the witnessed improvements also allow more users to be accommodated in a particular network before reaching the same quality-affecting threshold.

## DEDICATION

This work is dedicated to my family for their unconditional love and support in all aspects of my life.

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## **ABBREVIATIONS AND ACRONYMS**

ACK	Acknowledgement
AP	Access Point
BSA	Basic Service Area
BSS	Basic Service Set
CBR	Constant Bit Rate
CID	Context ID
CFP	Contention Free Period
СР	Contention Period
CSRC	Contributing Source
cRTP	Compressed RTP
CSMA/CA	Carrier Sense Multiple Access / Collision Avoidance
CTS	Clear-to-Send
<b></b>	Contention Window
CW	Contention window
CW DCF	Distributed Coordination Function
CW DCF DIFS	Distributed Coordination Function DCF Interframe Space
CW DCF DIFS DS	Distributed Coordination Function DCF Interframe Space Distribution System
CW DCF DIFS DS DSSS	Distributed Coordination Function DCF Interframe Space Distribution System Direct Sequencing Spread Spectrum
CW DCF DIFS DS DSSS ESS	Distributed Coordination Function DCF Interframe Space Distribution System Direct Sequencing Spread Spectrum Extended Service Set
CW DCF DIFS DS DSSS ESS IBSS	Contention Window         Distributed Coordination Function         DCF Interframe Space         Distribution System         Direct Sequencing Spread Spectrum         Extended Service Set         Independent Basic Service Set
CW DCF DIFS DS DSSS ESS IBSS IEEE	Contention WindowDistributed Coordination FunctionDCF Interframe SpaceDistribution SystemDirect Sequencing Spread SpectrumExtended Service SetIndependent Basic Service SetInstitute of Electrical and Electronics Engineers
CW DCF DIFS DS DSSS ESS IBSS IEEE IFS	Contention WindowDistributed Coordination FunctionDCF Interframe SpaceDistribution SystemDirect Sequencing Spread SpectrumExtended Service SetIndependent Basic Service SetInstitute of Electrical and Electronics EngineersInterframe Space

ITU-T	International Telecommunication Union Telecommunication Standardization Sector	
LAN	Local Access Network	
MAC	Medium Access Control	
MS	Mobile Station	
MSDU	MAC Service Data Unit	
NAV	Network Allocation Vector	
PC	Point Coordinator	
PCF	Point Coordination Function	
РСМ	Pulse Code Modulation	
PIFS	PCF Interframe Space	
PLC	Packet Loss Concealment	
POTS	Plain Old Telephone Service	
RFC	Request For Comments	
RTP	Real-time Transport Protocol	
RTS	Request-To-Send	
SIFS	Short Interframe Space	
SS	Silence Suppression	
SSRC	Synchronization Source	
твтт	Target Beacon Transition Time	
UDP	User Datagram Protocol	
VAD	Voice Activity Detection	
VBR	Variable Bit Rate	
VolP	Voice-over-IP	
WLAN	Wireless LAN	

### **1 INTRODUCTION**

The hype for voice-over-IP (VoIP) started over five years ago, but the technology encountered some tough times and its popularity has increased at a much slower rate than first expected. Recent trends have shown a rebound in this area, with more money being spent on developing and purchasing VoIP equipment [7]. Small businesses and home users also now have the resources available to manage VoIP capabilities through a host of software applications, many of which come in open source form for Linux machines. The cost savings and expanded feature set introduced by VoIP make it an attractive solution to replace the TDM-based plain old telephone service (POTS) alternative which has been the incumbent technology over the past century of telecommunications.

While penetration into the wireless space is relatively low, some trends indicate a promising future for Wireless Local Area Networks (WLAN) [10]. The convenience of mobility in both home and office settings is the advantage WLAN has over its wired predecessor. Much reluctance to deploy WLANs comes from security issues associated with a wireless medium, however improvements in security management will likely win over concerned users and increase the rate at which WLAN networks are deployed and expanded. The Wireless LAN specification is described in more detail in Section 2.3.

#### 1.1 Problem Definition

With both VoIP and WLAN finding their ways into more businesses and homes, it is hardly inconceivable that these two technologies will eventually merge and coincide on the same networks. It is therefore important to consider the bandwidth usage VoIP traffic may exert on a wireless network. VoIP, as with many types of real-time traffic, is

capable of occupying a large amount of bandwidth depending on the compression algorithm used. Different compression algorithms, such as ITU-T defined G.711, G.723.1, G.726, and G.728, offer a range of compressibility, and hence bandwidth savings, at the cost of voice quality. VoIP payloads are encapsulated by RTP/UDP/IP protocol headers, which remain relatively fixed in size at approximately 40 bytes in total per packet. With higher compression or more frequent sample rates, the size of the header can be overwhelmingly large – in some cases more than the size of the VoIP payload itself. When the RTP/UDP/IP headers comprise of a large percent of the total packet size, it presents poor bandwidth usage. The effects of poor bandwidth usage can be even more devastating over a WLAN where channel contention and collisions are more prominent.

From the point of view of VoIP users, the main factor of perceived quality, excluding voice quality inherent in voice compression algorithms, is end-to-end delay. Many other factors affect voice quality, such as packet loss, delay jitter, and echo; however additional algorithms can be added to the VoIP service stack to handle loss, jitter, and echo, at the expense of the end-to-end timing.

### 1.2 Project Overview

This project investigates the effects in performance of two bandwidth-reduction options for Voice-over-IP: RTP/UDP/IP header compression (cRTP) and Silence Suppression (SS). cRTP and SS are described in Sections 2.1 and 2.2 respectively. The main focus of this project is on cRTP over 802.11 through the use of simulations in the Optimum Network Performance (OPNET) simulation software, as there has been less research in this area.

The following statistics are considered for cRTP and SS for VoIP over 802.11:

- a) bandwidth usage with and without cRTP/SS,
- b) channel access delays,
- c) end-to-end packet transmission delays, and
- d) packet loss

The details of the simulation system are examined in Section 3, and the simulation results are revealed in Section 4.

## **2 SPECIFICATION BACKGROUND**

Two specifications that compose a large part of this project work are RFC2508 and IEEE 802.11. This section provides some background knowledge to the reader. Silence suppression is also briefly described in Section 2.2.

## 2.1 RFC2508 cRTP

Compressed Real-Time Transport Protocol is defined in RFC2508 as an algorithm used to reduce the size of 40-byte RTP/UDP/IP headers in real-time application traffic. Devices supporting cRTP recognize that most RTP, UDP, and IP header fields either remain constant or have a constant first-order difference.

Header fields that generally remain the same are:

- IP fields: version
  - IP header length
  - type of service
  - flags
  - time-to-live
  - protocol type
  - source address
  - destination address
- UDP fields: source port
  - destination port

#### RTP fields: - version

- extension
- contributing source (CSRC) count
- payload type
- synchronization source (SSRC)

Header fields that generally increment by a fixed number are:

- IP fields: IP identification
- RTP fields: timestamp
  - sequence number

Both sender and receiver of the RTP stream must support cRTP in order for it to be applied properly to the RTP packets. Each endpoint maintains a session context for each RTP stream, or context, it is a member of. The session context at the sender (compressor) contains an image of the last RTP/UDP/IP header sent, while the session context at the receiver (decompressor) contains an image of the last RTP/UDP/IP header sent, while the session context at the received. Both compressor and decompressor context states also include the delta values for the fixed-increment fields, calculated from the previous field values and the newest field values. The compressor compresses outgoing RTP/UDP/IP headers where possible, sending one of the four packet types described below. Using the information stored at the decompressor and the fields transmitted in an incoming compressed packet, each packet can be uncompressed to its original form, then forwarded to the higher RTP application layer. Session contexts are referenced by a unique session context ID (CID) assigned to the RTP stream, based on its IP source and destination addresses, UDP source and destination ports, and RTP SSRC field.

۰.

Four packet formats are introduced in RFC2508: COMPRESSED\_RTP, COMPRESSED\_UDP, FULL\_HEADER, and CONTEXT\_STATE.

The COMPRESSED\_RTP format is used when each of the RTP, UDP, and IP headers can be compressed with only IP identification, RTP timestamp, RTP sequence number, RTP marker bit, and RTP CSRCs changing. At best, the header of the COMPRESSED\_RTP packet can be reduced to 2-bytes, depending on the behaviour of the RTP application.

A COMPRESSED\_UDP packet is sent when an RTP field other than those mentioned for the COMPRESSED\_RTP format changes. This compresses the UDP/IP headers down to between 2 - 6 bytes.

The FULL\_HEADER format communicates an uncompressed IP header and is used when header compression cannot be done or to refresh the session contexts' header images - particularly after a lost packet.

When a packet is dropped during transmission, the decompressor transmits a CONTEXT\_STATE packet to the sender to indicate that a packet has been lost. This indicates to the sender that a FULL\_HEADER must be sent in order to restore order to the header-compressed RTP stream. Between the time the receiver sends the CONTEXT\_STATE packet and receives a new FULL\_HEADER packet, the session context is invalidated and all packets for that context are discarded.

Figure 1 and Figure 2 illustrate the cRTP header compressor and decompressor functionality.







Figure 2: Block Diagram for cRTP Header Decompressor

Detailed information on cRTP packet formats and procedures can be found in [12].

### 2.2 Silence Suppression

Studies on typical speech patterns show that during a normal conversation, each speaker is active only 40 percent of the time [8][2]. The remaining 60 percent of the time is spent listening to the person at the other end of the conversation and during pauses. Silence suppression algorithms take this phenomenon into account, and does not send voice packets during silent periods. Silence is determined through voice activity detection (VAD), where power levels under a certain threshold are considered silence.

Two voice models, Brady's model [8] and May and Zebo model [2], are commonly used in modelling speech burstiness. These models have exponentially distributed ON and OFF state times with mean values shown in the table below.

Model	Mean ON Period (seconds)	Mean OFF Period (seconds)
Brady's Model	1.00	1.35
May and Zebo Model	0.352	0.650

Table 1: Voice Models

For the purposes of this project's simulations, only Brady's Model is considered.

#### 2.3 IEEE 802.11

IEEE 802.11 standard, ratified in 1997, defines a wireless local area network architecture that can be viewed as a wired Ethernet network (IEEE 802.2) to layers

above it / application layers. The original specification supports 1Mbps and 2Mbps transfer rates.

### 2.3.1 General Architecture

In an IEEE 802.11 network architecture, a group of mobile stations (MSes) or devices controlled under a distribution system (DS) is called a Basic Service Set (BSS). A BSS, which occupies a Basic Service Area (BSA), can be either an Independent Basic Service Set (IBSS) ad hoc network, in which any station can establish a direct communication path with any other station (Figure 2-3), or an infrastructure network, where communications between stations is done through a centralized Access Point (AP).



Figure 2-3: IBSS / Ad Hoc Network

In an infrastructure network, BSSes can have an extended range via intercommunication of APs from different BSSes. This extended infrastructure is called an Extended Service Set (ESS), and can also provide access to wired networks via portals. Figure 2-4 illustrates an exemplary infrastructure network. The DS is analogous to a backbone network responsible for the MAC level transport of MAC service data units (MSDUs).



Figure 2-4: ESS Infrastructure Network

### 2.3.2 Physical Layer

Three physical layer implementations are specified for IEEE 802.11: Frequency Hopping Spread Spectrum (FHSS), Direct Sequence Spread Spectrum (DSSS), and Infrared (IR). The physical layer is responsible for transmitting packets over the wireless medium, and if functioning properly, should not be of any concern to the overall system. For this project, DSSS is considered and used for simulation.

#### 2.3.3 MAC Sublayer

The MAC sublayer is responsible for channel allocation, protocol data unit addressing, frame formatting, error checking, and fragmentation and reassembly. The transmission medium has two types of operation: contention and non-contention. During contention periods (CP), all stations contend for the channel for each packet transmitted. This mode is used for 802.11 Distributed Coordination Function (DCF), as described in Section 2.3.4. During contention free periods (CFPs), the medium usage is controlled (or mediated) by the AP, thereby eliminating the need for stations to contend for channel access. To include CFPs, the medium must alternate between CP and CFP modes, with enough time during the CP to transmit at least one MSDU under DCF. Each CFP followed by a CP is called a superframe. 802.11 Point Coordination Function (PCF, described in Section 2.3.5) is used during the CFP.

IEEE 802.11 supports three different types of frames: management, control, and data. The management frames are used for station association and disassociation with the AP, timing and synchronization, and authentication and deauthentication. One management frame is called a beacon frame, and is sent at the beginning of each superframe to maintain the synchronization of local timers in the stations and deliver protocol related parameters. The beacon frame also announces the time the next beacon frame will arrive, called the target beacon transition time (TBTT). Control frames are used for handshaking during the CP, for positive acknowledgments during the CP, and to end the CFP. Data frames are used to transmit data during CPs and CFPs, and can be combined with polling and acknowledgments during CFPs.

#### 2.3.4 Distributed Coordination Function

Distributed Coordination Function is the fundamental 802.11 MAC protocol and uses Carrier Sense Multiple Access with Collision Avoidance (CSMA/CA) on top of the physical layer; in other words, it works off a contention-based "listen-before-talk" scheme for transmission of MSDUs over the wireless medium to reduce the statistical probability of collisions. Before transmitting a frame, each station must perform a backoff procedure, sensing the channel for a minimum duration called the DCF Interframe Space (DIFS) followed by a random backoff time. The additional random backoff time is a multiple of a slot time. The channel must stay idle during the entire wait before the frame transmission can be initiated. Each station maintains a contention window (CW) that determines the remaining number of slot times a station must wait before transmission. When a station transmits an MSDU, a duration field is set in the MAC header indicating the time the channel will be busy with the current transaction. Based on these fields, stations detecting MSDUs sent update their Network Allocation Vectors (NAVs). The NAV indicates the amount of time remaining for the current transmission session to complete, before the channel will be idle once again.

In the case of multiple DCF stations, the station with the shortest wait time transmits first. The remaining stations do not select a new random backoff, but continue to count down the remaining slots as soon as the channel is idle. This gives the waiting stations higher priority when they resume transmission attempt. Collisions occur when two or more stations simultaneously count down to zero. In this case, each transmitting station must re-transmit with a new backoff time.

After each successful transmission, the receiving station acknowledges the frame reception with an acknowledge frame (ACK) after a Short Interframe Space (SIFS), an Interframe Space (IFS) shorter than the DIFS. The sender then does another random backoff, called a "post-backoff", even if there are no more MSDUs to be delivered. If the transmission fails, i.e. no ACK is received from the destination station, the transmission is retried with a doubled CW, reducing the probability of collisions with other stations.

The maximum MSDU size is 2304 bytes. Frames longer than 2304 bytes can be fragmented into smaller frames and sent individually, following the same collision avoidance scheme described. As an alternative option to avoid wasted bandwidth due to collisions with longer frames, a Request-to-Send (RTS) frame, followed by a Clear-to-Send (CTS) response, can be sent to reserve a channel prior to sending a long frame. RTS and CTS frames also contain duration fields for other stations to update their NAVs.

Figure 2-5 shows the timing for a possible DCF scenario.





#### 2.3.5 Point Coordination Function

IEEE 802.11 defines Point Coordination Function as a central controlled access method coordinated by a Point Coordinator (PC) within the Access Point (AP) in each BSS. PCF is optionally supported for 802.11 stations, and is most appropriate for time-bounded services such as voice or video applications. The PC polls stations during the CFP to transmit without contending for the channel. The PCF has higher priority than the DCF, because it may start transmission after a PCF Interframe Space (PIFS), which is shorter than the DIFS, but longer than the SIFS.

The duration of the CFP interval is an integral multiple of the beacon frame period. This interval length is determined by the AP to best manage the traffic. During the CFP, all stations in the BSS update their NAVs to the length of CFP, and may only transmit when polled by the PC or when sending an ACK frame following reception of data frame.

In a PCF sequence during CFP, the PC polls a station for pending data. If the polled station has a frame to send, then it may do so; if the polled station has no data to send, the PC will wait with no response for PIFS and will poll the next station or end the CFP. In this contention-free scheme, the channel does not stay idle for longer than PIFS. The PC continues polling until the CFP ends, at which time a CF-End control frame is sent to signify the last frame of the CFP.

Figure 2-6 illustrates a PCF sequence during the contention free period.



Figure 2-6: Example of PCF Operation

PCF is not very scalable, in that a single point has control of media access and must poll all stations, which can be ineffective in large network. However, it offers benefits of dedicated bandwidth during the CFP.

## **3 SIMULATION MODEL**

Simulations of cRTP over IEEE 802.11 were conducted using Optimum Network Performance (OPNET). Much of the work required to complete this project involved developing the cRTP process model to a point where it could provide a fairly accurate representation of a software module performing the RFC2508 algorithm. This section provides an overview of the simulation system and components.

#### 3.1 System Model Overview

The OPNET project includes N mobile stations, where N can range from 2 to 22 (Figure 3-1 shown an example where N = 20), each with a node model consisting of the elements shown in Figure 3-2. These nodal components are described in the following section.



Figure 3-1: Simulation Project Model



Figure 3-2: Mobile Station Node Model

### 3.2 Model Components

As seen in Figure 3-2, each node contains a packet generator, an RTP/UDP/IP encapsulation module, a cRTP compressor/decompressor, a packet sink, and WLAN MAC components.

#### 3.2.1 Data Traffic

RTP/UDP/IP traffic is generated through two components: a packet source and an RTP/UDP/IP encapsulator. The packet source used is the "bursty\_source" process model, as provided in the OPNET application. The RTP/UDP/IP encapsulation is done by a simple process model created for its purpose.

RTP payload sizes can be chosen as desired, and are kept constant in this project. The payload content is not voice traffic, but is irrelevant to the simulations – it is only the packet size that of importance. Packet transmission distribution properties are selected between constant bit rate (CBR) and silence suppressed. During a CBR stream, fixed

packet-sized packets are generated and sent at a fixed sampling interval. For SS streams, fixed-sized packets are sent at fixed sampling intervals when the source is in an ON state; otherwise, no packets are sent during the OFF state. The ON and OFF states' distributions are characterized by Brady's Model in Table 1.

The RTP/UDP/IP encapsulator receives the generated payload from the packet source and adds the appropriate RTP, UDP, and IP headers with realistic values. This process model also keeps track of incrementing header fields. The header fields are fairly wellbehaved, as it is expected that a typical real-time application would run in a reasonable fashion. Degradation to the voice channel will be introduced externally by means of intentionally dropped packets and WLAN congestion.

#### 3.2.2 cRTP Process Model

After packets have been encapsulated with RTP, UDP, and IP headers, the cRTP process model compressor performs compression possible before forwarding the packet to the WLAN interface. This process model compressed based on the methods described in RFC2508.

When receiving packets from the WLAN interface, the decompressor decompresses compressed packets based on RFC2508 and sends the restored packet to the packet sink.

#### 3.2.3 WLAN Process Model

Two WLAN process models are included in the MS node model: wlan\_mac\_interface and wlan\_mac. These models are included in the OPNET package. Together, they

accept packets from higher level applications (an RTP application in this case), and transmit them over a wireless medium as specified in the IEEE 802.11 standard. Numerous options can be chosen through this model, including AP functionality, distribution system, beacon interval, CFP interval, data rate, and physical layer.

### 3.3 Simulation Scenarios

Various situations are tested to demonstrate the effectiveness of cRTP and SS over IEEE 802.11. The following table presents the simulation objectives to show the advantages of cRTP and SS over IEEE 802.11 DCF and PCF. Section 3.3.1 tabulates the parameters selected for the simulations.

	Objectives	Results to Acquire
1	Bandwidth savings from cRTP	cRTP/RTP Packets Sent vs. Time
2	Effect of packet loss on cRTP bandwidth savings	cRTP/RTP Ratio vs. Packet Loss Rate
3	Effect of packet sizes on cRTP bandwidth savings	cRTP Packets Sent (for 5ms, 10ms, and 20ms samples, with and without SS) vs.
4	Effect of SS on bandwidth savings	Time
5	Effect of cRTP and/or SS over WLAN for different number of mobile stations	10ms packets, over PCF or DCF, with and without cRTP, with and without SS: A) Average Load vs. Number of Stations
6	Comparison of DCF and PCF on VoIP traffic	<ul><li>B) End-to-End Delay vs. Number of Stations</li><li>C) Packet Loss vs. Number of Stations</li></ul>

#### Table 2: Simulation Goals

## 3.3.1 Selected Parameters

Process Model	Situation	Parameter	Value
Packet Source	5ms PCM	RTP Payload Size	58 bytes
	sampling	Interpacket Time	0.005 seconds
	10ms PCM	RTP Payload Size	98 bytes
	sampling	Interpacket Time	0.01 seconds
	20ms PCM	RTP Payload Size	178 bytes
	sampling	Interpacket Time	0.02 seconds
	No SS	ON State Time	3600 seconds
		OFF State Time	0 seconds
	SS	ON State Time	1.00 second
		OFF State Time	1.35 seconds
WLAN	General	AP Functionality	MS01 Only
		Data Rate	2 Mbps
		Physical Layer	DSSS
	PCF Enabled	Beacon Interval	0.1 seconds
		CFP Interval	0.099 seconds

For the scenarios listed in Table 2, the following simulation values were applied:

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#### Table 3: Simulation Parameters

As mentioned in Section 2.3.2, a direct sequencing physical layer is applied during the simulation. For DSSS, the interframe space values are SIFS =  $10\mu$ s, DIFS =  $50\mu$ s, and PIFS =  $30\mu$ s.

### 3.3.2 Assumptions

The following stream and network assumptions were made during the simulation process.

#### Stream Level Assumptions:

- 1. Each MS manages only two unidirectional voice streams.
- 2. Each MS sends to one, and only one, other MS (via the AP), i.e. no multicasting.
- 3. UDP checksum is handled at the higher layer. More information about this is provided in RFC2508 [12].
- 4. IP and UDP lengths are handled at link layer level. More information about this is provided in RFC2508 [12].
- 5. Calls do not end, i.e. calls start at time t<sub>s</sub> and continue to transmit packets until the end of the simulation.
- 6. Propagation delay is near negligible due to proximity of MSes.
- 7. RTS/CTS mechanism is not used due to relatively small sizes of voice packets.

#### Network Level Assumptions:

- 8. Each pair of MSes start transferring packets at simulation times  $t_s = 1s$  for MS01 and MS02,  $t_s = 1.1s$  for MS03 and MS04,  $t_s = 1.2s$  for MS05 and MS06, and so on.
- 9. All MSes are in the same BSS, and each MS can access the AP (MS01).
- 10. 802.11 WLAN models work properly and follow the specification as in [4].
- 11. Distribution system for all MSes in the BSS is either DCF-only or PCF-only, not a mix.

## **4 SIMULATION RESULTS**

In running the simulations described in Section 3.3, the test results fortify the intuitive expectations of employing an additional compression scheme. In this section, simulation results are revealed and explained.

At a basic level, excluding MAC layer complexities (i.e. without 802.11), bandwidth savings using cRTP over a non-header compressed stream is

Bandwidth savings = 
$$\frac{38}{payload size + 40}$$
 (4.1)

Typical PCM VoIP packets have payload sizes 58 bytes for 5ms sampling, where up to 38 percent bandwidth can be saved using cRTP. Figure 4-1 shows the total number of packets transmitted, for both RTP and cRTP cases, for a well-behaved 5ms sampled. For increased sampling sizes, 98-byte 10ms samples for example, the difference between the cRTP and RTP lines will be smaller. In other words, a smaller payload size will benefit more from header compression as the header composes a larger percentage of each packet.



Figure 4-1: Cumulative Traffic Sent (bytes) versus Time (minutes)

Bandwidth savings is further reduced by dropped packets. Each time an RTP packet is lost, due to collisions or other reasons, the cRTP mechanism must refresh its session context table. Figure 4-2 illustrates the sequence of packets for a well-behaved (where full compression can be done) RTP stream in which a packet loss occurs. When packet loss is discovered by the decompressor, the newest received packet is discarded, as it cannot be reconstructed without the information from the lost packet, and a CONTEXT\_STATE packet of 5 bytes size is sent to the compressor. Upon receiving the CONTEXT\_STATE packet, the compressor sends a FULL\_HEADER packet on its next transmission. For a 5ms sampled stream, this would imply that each lost packet results in sending at least 43 additional bytes (5 bytes for the CONTEXT\_STATE, 38 bytes for additional header fields). Depending on the behaviour of the RTP stream, additional bytes may be necessary in the packet following the FULL\_HEADER to update the first

order differences stored in the compressor and decompressor session contexts, which are reset when the FULL\_HEADER is transmitted.



Figure 4-2: Packet Transmission Sequence During Packet Loss

Figure 4-3 shows the activity between a compressor and decompressor when packets are dropped at 3 percent packet loss. The top plot shows when dropped packets are detected at the decompressor, after which a CONTEXT\_STATE is sent. The bottom plot shows the additional bytes sent following a dropped packet.



Figure 4-3: Simulated Packet Drops

One could deduce that as the packet loss rate increases, the bandwidth savings will be reduced. Figure 4-4 shows that this deduction is true, plotting the ratio of total cRTP traffic to the total original traffic for rising packet loss. A smaller ratio suggests a larger savings in bandwidth.



Figure 4-4: cRTP Size / Original Size versus Packet Loss Rate

The objective behind implementing silence suppression is to reduce the bandwidth required by each end of a conversation, potentially by 60 percent. Based on the voice pattern distributions according to Brady's Model, SS provides a much-reduced usage of bandwidth, as shown in Figure 4-5 (DCF) and Figure 4-7 (PCF). These figures show the reduction of traffic rates with larger sampling intervals. Figure 4-6 and Figure 4-8 plot similar graphs, however providing a cumulative result over the 30 minute DCF and PCF simulation periods respectively. These four graphs are for two-mobile station networks.



Figure 4-5: Simulated cRTP Voice Traffic over DCF vs. Time



Figure 4-6: Cumulative Simulated cRTP Voice Traffic over DCF vs. Time



Figure 4-7: Simulated cRTP Voice Traffic over PCF vs. Time



Figure 4-8: Cumulative Simulated cRTP Voice Traffic over PCF vs. Time

The following four graphs show the channel reservation times and the media access delay times for two-mobile station DCF and PCF networks. Due to polling, the channel reservation time in a PCF scenario is short, seen in particular between the simulation times of 5 minute and 20 minute; however there are longer media access delays, as packets must wait for the next set of polling. Media access delay has a directly effect on end-to-end transmission delay.



Figure 4-9: Access Point Channel Reservation in DCF DS



Figure 4-10: Media Access Delay in DCF DS



Figure 4-11: Access Point Channel Reservation in PCF DS



Figure 4-12: Media Access Delay in PCF DS

The following series of plots compare DCF versus PCF, RTP versus cRTP, and CBR versus SS with respect to packet loss (Figure 4-13), media access delay (Figure 4-14), end-to-end delay (Figure 4-15), and network load (Figure 4-16). These simulations were done with 10ms PCM sampling – 98 bytes payload every 10ms.

In Figure 4-13, the plot is somewhat deceiving because the DCF simulations resulted in a massive packet loss is observed at some time, after which no packets are collected properly, invalidating the data. For the non-header compressed RTP stream, this happens when the number of MSes exceeds 4 when SS is disabled, and 6 when SS is enabled. In the cRTP stream, the explosion occurs at 8 MSes and 10 MSes for SS disabled and enabled respectively.



Figure 4-13: Packet Loss versus Number of Mobile Stations

Most VoIP applications are able to compensate for a certain amount of packet loss with a packet loss concealment (PLC) algorithm. PLC usually comes at the cost of end-toend delay, but has the ability to improve voice quality at reasonable levels of packet loss, say, less than 10 percent. Looking only at the PCF data in the Figure 4-13, at 10 percent packet loss, there is a slight increase in the number of allowable stations from employing cRTP; however, there is a significantly large improvement when silence suppression is enabled. This major improvement is attributed to the diminished number of packet transmissions attempted at any one time for a fixed number of stations, allowing more MSes to be added.

Figure 4-14 plots the media access delay for varying number of stations. The large packet drop described above is even more evident here, as the media access delay skyrockets to between 200 and 300 seconds. Figure 5-1 in the Appendix shows a complete plot of the media access delay, including the extended DCF lines. RTP header compression provides little assistance in the media access delay because it does not reduce the number of packets trying to access the channel. Silence suppression, on the other hand, does help reduce the average media access delay. At the 250ms end-to-end delay boundary, after which the delay becomes a disturbance to the VoIP end users, again, there is a rise in number of MSes when SS is enabled. This result directly influences the average end-to-end delay (Figure 4-15). The DCF lines for end-to-end delay are shown in full in Figure 5-2 of the Appendix.



Figure 4-14: Average Media Access Delay versus Number of Mobile Stations



Figure 4-15: Average End-to-End Delay versus Number of Mobile Stations

The last results, shown in Figure 4-16, expose the benefits of cRTP and SS towards bandwidth. In this figure, the DS used in the system (DCF or PCF) has little effect on the allowable load. For all cases, as the number of mobile stations increases, a load limit is reached, and traffic is then compensated in delay and packet loss. Header compression and SS provide more efficient bandwidth usage, thereby enabling more stations to be included in the DSS before high packet loss and long delays are observed.

The worst case of network load is apparent when neither cRTP nor SS are employed. For smaller number of MSes, cRTP provides more bandwidth relief over SS; however SS becomes a more attractive alternative as the number of MSes increases past 12. The best option is to integrate both cRTP and SS to achieve a slower rate of increasing WLAN network load.



Figure 4-16: Average Channel Load versus Number of Mobile Stations

### 5 CONCLUSION

With an increased deployment of both wireless LAN and voice-over-IP solutions, it is essential to find ways to optimize the use of network bandwidth. This is particularly true with VoIP systems, which can potentially absorb resources and congest networks very quickly. Compressed RTP and silence suppression are two independent implementations that can dramatically enhance network efficiency for real-time applications. The advantages of silence suppression have already been recognized, which is why is it already defined in several ITU-T vocoder algorithms. cRTP, on the other hand, has been slow to find its way into many real-world applications. It is possible that its slow deployment is due to a fairly open RFC specification, which makes interoperability between cRTP-supporting applications difficult. Nevertheless, the benefits to its employment are clear. When coupled, the collective bandwidth savings of these algorithms can realize major improvements in end-to-end delays and packet loss, two important considerations for quality of VoIP connections. Finally, the simulation results also show that 802.11 point coordination function is more suitable for voice-over-IP traffic streams, as expected.

#### 5.1 Future Considerations

While the objective of this project is to demonstrate the performance of cRTP and SS over an IEEE 802.11 wireless LAN, there is a fair amount of additional research that can be done in this respect. This project lays down the basic groundwork for future investigation in the related area. To draw complete conclusions from simulations, other system models should be explored. These additional models may include the following:

- BSS/ESS with both DCF and PCF: Real world systems are seldom PCF-exclusive since it is rare that all traffic transmitted on a network is real-time. Future testing should involve the more probable scenario that includes a mix of the distribution systems. Furthermore, VoIP calls are more likely connected over a distance, in which case an ESS would be used instead of a single BSS.
- Faster transmission rates: IEEE 802.11b specifies an increase in transmission rates to 5.5 Mbps and 11 Mbps, because the 1 Mbps and 2 Mbps rates defined in the original 802.11 were too slow for most home and office use.
- Additional vocoder tests: A wide variety of vocoders, both CBR and variable bit rate (VBR), are commonly used. These vocoders can compress the PCM payload to much smaller sizes, which will result in more bandwidth savings.
- Call simulations: Conversations simulated within this project start at the beginning of the simulation, but do not end. In a real system, mobile stations used for VoIP (which may include wireless SIP phones in the future) cycle through call connections and disconnections, as well as voice traffic patterns during connected calls.

## **APPENDIX**

Figure 5-1 shows the fully-collected average media access delay statistics. A zoomed-in version is seen as Figure 4-14 on page 34.



Figure 5-1: Average Media Access Delay versus Number of Mobile Stations (Full)

Figure 5-2 shows the fully-collected average end-to-end delay statistics. A zoomed-in version is seen as Figure 4-15 on page 34.



Figure 5-2: Average End-to-End Delay versus Number of Mobile Stations (Full)

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