# **SoC Prototyping and Validating during DSM CMOS Technology Transfer**

by

Brian SeJin Park B.A.Sc. University of British Columbia, 2001

# PROJECT REPORT SUBMITTED IN FULFILMENT OF THE REQUIREMENTS FOR THE DEGREE OF

### MASTER OF ENGINEERING

In the

**School** 

of

Engineering Science

0 Brian SeJin Park, 2004 SIMON FRASER UNIVERSITY Fall 2004

All rights reserved. This work may not be reproduced in whole or in part, by photocopy or other means, without permission of the author.

# **Approval**



## Examining Committee:

Dr. Bonny Gary, Examining Committee Chair Assistant Professor, School of Engineering Science

Dr. Glenn Chapman, Senior Academic Supervisor Professor, School of Engineering Science

**Jim Younger, Industrial Technical Supervisor** Manager of Product Engineering, PMC-Sierra

Dr. Albert Leung, Supervisor Professor, School of Engineering Science

Date Approved:  $\frac{D_{e} / 4}{\sqrt{4}}$ 



# **DECLARATION OF PARTIAL COPYRIGHT LICENCE**

The author, whose copyright is declared on the title page of this work, has granted to Simon Fraser University the right to lend this thesis, project or extended essay to users of the Simon Fraser University Library, and to make partial or single copies only for such users or in response to a request from the library of any other university, or other educational institution, on its own behalf or for one of its users.

The author has further granted permission to Simon Fraser University to keep or make a digital copy for use in its circulating collection, and, without changing the content, to translate the thesislproject or extended essays, if technically possible, to any medium or format for the purpose of preservation of the digital work.

The author has further agreed that permission for multiple copying of this work for scholarly purposes may be granted by either the author or the Dean of Graduate Studies.

It is understood that copying or publication of this work for financial gain shall not be allowed without the author's written permission.

Permission for public performance, or limited permission for private scholarly use, of any multimedia materials forming part of this work, may have been granted by the author. This information may be found on the separately catalogued multimedia material and in the signed Partial Copyright Licence.

The original Partial Copyright Licence attesting to these terms, and signed by this author, may be found in the original bound copy of this work, retained in the Simon Fraser University Archive.

> Simon Fraser University Library Burnaby, BC, Canada

## **Abstract**

This report lays out the importance in different technology used from one wafer process foundation to another. Depending on the process technologies they use, processed devices can have varying performance and characteristics. The HSPICE BSIM3 model is used to analyze IV characteristics of N/PMOS transistors based on both FAB1 and FAB2 technology files. Sub-threshold current has also been simulated. Simple five stage inverters as well as ring oscillator with 100nm length and 200nm width transistors are created to simulate and analyze the performance variations. The analysis consists of delay associated with parasitic capacitance parameters from both foundries. Lastly, a simple model, consisting of series of inverters and resistors, is created to simulate effect of power distribution.

# **Acknowledgements**

The author would like to thank Dr. Glenn Chapman of Simon Fraser University for offering to help finalize this project within such short notice. Also, Dr. Glenn Chapman had kindly provided detailed information required for the project requirements, which enabled such successful completion of this project.

The author, also, would like to thank Bruce Scatchard of PMC-Sierra and Jim Younger of PMC-Sierra for support and review of this project as well as concept development for this project.

This work was supported in part by PMC-Sierra.

# **Table of Content**



# **List of Figures**



# **Definitions**



# **Chapter 1. Introduction**

### **1.1 General**

This thesis is concentrated on feasibility comparison of the technology between two silicon fabrication foundries, also called FABs. Fabricating technologies of both FABs are implementing processes of 0.18um single poly two-metal layer with 95%AI/-5%Cu and salicided poly-silicon. Even with same technology levels, each FAB can produce rather different products with the same layout designs. For proprietary protection reasons, these FABs will be identified in this thesis as FA91 and FAB2. The FAB1 is PMC's original fabrication foundry while FAB2 is fabrication foundry to which the design technology is being transferred to for reduced process costs. Since both foundries have their own budgets for purchasing equipments and developed their own processing steps, they have slightly different 0.18um process capacities and technologies.

Both foundries are fully capable of fabricating 0.18pm devices, but what are the tradeoffs in IC quality and cost? This question can be answered rather quickly when you start looking at the simulation results of different process technologies being used for wafer fabrication. The different process technologies give each foundry its own capacity and characteristics. However, would each foundry be able to support and process a layout for PMC's designed requirements for a mature 0.18pm technology? This thesis will contain analysis of two fabrication foundries based on the simulation result with their process technology files.

This chapter contains an introduction to what is involved in design technology transfer between foundries. Subsequent chapters elaborate on these topics in further detail. The last section of this chapter contains an outline summary of each chapter.

#### **1.2 Background**

Today, a fabless model for semiconductor chipmakers is one of the most successful business methodologies being used in semiconductor companies. The advantage of these fabless companies is that they can concentrate their resources in device design and characterization, while fabrication companies like FAB1 and FAB2 can concentrate on process technology developments.

In order to ensure the fabrication processes are properly qualified to certain standards, characterization of the processed devices is required. This step is necessary to guarantee the function and performance of fabricated devices for different foundries at given technology nodes.

PMC-Sierra (PMC) is one of the companies that utilize the fabless model. After the recent economic downturn, high tech companies have gone through hardship due to the market depression. Therefore, it became imperative for PMC to reduce costs in order to remain competitive in the market. By switching to another fabrication foundry, PMC enjoys a large cost saving in wafer fabrication for a mature process technology like 0.18ym process. However, one must keep in mind such factors as time of delivery, setup cost, and yield from the wafer. If any one factor is compromised, then it is possible that such foundry transfer might not give enough cost savings.

To ensure the characteristics of the devices processed from both foundries were the same, the simulation based on HSPICE (version U-2003.09 from Synopsys Inc. under SUN Solaris 5.8 system) has been conducted. The HSPICE software is using BSlM3 model library files. Also, parasitic technology parameters for both foundries in 0.18ym technology are used. From the seven-metal, single poly process technology, this thesis restricts itself to only a single poly with two-metal layer analysis to conduct the basic simulation and simplify the analysis of the data plus comparisons of the FABs. 0.18ym technology has been developed for many years and is at mature stage of the development cycle. This is the reason 0.18<sub>pm</sub> technology is chosen for the transfer.

All the resources and manufacturer's technology files are provided by PMC-Sierra. The details of technology files from FABI and FAB2 cannot be revealed due to proprietary nature of the information. PMC-Sierra has signed Non-Disclosure Agreements concerning the details of these files. Hence, the following process details are based on those technology files and full details cannot be revealed.

That being said, for proprietary reasons this report is based solely on results from the simulations. The simulation is based on parasitic parametric values provided from FABI and FAB2 technology libraries. The analysis is done based on the simulation which was conducted with basic transistor, inverter, five stage inverters, and five stage ring oscillators with 100nm length and 200nm width for both NMOS and PMOS. Also, other possible effects like cross talk and power grid resistance, which can cause unfavorable performance issues, is reviewed and analyzed. These are the basic and most common test structure that allows unbiased performance comparisons from both FABs.

The impact on either analog or digital circuits will be reviewed and analyzed. Some of the results only affect analog circuits while some others only affect digital circuits. Also, the report will start with smaller and simpler (transistor level) circuits then move on to higher-level general-purpose circuits like power grid resistance effects and cross-talk effects.

3

### **1.3 Thesis Outline**

In chapter 2 the transistor model simulations are first conducted to compare the I-V characteristics of the transistors. Then the threshold voltage effects of the devices from each FAB are compared.

Chapter 3 presents the device level simulation based on simple inverter, fivestage inverter chain, and five-stage ring oscillator. The analysis is mostly based on the voltage characteristics as well as propagation delay of the input signal. Results from each FAB are analyzed and compared.

Chapter 4 examines a couple of possible issues at the top level. This section includes possible cross talk issues within the device that may affect other signal lines. Also, the power supply grid resistance effect is reviewed to analyze possible power degradation throughout the device.

Chapter 5 presents this project with the conclusion of the analysis.

# **Chapter 2. Analysis of Transistor Level HSPICE Simulation Results**

This chapter provides transistor level simulation results like I-V and transconductance characteristics of 0.18ym NIPMOS transistors. The HSPICE simulation is based on 0.18ym process technology library files obtained from both FABl and FAB2. The simulation uses BSIM3 model library files. For convenience, the length of the transistors is set to 180nm for both N and P channel transistors and the width of the transistors is set to 720nm for both N and P channel for I-V Characteristics. This size is used to compare equal size N and P channel transistors. The sub-threshold current simulation is conducted with the length of 180nm for both N and P channel, and the width of 1800nm for P channel and 720nm for N channel transistors. P channel transistor width is greater then N channel transistor to incorporate slower P channel transistor due to slower electron drift velocity. Larger then minimum transistor width is used to increase amount of current drive strength.

#### **2.1 I-V Characteristics**

I-V characteristics of FABl and FAB2 for the NMOS transistor model with varying gate to source voltage,  $V_{GS}$ , are shown in Figure 1. The characteristics for the PMOS transistor model with varying gate to source voltage,  $V_{GS}$ , are shown in Figure 2.  $V_{GS}$  values used for each curve are  $V_{GS} = 0V$ , 0.6V, 1.2V, and 1.8V respectively along the voltage-axis (or x-axis). These characteristics show threshold voltage,  $V_{TH}$ , values to be roughly 0mV, 100mV, 350mV, and 650mV respectively.

Curves where  $V_{GS} = 0V$ , 0.6V, and 1.2V show almost the same  $V_{TH}$  characteristic values for both FABs while  $V_{GS} = 1.8V$  shows differences in their measurements. FAB1's NMOS transistor shows V<sub>TH</sub> of ~600mV while FAB2's shows V<sub>TH</sub> of  $\sim$ 700mV. PMOS transistor, however, shows V<sub>TH</sub> of  $\sim$ 810mV from FAB1 and

 $\sim$ 720mV from FAB2, with FAB2 devices having higher  $I_{DS}$  values. Also, these graphs show that FAB1 NMOS transistors reach the saturation region faster than FAB2 NMOS transistors and the other way around for PMOS transistors. This could be the result of channel length modulation<sup>5</sup>. This effect can be derived from the length of the transistor's channel since it is inversely proportional to the length of the transistor. At the same time, the thickness of the poly-silicon would cause a similar effect due to decreased electrical field applied to the channel'.

The graphs in Figures 1 and 2 also show the difference in slope for the triode region from both FABs between  $V_{DS}$  of OV to ~800mV. At full operating voltage of 1.8V the FAB1 NMOS transistor's triode region slope is greater than that of the FAB2 NMOS transistor. The PMOS transistor, however, shows that the slope of FAB2 is greater then FABI for the triode regions. This result indicates potential degraded performance for both analog and digital circuitry.







**Figure 1 (Continue)** 



Figure 2 I-V (I<sub>DS</sub> vs V<sub>DS</sub>) Characteristics for minimum geometric 0.18µm PMOS **transistors (Linear scale)** 



**Figure 2 (Continue)** 

Since the slopes of triode region for the FAB2 devices are smaller for NMOS, the analog circuits will operate slower than the FABI devices for N-channel signals. The opposite would happen for PMOS transistors since the slope of FAB2 triode region is greater then FAB1. Also, now we have slightly mismatched N and P channel signals for FAB1 devices and this can cause an increased rise/fall time of the signals. This skew can potentially lower the performance of the high-speed differential signals by generated skew and degraded data-eye. FAB2 devices, however, have closely matched N and P channel transistors. This will help FAB2 devices' analog signal to have better rise and fall time as well as cleaner dataeye.

N and P transistor skew from FABl can also cause problems for digital circuitry. The bigger N and P skew also means longer "undefined" regions in the digital signal domain<sup>3</sup>. Think about a simple standard inverter for example: The output voltage will stay "unknown" for an input voltage of 600mV to 810mV for FAB1 devices and 700mV to 720mV for FAB2 devices because between these two values  $V<sub>THN</sub>$  will reach the threshold while  $V<sub>THP</sub>$  will not. There is an undefined region gap of 210mV for FAB1 devices and 20mV for FAB2 devices. Therefore, both N and P channel transistors would stay "on" or "off" at the same time causing the output to be "unknown." As the "unknown" region becomes longer, the circuit downstream will need longer setup and hold time to recognize the data. As a result, the digital circuits will have to operate at lower frequency in order to operate without any errors. Comparing the digital circuits from the two FABs, FAB2 digital circuits will be capable of running at higher frequency due to lesser N and P process skew.

Another implication of this "unknown" stage is that there will be a short from  $V_{DD}$ to the ground causing sudden high current draw. Based on this, FAB1 devices will have higher current consumption compared to FAB2 devices for signals with higher transition density. This will be checked in Chapter 3.



Figure 3 I-V (I<sub>DS</sub> vs V<sub>DS</sub>) Characteristics for minimum geometric 0.18µm NMOS **transistors (Logarithmic scale)** 



Figure 3 and Figure 4 are the same type of graph as in Figure 1 and Figure 2 but with the  $I_{DS}$  axis (y-axis) in a logarithmic scale. These two graphs highlight how saturation regional and triode regional slopes are similar for both FABl and FAB2 devices. The current measurements at saturated voltage are  $~1pA$  for lower voltage setting, which is effectively a zero. The higher voltage setting, however, measured to be  $\sim$ 10uA to  $\sim$ 100uA. The current measurements of the devices from both FABs draw about the same amount of current in their transistor operations. Therefore, the power consumption on both FAB's devices would be the same.



#### Figure 4 I-V (I<sub>DS</sub> vs V<sub>DS</sub>) Characteristics for minimum geometric 0.18µm PMOS **transistors (Logarithmic scale)**



**Figure 4 (Continue)** 

## **2.2 Transconductance Characteristics**

Another important characteristic of a MOS transistor can be obtained by graphing  $I_{DS}$  vs  $V_{GS}$ , known as the transconductance characteristic<sup>4</sup>. Transconductance for FABl and FAB2 transistors' are shown in Figure 5.



Figure 5 Vt, Sub-threshold current (V<sub>GS</sub> vs I<sub>DS</sub>)



**Figure 5 (Continue)** 

The curve with positive current is the result from PMOS transistors and the curve with negative current is the result from NMOS transistors. As shown in Figure 5, the transconductance characteristics for FABl and FA62 PMOS transistors are similar. However, there seems to be a constant DC offset from FABl to FAB2 NMOS transistors.

The DC current shift is  $\sim 30\mu$ A. This means that NMOS transistors need  $\sim 30\mu$ A more to reach the threshold voltage. Also,  $V_{GS}$  ranges from 0V to 0.6V, where the transistor is in "off" state, FAB2 devices have leakage current of about 60pA while FAB1 devices have leakage current of about 30µA.

The 30yA DC offset current can potentially cause higher power consumption for FAB2 devices due to higher current usage. This can also cause higher draininduced barrier lowering (DIBL)<sup>5</sup> for FAB2 devices compared to FAB1 devices. At the same time, this means that FAB2 devices will have higher drive strength compared to FABl devices.

#### **2.3 Transistor Level Simulation Conclusions**

There were a couple of issues found from both FABs. There was skew in the I-V characteristics in FAB1 and FAB2 in the triode regions for N/PMOS transistors. This can lead to a major problem within analog circuitries. The slope difference in the triode region for I-V characteristics can manifest itself by causing higher rise and fall times for signal transitions. It can also increase the amount of jitter embedded in the signals as well as reduced maximum operating frequency.

FAB2 devices in general will perform better than FABl devices for both analog and digital circuitries. For NMOS transistors FAB1 processed devices have  $V_{TH}$ of 600mV while FAB2 processed devices have  $V<sub>TH</sub>$  of 700mV. For PMOS transistors FAB1 processed devices have  $V<sub>TH</sub>$  of 810mV while FAB2 processed devices have  $V_{TH}$  of 720mV. The gap resulting from the  $V_{TH}$  difference of NMOS and PMOS transistors will cause "undefined" outputs. Thus, FABI devices will have bigger undefined gap compared to FAB2 devices. This gap is due to the N/PMOS process skew and can be devastating for both analog and digital circuits.

Such differential skew presence in the analog signal causes increased rise and fall times. This also implies decreased pulse width of the signal, therefore causing a limitation in the operating frequency. Increased differential skew also decreases the signal integrity by decreased data-eye while at the same time increasing the amount of jitter present in the signal. Having this in mind, it is apparent that because FAB2 devices have lower differential skew compared to FABI, the FAB2 devices will be able to operate at higher frequency and have better signal integrity than FABI devices.

From the digital circuit domain, this N/PMOS skew will lead to a longer "unknown" region, causing higher setup and hold time requirements. Because digital signals only care about the saturation region of the signal, only a solid '1'

18

or '0' value is important to digital circuitries. Therefore, when there are longer transition gaps from "undefined" region, downstream circuits need longer setup and hold times to be able to latch the correct data. Without longer setup and hold times, the transfer data can be corrupted. Previous assessments from both FAB suggest that FAB2 devices will operate faster and more reliably compared to FAB1 devices, because the FAB2 devices have less NIPMOS skew compared to FAB<sub>1</sub> devices.

The transconductance simulation shows that FAB2 NMOS transistors would have higher DC operating current by about 30µA compared to FAB1 NMOS transistors. Although the simulation shows higher current draw for FAB2 devices compared to FAB1 devices, this is not necessarily a "bad" thing. Though there is a potential problem with power consumption of the devices due to higher current draw, it also means that FAB2 devices will have higher drive capabilities. Therefore, both FAB1 and FAB2 devices are desirable depending on the application. For low power requirement applications, FAB1 devices will be more desirable to minimize the power consumption. For applications that require higher performance, FAB2 devices will be more advantageous because the transistors can drive more loads in the output and signal integrity will be better.

Now that the transistor level simulations have been reviewed, let us move onto higher-level simulations.

# **Chapter 3. Analysis of Gate Level HSPICE Simulation Results**

This chapter shows the analysis of multiple transistor device performance from the two different FABs. Voltage transfer, five-stage inverter, and five-stage ring oscillator characteristics were simulated. For convenience, the length of transistors is set to 180nm for both N and P channel transistors and width of the transistors is set to 1440 for P channel and 720nm for N channel for voltage transfer characteristics simulation. This is to offset slower P channel electron drift velocity. Then five-stage inverter and ring oscillator simulations are conducted with the length of 180nm for both N and P channel, and the width of 3600nm for P channel and 1800nm for N channel transistors. The width of transistors has increased since the five-stage invertors needs higher drive strength.

### **3.1 Voltage Transfer Characteristics**

The simple inverter model used in this analysis is shown in Figure 6. Figure 7 simply shows the voltage transfer characteristic for basic inverters with different process parameters provided from FAB1 and FAB2.



#### **Figure 6 Simple Inverter model used for Voltage transfer characteristics**



**Figure 7 Voltage transfer characteristics of simple inverter (Vin vs Vout)** 



**Figure 7 (Continue)** 

As shown in Figure 7, output voltage characteristics show that FABI and FAB2 have almost the same characteristics in the saturation region. However, in the triode region, from Vin of 0.6V to 1 .OV, FAB2 is slightly delayed behind FABI . In the lower voltages, slope is greater for FABI, while slope of FAB2 device becomes greater beyond -800mV point. At this point there are about 22mV Vin difference from FABI to FAB2.

This means that during the transition point, FAB2 devices would switch faster than FABI devices for '1' to '0' transition. However, FABI devices will switch faster for '0' to '1' transition. This effect can possibly enhance the digital switching speed since digital circuits only respond when the signal reaches VOL/VOH. Overall switching speed for both devices would stay about the same.

A closer analysis of the slope shows that between Vin of 720mV to 810mV, FAB1 devices have a slope of -8.33 while FAB2 devices have a slope of -6.22. Between Vin of 810mV to 900mV, FAB1 devices have a slope of -8.11 while FAB2 devices have a slope of -10.22. This suggests that FABl devices' transition is more linear compared to FAB2 devices' transition slope. From the analog circuit point of view, FABl devices would be more desirable since their transient curve is more linear than FAB2 devices.



**Figure 8 Current Draw during the inverter switch (Vin vs Iin)** 



**Figure 8 (Continue)** 

Figure 8 shows the current draw from a Vdd power supply for FAB1 and FAB2 devices. Again there is almost no difference between the two. However, a closer look at the ~800mV Vin point on x-axis shows that total current draw from FAB1 device is -72µA and FAB2 is -70µA. The 2µA difference in instantaneous peak current draw during this operation seems to be driving the difference on the slope of two inverters.

This also means that there will be a difference in power consumption whenever the transistors go thru a transition or switching. Let's consider a system that consists of one million transistors and assume about ten percent of the transistors will be switching at the same time. When these 100,000 transistors are switching at the same time, if the system is built from FABI, the device will draw instantaneous peak current of 7.2A or instantaneous peak power of 12.96Watts. If the system is built from FAB2, the device will draw instantaneous peak current of 7.OA or instantaneous peak power of 12.6Watts.

The small difference of power consumption difference would cause devices from FABI to draw much more compare to its counter part from FAB2 during multi-million transistors switches. Such small differences can manifest to become signal integrity problems considering slower process corners, low V<sub>DD</sub>, and high temperature environments. Such conditions will slow down the device operation considerably and degrade the device performance.

#### **3.2 Five-Stage Inverter Characteristics**

Figure 9 shows the five-stage inverter chain model used in this chapter for an ideal square wave input. Figure 10 shows the output of the five identical inverters with annotated delay and parasitic capacitances for the first input cycle of the simulation. This demonstrates the associated propagation delay through five inverter chains. For the sake of simulation the distances between each inverter are neglected, because of the distance between each inverter will vary for design to design. However, for real device simulations, one has to incorporate the effect of wire resistances as well as capacitances. To the first order approximation, the metal resistance is 50m $\Omega$ /square and the metal capacitance is 0.1fF/ $\mu$ m. Point 'a' indicated in Figure 9 is the input 'Vin' as shown in Figure 10, and point 'b' indicates output 'Vout'. chapter for an<br>tical inverters<br>t cycle of the<br>p through five<br>each inverter<br>ary for design<br>rate the effect<br>oximation, the<br> $F/\mu m$ . Point 'a'<br>and point 'b'<br>p to the set of the<br>p e



**Figure 9 Identical Five Stage Inverter Chain** 



**Figure 10 Five-Stage Inverter Chain Voltage Characteristics (Voltage vs Time)** 



**Figure 10 (Continue)** 

The outputs of this series of inverters are loaded with another of the same type of inverter to keep the loading termination consistent at the output. This graph shows that the propagation delay associated with five-stage inverters are  $~130$ ps for FAB2 devices and ~140ps for FAB1 devices. There is roughly a 10ps or 7.7% propagation delay difference from FABl to FAB2 devices when signal is being propagated from point 'a' to 'b.' From this result, FAB1 seems to have higher impedance loading than FAB2, causing the delay to be increased as the signals propagate through the inverters. Each inverter adds -26ps for FAB2 and -28ps for FAB1. Thus there is a  $\sim$  2ps or 7.7% difference in propagation delay from FAB1 to FAB2.

A 2ps difference in delay in signal propagation within digital circuitries may not cause any harm as long as the digital circuits operate at a slower rate by limiting maximum operating frequency. Still, this would cause delayed clock distribution circuitries and increased signal propagation delay.

This can also cause a race condition in the critical path of the data. These effects are impossible to analyze using simulation tools. In order to estimate the possible effects, real device measurements from both FABs are required. With real-data at hand, it is possible to deduce the standard deviation of each delay to see how reliable the system will be.

Although the simulation result shows that FAB2 devices will run at a higher rate compared to FAB1 devices, if FAB2 devices' measurements has a higher variation than FAB1 devices, then FAB1 devices will be more reliable.

In either case, if the circuits are designed properly with this delay in mind, devices fabricated from both FAB1 and FAB2 should not cause much problems. Otherwise, it will be required to re-design in order to eliminate possible critical path problems and make the variation smaller to make the device more reliable.

28

In analog circuits, however, this delay can pose much bigger problems. The analog signal spends most of the time at the transition point rather than saturation point of the signal. This amount of delay means the analog signals have 2ps less time to rise or fall to either '1' or '0' value. This can ultimately cause smaller signal swing at maximum operating frequency or slower operation.

 $\sim 10^7$ 

 $\hat{\boldsymbol{\beta}}$ 

 $\sim$ 

### **3.3 Five-Stage Ring Oscillator Characteristics**

The five-stage ring oscillator is similar to the five-stage inverter as shown in section 3.2. The five-stage ring oscillator is differentiated from a five-stage inverter because it has a line connecting point 'a' and 'b' in the inverter chain as shown in Figure 11. Since the voltage at point 'a' oscillates like a clock, this type of inverter chain in Figure 11 is called a ring oscillator. The ring oscillators are the common test devices for checking circuit speed. Similar to five-stage inverter model, each gate distance is neglected. Again, in order to simulate the real-life device, the designer needs to incorporate the metal resistance and capacitance. Figure 12 shows the first four cycles of simulation results from the five-stage ring oscillator.



**Figure 11 Five-Stage Ring Oscillator** 



**Figure 12 Five-Stage Ring Oscillator Voltage Characteristics (Voltage vs Time)** 



**Figure 12 (Continue)** 

Since there was a propagation delay difference between FABl and FAB2 inverter models as shown in section 3.2, it is expected that there is a similar effect on the ring oscillator model. As shown in Figure 12, the different amount of internal loading of each FAB model distinguishes the period of FABI and FAB2 oscillating signals.

The FAB1 model reveals the clock pattern with a period of  $\sim$ 260ps while the FAB2 model reflects -240ps period. Around 20ps or 8.3% difference in their period is observed, as it was shown in section 3.2. This 20ps difference explains the clock frequency offset generated from both oscillators. The FABI ring oscillator runs at 3.85GHz while FAB2 oscillator runs at 4.17GHz. This small propagation delay caused by the difference in parasitic loading results in a -0.32GHz operating frequency difference.

These results show that the maximum frequency clock that can be generated from either FABI or FAB2 will be limited by the amount of propagation delay of their clock circuitry. From the simulation, FABI devices' propagation delay is less then FAB2 devices.' Thus the clock circuitry built on FABI process would have higher operating frequency. With process, voltage, and temperature variation, this can actually cause FAB2 devices to under-perform.

#### **3.4 Gate Level Simulation Results**

From the simulation results, there were not any significant differences between FABI and FAB2 processed devices except for the propagation delay difference between the two. The FABI processed devices have 2ps less propagation on 26ps delay than FAB2 processed devices. Depending on the application, this difference can have huge impact. For lower frequency applications, this should not cause and problems but for higher frequency applications, FABI would be preferable.

32

# **Chapter 4. Coupling and Power Bus Resistance Effect of HSPICE Simulation Results**

This chapter gives a simple analysis of system level performance and its possible outcome with given variable settings. It discusses the cross talk effect by use of coupling capacitor between two live wires and power grid resistance effect by increasing resistance of a power bus connected to a series of inverters. As before, the length of transistors is set to 180nm for both N and P channel transistors and the width is set to 18pm for P channel and 9pm for N channel transistors for aggressor line and 14.4pm for P channel and 7.2pm for N channel transistors for victim line for cross talk effect simulation. To highlight the effect of inter-symbol-interference, the size of the transistors has increased to increase the drive strength. The power grid resistance simulation is conducted with the length of 180nm for both N and P channel, and the width of 1440nm for P channel and 720nm for N channel transistors. The typical transistor size has been used to simulate typical power consumption environment.

### **4.1 Cross Talk Effect of Coupling Capacitances**

This section deals with two adjacent lines with 100fF coupling capacitance between them, which is approximately equivalent to  $1 \mu m$  distance between two adjacent signal wires. The coupling capacitance circuit model shown in Figure 13 has an effect similar to crosstalk. Such crosstalk or inter-symbol interference within the device can cause huge performance reductions due to induced deterministic jitter. This section deals with inter-symbol interference or crosstalk by pseudo-simulation describing two closely located wires with high-speed signals. All the gates and circuit components are set apart by a minimum line length of  $0.18 \mu m$ .



**Figure 13 Coupling Capacitance circuit model** 







Figure 14 shows the signal in the main, aggressor, line and in the adjacent, victim, line due to the coupling capacitance of 100fF. The coupling capacitance between two wires is an illustration of energy transfer from one wire to the other by the electro-magnetic field generated by the signal. Signals generated from both FAB1 and FAB2 produce a similar trend line. When the input is forced to 1.8V, the aggressor line is slowly increased toward 1.8V while charging up the coupling capacitor, causing the capacitively coupled voltage in the victim line. This victim for FAB1 is increased to a maximum of  $\sim$ 220mV while FAB2 is increased to a maximum of  $\sim$ 240mV. This means that the part of the aggressor signal is being propagated to the victim line. Unwanted signal in the victim line can consequently have a destructive effect on signals that travel through a victim line. Figure 14 reveals that FAB2 devices are more susceptible to internal crosstalk noise from adjacent lines compared to FABI devices. This effect can cause higher jitter propagation or crosstalk throughout the device for FAB2.

#### **4.2 Effect of Power Grid Resistance**

The issue of power grid resistance arises in any high power circuits. In a poorly designed power grid, part of the circuits cannot receive Vdd close to the full amount. Power grid resistance models simulate the power distribution circuit with varying power dissipation or voltage. As the part of circuit is located further away from the main power line, power grid resistance will increase.

The model used in this analysis consists of  $0.4\mu$ m wide wire with length of  $2\mu$ m and 1000um used as a power bus. The system consists of 32 inverters with the width of 1440nm for P channel and 720nm for N channel transistors, each connected to the power line. To sirnulate the worst-case condition, all the inverters are switched to high at the same time within a 100ps time period. Same inverter used in section 3.1 is used for this simulation.



**Figure 15 Resistance model in power grid** 



**Figure 16 Added resistance to power grid (Voltage vs Time)** 



**Figure 16 (Continue)** 

Figure 15 reflects the power grid resistance circuit used for this analysis. Figure 16 shows the effect of the power grid with a small amount of added resistance. The amount of resistance added is determined by varying the length of the wire between each transistor. Figure 16 is the simulation result with total wire length of 2pm. Each transistor is spaced equally apart by 0.0625pm. Since the added resistance is small, the voltage drop at the end of the inverter does not have much effect. There is a little bit of roll off close to ~420ps for FAB2 and ~480ps for FABI. The voltage drop is less then 1 OmV, which is negligible.

Reducing the bus length increased the resistance. This illustrates the possible problems with a poorly designed power grid. The result is as shown in Figure 17 with bus length of 1000 $\mu$ m where each transistor is set equally apart by 31.25 $\mu$ m. Now the power dissipation takes a huge effect on inverters located toward the end of the power grid. The voltage dropped by  $\sim$ 140mV for FAB2 devices while FAB1 devices dropped -130mV. This causes the power supply voltage to drop from 1.8V to 1.66V-1.67V. The voltage drop is more than enough to degrade the

38

operational performance of the inverter, even without taking the temperature effect into account in the simulation. If the temperature is increased, the voltage drop will increase even further causing possible malfunction of the device.



**Figure 17 Increased resistance in power grid (Voltage vs Time)** 



### **4.3 Coupling And Power Grid Resistance Results**

FAB2 devices are more susceptible to crosstalk noise compared to FAB1 devices as shown in section 4.1. FAB1 devices' interference signal peak in the victim line is at 220mV while FAB2 devices' interference signal peak is at 240mV. This means when the signal is propagating through an aggressor line, the victim line receives 20mV more interference for FAB2 devices. If the victim line also contains its own signal, the crosstalk from the aggressor line will collide with the signal within the victim line, potentially corrupting it. The crosstalk also adds more deterministic jitter within the signal causing higher total jitter within the signal. As observed from the coupling effect of two lines, FAB2 devices will have higher deterministic jitter compared to FAB1 devices.

As for the power grid resistance effect, there was almost no difference for the closely bounded gates of total length of 0.8pm for both FAB1 and FAB2 devices. When the length had been increased to 400µm, however, there was shown quite a difference between two FABs. FAB2 devices' power supply dropped by 140mV while FAB1 devices' power supply dropped by 1 30mV. This means that the gate, which is located at the end of the power bus, only receives 1.66V for FAB2 devices and 1.67V for FAB1 devices. With possible process parameter corners as well as temperature and power supply variation, 10mV will be enough to cause a device not to function for FAB2 devices while FAB1 device will be still functional.

# **Chapter 5. Conclusion**

The I-V characteristic of FAB1 and FAB2 devices shows that for NMOS transistors, FAB1 devices have higher increasing slope while for PMOS transistors, FAB2 devices have higher increasing slope. Because NMOS transistors will operate faster for FAE31 devices while PMOS transistors will operate faster for FAB2 devices, the combined operating frequency for both FABs will be similar. This, however, also indicates that both FABs devices will have higher signal skew and rise/fall time causing signal integrity problems for very high performance devices. The transconductance simulation shows that FAB2 devices would have higher power consumption for NMOS transistors due to DC offset voltage.

All the simulation in this paper is based on mean process parameters. There is also a factor of variation in process parameter one should consider. Even though the simulation result shows good results, larger variation in the process parameters can actually cause device to under-perform or malfunction in significant factor. However, due to the proprietary reasons, author is not permitted to disclose this information in this paper.

Most of the analysis from the gate level simulation shows that FAB2 devices would operate at a slower speed than the FAB1 devices, while the loading capacitances caused by parasitic load are more for FAB1 than FAB2. When looking at device operation from the top level, the operating frequency of each FAB would not be affected in a great deal either by faster transistor transition or by higher loading effects from FAB1 and FAB2. Incidentally, both effects cancel each other causing the operational frequency of FAB1 and FAB2 to be about the same.

The higher loading capacitance from FAB1 devices cause less crosstalk by decreasing the amount of jitter propagated from wire to wire At the same time it is increasing the propagation delay of each inverter. FAB2 devices show less loading capacitance by increasing the propagation delay of each inverter. At the same time it is increasing the cross-talk effect causing higher jitter propagation. Therefore, the differences between the two fabrication foundations are small enough that it would not cause a functional problem between two separately fabricated devices.

Although, the cost reduction of the wafer cost is one of the most critical factors in technology transfer, there are couple other factors that must considered. First, one must consider the amount of good die yield from each wafer. When one FAB provide wafer process with lesser cost but with much lower yield, then one might end up with lesser number of good dies with cheaper wafer cost. So at the end, one might not gain much cost reduction or possibly even increase per device cost. Another factor to be considered is the setup cost. If the mask cost is higher on one FAB to the other, cheaper wafer price might not be enough to offset the higher mask cost. Therefore, keeping all the factors in mind before one make a decision about the technology transfer to reduce the cost.

# **Appendix A HSPICE model source files**

All the HSPICE source files are included in this compressed file:

HSPICE source code.zip

### **File descriptions are as follows:**

- projl-1: I-V Characteristics for DSM transistors
- projl-2: Sub-threshold current
- proj1\_3: Voltage transfer characteristics
- proj2\_2: Five Stage Inverter Chain
- proj2-3: Five Stage Ring Oscillator
- proj3\_1: Coupling Capacitance
- proj3-2a: Added resistance to the power grid
- proj3-2b: Added more resistance to the power grid

## **Appendix A.1 I-V Characteristic HSPICE Source Code**

```
* IV Characteristics for DSM Transistors
* Set supply and library ........................................................................ 
.param Sup=1.8 * Must set before calling .lib 
.temp 25 * Override temperature by setting it before .lib 
.protect * Don't print the contents of library 
                      * Load the library for process corner 
* CHANGE THE FOLLOWING LINE IN ALL SPICE FILES FOR PMC-SIERRA 
.lib 
'/home/liblib/fab1/techdata/v1_11/models/b3_spdv_v1_11/standalone/hspice/PR
0CESS.L' TT 
.unprotect * Resume printing SPICE deck 
.opt scale=O.O90u * Set lambda 
* Save results of simulation for viewing 
.options post 
            * Define power supply ....................................................................... 
.global Vdd Gnd 
Vdd Vdd Gnd 'Sup' * Sup is set above
* Top level simulation netlist ....................................................................... 
mp drainp gatep Vdd Vdd PE2 I=2 w=8 ad=20 pd=4 as=20 ps=4<br>mn drainn gaten Gnd Gnd NE2 I=2 w=8 ad=20 pd=4 as=20 ps=4
       drainn gaten Gnd Gnd NE2 l=2 w=8 ad=20 pd=4 as=20 ps=4*****new*****
Vdsp Vdd drainp dc 
Vgsp Vdd gatep dc 
Vdsn drainn 0 dc 
Vgsn gaten 0 dc 
************
*.dc Vdsp 0 'Sup"Sup/20' Vgsp 0 'Sup' 'Sup/3'
.dc Vdsn 0 'Sup"Sup/20' Vgsn 0 'Sup' 'Sup/3'
.plot dc 11 (mp)
.plot dc I1 (mn) ....................................................................... 
* End of Deck ....................................................................... .end
```
#### **Appendix A.2 Sub-threshold current HSPICE Source Code**

```
* Vt, Subthreshold current and Temperature ........................................................................ 
* Set supply and library ....................................................................... 
.param Sup=1.8 * Must set before calling .lib 
.temp 25 * ADJUST THIS TO CHANGE TEMP 
.protect * Don't print the contents of library 
                        * Load the library for process corner 
.lib 
'/home/liblib/fab1/techdata/v1 11/models/b3 spdv v1 11/standalone/hspice/PR
OCESS.L'TT
.unprotect * Resume printing SPICE deck 
.opt scale=O.O90u * Set lambda 
* Save results of simulation for viewing 
.options post 
....................................................................... 
* Define power supply 
                                ....................................................................... 
.global Vdd Gnd 
Vdd Vdd Gnd 'Sup' * Sup is set above
* Top level simulation netlist ....................................................................... 
mp Gnd gatep Vdd Vdd PE2 l=2 w=20 ad=20 pd=4 as=20 ps=4<br>mn Vdd gaten Gnd Gnd NE2 l=2 w=8 ad=20 pd=4 as=20 ps=4
                gaten Gnd Gnd NE2 l=2 w=8 ad=20 pd=4 as=20 ps=4
****new***** 
Vgsp gatep 0 dc 
Vgsn gaten 0 dc ************ 
*.dc Vgsp 0 'Sup' 'Sup/201 
.dc Vgsn 0 'Sup' 'Sup/201 
*.plot dc 11 (mp)
.plot dc = 11 (mn)
                                ........................................................................ 
* End of Deck ....................................................................... .end
```
**Appendix A.3 Voltage transfer characteristics HSPICE Source Code** 

```
* VTC 
                          ........................................................................ 
* Set supply and library *********************************************.k************************* 
.param Sup=1.8 * ADJUST THIS TO CHANGE VTC<br>temp 25 * Override temperature by setting it.
                       * Override temperature by setting it before .lib
.protect * Don't print the contents of library 
                       * Load the library for process corner 
.lib 
'/home/liblib/fab1/techdata/v1 11/models/b3_spdv_v1_11/standalone/hspice/PR
0CESS.L' TT 
.unprotect * Resume printing SPICE deck
.opt scale=O.O90u * Set lambda 
* Save results of simulation for viewing 
.options post 
         * Define power supply 
                            ....................................................................... 
.global Vdd Gnd 
Vdd Vdd Gnd 'Sup' ....................................................................... 
* Top level simulation netlist ....................................................................... 
m1 Out In1 Vdd Vdd PE2 \leq 2 w=16 ad=200 as=200 pd=40 ps=40
m2 Out \ln 100 NE2 \text{I} = 2 \text{ w} = 8 \text{ ad} = 100 \text{ as} = 100 \text{ pd} = 20 \text{ ps} = 20* Stimulus 
........................................................................ 
Vinl In1 Gnd DC ........................................................................ 
* Simulation 
                 ....................................................................... 
* for Id vs. Vds 
.dc Vin1 0 'Sup' 'Sup/20'
         * Measurements 
                     ....................................................................... .plot DC V(Out)
.plot DC I(Vdd)
```
 $\ddot{x}$ \* End of Deck ....................................................................... .end

# **Appendix A.4 Five Stage Inverter Chain HSPICE Source Code**



m9 Out4 Out3 Vdd Vdd PE2  $l=2$  w=40 ad=200 as=200 pd=40 ps=40 m10 Out4 Out3 0 0  $NE2$   $|=2$  w=20 ad=100 as=100 pd=20 ps=20 \* 1 OX inverter m11 Out5 Out4 Vdd Vdd PE2  $l=2$  w=40 ad=200 as=200 pd=40 ps=40 m12 Out5 Out4 0 0 NE2 l=2 w=20 ad=100 as=100 pd=20 ps=20 \* Stimulus ....................................................................... Vinl In1 Gnd PWL (0 0 25ps 0 30ps 1.8 195ps 1.8 200ps 0) ....................................................................... \* Simulation ........................................................................ .tran 5ps 350ps \* You can add other requested simulations here<br>\* or write your own spice deck \* or write your own spice deck ........................................................................ \* Measurements ....................................................................... .print tran V(ln1) V(Out4) \* End of Deck ....................................................................... .end

## **Appendix A.5 Five Stage Ring Oscillator HSPICE Source Code**



Define power supply

.global Vdd Gnd Vdd Vdd Gnd 1.8 ....................................................................... \* Top level simulation netlist ........................................................................ \* 10X inverter<br>m1 Out In1 Vdd Vdd m1 Out In1 Vdd Vdd PE2  $1=2$  w=40 ad=200 as=200 pd=40 ps=40 m2 Out  $ln 1 0 0$  NE2  $l=2$  w=20 ad=100 as=100 pd=20 ps=20 \* 1 OX inverter m3 Out1 Out Vdd Vdd PE2  $|=2$  w=40 ad=200 as=200 pd=40 ps=40 m4 Out1 Out 0 0 NE2 i=2 w=20 ad=100 as=100 pd=20 ps=20 \* 1 OX inverter m5 Out2 Out1 Vdd Vdd PE2  $=$   $=$  40 ad $=$  200 as $=$  200 pd $=$  40 ps $=$  40 m6 Out2 Out1 0 0 NE2 1=2 w=20 ad=100 as=100 pd=20 ps=20 \* 1 OX inverter  $m$ 7 Out3 Out2 Vdd Vdd PE2  $|=2$  w=40 ad=200 as=200 pd=40 ps=40 m8 Out3 Out2 0 0 NE2 1=:2 w=20 ad=100 as=100 pd=20 ps=20 \* 1 OX inverter m9 In1 Out3 Vdd Vdd PE2  $|=2$  w=40 ad=200 as=200 pd=40 ps=40 m10 In1 Out3 0 0 NE2 1=2 w=20 ad=100 as=100 pd=20 ps=20 ....................................................................... \* Stimulus ....................................................................... .ic V(lnl)=1.8V V(out)=O.OV V(out1 j=1.8V V(out2)=O.OV V(out3)=1.8V ....................................................................... \* Simulation ....................................................................... .tran 5ps 900ps uic \* You can add other requested simulations here \* or write your own spice deck ....................................................................... \* Measurements ....................................................................... .print tran V(ln1) V(Out3) ....................................................................... \* End of Deck .......................................................................

.end

### **Appendix A.6 Coupling Capacitance HSPICE Source Code**

\* Coupling Capacitance **\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*,h\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\*\***  \* Set supply and library ....................................................................... .param Supply=1.8 \* Must set before calling .lib \*.temp 25 \* Override temperature by setting it before .lib .protect \* Don't print the contents of library \* Load the library for process corner .lib '/home/liblib/fab1/techdata/v1\_11/models/b3\_spdv\_v1\_11/standalone/hspice/PR OCESS.L'TT .unprotect \* Resume printing SPICE deck<br>
.opt scale=0.090u \* Set lambda .opt scale=0.090u \* Save results of simulation for viewing .options post \* Define power supply ....................................................................... .global Vdd Gnd Vdd Vdd Gnd 1.8 ....................................................................... \* Top level simulation netlist ....................................................................... \* 50X inverter ml Out In1 Vdd Vdd PE2 1=2 w=200 ad=1000 as=1000 pd=200 ps=200 m2 Out In1 0 0 NE2 1=2 w=100 ad=500 as=500 pd=100 ps=100 \* 1X inverter \*m3 Out1 Vdd Vdd Vdd PE2  $|=2$  w=2 ad=200 as=200 pd=40 ps=40 \*m4 Out1 Vdd 0 0 NE2  $|=2$  w=2 ad=100 as=100 pd=20 ps=20 \* 40X inverter m3 Out1 Vdd Vdd Vdd PE2  $|=2$  w=160 ad=800 as=800 pd=160 ps=160 m4 Out1 Vdd 0 0 NE2  $|=2$  w=80 ad=200 as=200 pd=80 ps=80 Cg1 Out 0 50fF \*adjust this to compute Ceff Cc Out1 Out  $100 \text{fF}$  \* adjust this to compute Cq Cg2 Outl 0 60fF ........................................................................ \* Stimulus ....................................................................... Vinl In1 Gnd PWL (0 1.8 25ps 1.8 30ps 0 195ps 0 200ps 0) .......................................................................

\* Simulation ....................................................................... tran 5ps 350ps. \* You can add other requested simulations here \* or write your own spice deck **........................................................................**  \* Measurements ....................................................................... .print tran V(0ut) V(Out1)  $\frac{1}{2}$ plot tran V(Out) V(Out1) \* End of Deck ....................................................................... .end

## **Appendix A.7 Added resistance to the power grid HSPICE Source Code**



.subckt inv in out  $Vp$  \* This is an inverter mp out in  $Vp$  PE2 mp out in Vp Vp PE2  $+$   $|=2$   $w=16$  $+$  ad=0 pd=0  $+$  as=0 ps=0 mn out in Gnd Gnd NE2  $+$  1=2  $w=8$  $+$  ad=0 pd=0  $+$  as=0 ps=0 .ends .subckt signalwire nl n2 C1 n1 Gnd 'cLength\*wireLength/2'<br>Rpi n1 n2 'rSquare\*wireLength/wi Rpi n1 n2 'rSquare\*wireLength/wireWidth'<br>C2 n2 Gnd 'cLength\*wireLength/2' n2 Gnd 'cLength\*wireLength/2' .ends xinvl in1 outl Vpl inv M=l xwire1 out1 in2 signalWire rgrid1 Vdd Vp1 'gridRSquare\*gridLength/gridWidth' xinv2 in2 out2 Vp2 inv M=l xwire2 out2 in3 signalwire rgrid2 Vp1 Vp2 'gridRSquare\*gridLength/gridWidth' xinv3 in3 out3 Vp3 inv M=l xwire3 out3 in4 signalwire rgrid3 Vp2 Vp3 'gridRSquare\*gridLength/gridWidth'  $xinv4$  in4 out4  $Vp4$  inv  $M=1$ xwire4 out4 in5 signalwire rgrid4 Vp3 Vp4 'gridRSquare\*gridLength/gridWidth' xinv5 in5 out5 Vp5 inv M=l xwire5 out5 in6 signalwire rgrid5 Vp4 Vp5 'gridRSquare\*gridLength/gridWidth' xinv6 in6 out6 Vp6 inv M=l xwire6 out6 in7 signalwire rgrid6 Vp5 Vp6 'gridRSquare\*gridLength/gridWidthl xinv7 in7 out7 Vp7 inv M=l xwire7 out7 in8 signalwire rgrid7 Vp6 Vp7 'gridRSquare\*gridLength/gridWidthl

xinv8 in8 out8 Vp8 inv M=l xwire8 out8 in9 signalwire rgrid8 Vp7 Vp8 'gridRSquare\*gridLength/gridWidthl xinv9 in9 out9 Vp9 inv M=l xwire9 out9 in10 signalWire rgrid9 Vp8 Vp9 'gridRSquare\*gridLength/gridWidthl  $xinv10$  in10 out10 Vp10 inv  $M=1$ xwire 10 out 10 in 11 signal Wire rgrid10 Vp9 Vp10 'gridRSquare\*gridLength/gridWidth'  $xinv11$  in11 out11 Vp11 inv  $M=1$  $xwire11 out11$  in12 signalWire rgrid11 Vp10 Vp11 'gridRSquare\*gridLength/gridWidth' xinvl2 in12 out12 Vp12 inv M=l xwire12 out12 in13 signalWire rgrid12 Vp11 Vp12 'gridRSquare\*gridLength/gridWidth'  $xinv13$  in 13 out 13 Vp13 in  $w = M = 1$ xwire 13 out 13 in 14 signal Wire rgridl3 Vp12 Vp13 'gridRSquare\*gridLength/gridWidth'  $xinv14$  in14 out14 Vp14 inv M=1 xwire14 out14 in15 signalWire rgrid14 Vp13 Vp14 'gridRSquare\*gridLength/gridWidth' xinvl5 in15 out15 Vp15 inv M=l xwire 15 out 15 in 16 signal Wire rgrid15 Vp14 Vp15 'gridRSquare\*gridLength/gridWidth' xinvl6 in16 out16 Vp16 inv M=l xwire16 out16 in17 signalWire rgrid16 Vp15 Vp16 'gridRSquare\*gridLength/gridWidth' xinvl7 in17 out17 Vp17 inv M=l xwire17 out17 in18 signalWire rgrid17 Vp16 Vp17 'gridRSquare\*gridLength/gridWidth' xinvl8 in18 out18 Vp18 inv M=l xwire 18 out 18 in 19 signal Wire rgrid18 Vp17 Vp18 'gridRSquare\*gridLength/gridWidth' xinvl9 in19 out19 Vp19 inv M=l xwire19 out19 in20 signalWire

rgrid19 Vp18 Vp19 'gridRSquare\*gridLength/gridWidth'  $xinv20$  in20 out20  $Vp20$  inv  $M=1$ xwire20 out20 in21 signalwire rgrid20 Vp19 Vp20 'gridRSquare\*gridLength/gridWidthl  $xinv21$  in21 out21  $Vp21$  inv  $M=1$ xwire21 out21 in22 signalwire rgrid21 Vp20 Vp21 'gridRSquare\*gridLength/gridWidthl xinv22 in22 out22 Vp22 inv M=l xwire22 out22 in23 signalwire rgrid22 Vp21 Vp22 'gridRSquare\*gridLength/gridWidthl  $xinv23$  in23 out23  $Vp23$  inv  $M=1$ xwire23 out23 in24 signalwire rgrid23 Vp22 Vp23 'gridRSquare\*gridLength/gridWidthl  $xinv24$  in24 out24 Vp24 inv M=1 xwire24 out24 in25 signalwire rgrid24 Vp23 Vp24 'gridRSquare\*gridLength/gridWidth' xinv25 in25 out25 Vp25 inv M=l xwire25 out25 in26 signalwire rgrid25 Vp24 Vp25 'gridRSquare\*gridLength/gridWidthl xinv26 in26 out26 Vp26 inv M=l xwire26 out26 in27 signalwire rgrid26 Vp25 Vp26 'gridRSquare\*gridLength/gridWidthl  $xinv27$  in27 out27  $Vp27$  inv  $M=1$ xwire27 out27 in28 signalwire rgrid27 Vp26 Vp27 'gridRSquare\*gridLength/gridWidthl xinv28 in28 out28 Vp28 inv M=l xwire28 out28 in29 signalwire rgrid28 Vp27 Vp28 'gridRSquare\*gridLength/gridWidthl xinv29 in29 out29 Vp29 inv M=l xwire29 out29 in30 signalwire rgrid29 Vp28 Vp29 'gridRSquare\*gridLength/gridWidthl  $x$ inv30 in30 out30 Vp30 inv  $M=1$ xwire30 out30 in31 signalwire rgrid30 Vp29 Vp30 'gridRSquare\*gridLength/gridWidth'

xinv31 in31 out31 Vp31 inv M=l xwire31 out31 in32 signalwire rgrid31 Vp30 Vp31 'gridRSquare\*gridLength/gridWidthl xinv32 in32 out32 Vp32 inv M=l xwire32 out32 in33 signalwire rgrid32 Vp31 Vp32 'gridRSquare\*gridLength/gridWidth' .tran 6p 600p .plot tran V(Vp31) .end

### **Appendix A.8 Added more resistance to the power grid HSPICE Source Code**



.subckt inv in out Vp \* This is an inverter mp out in Vp Vp PE2  $+$   $|=2$   $w=16$  $+$  ad=0  $pd=0$  $+$  as=0 ps=0 mn out in Gnd Gnd NE2  $+$   $I=2$   $w=8$  $+$  ad=0 pd=0  $+$  as=0 ps=0 .ends .subckt signalwire nl n2 C1 nl Gnd 'cLenath\*wireLenath/2' 'rSquare\*wireLength/wireWidth' Rpi nl n2 C2 n2 Gnd 'cLength\*wireLength/2' .ends xinvl in1 outl Vp1 inv M=1 xwirel outl in2 signalWire rgrid1 Vdd Vp1 'gridRSquare\*gridLength/gridWidth' xinv2 in2 out2 Vp2 inv M=1 xwire2 out2 in3 signalWire 'gridRSquare\*gridLength/gridWidth' rgrid2 Vpl Vp2  $x$ inv $3$  in $3$ out<sub>3</sub>  $Vp3$  inv  $M=1$ xwire3 out3 in4 signalWire rgrid3 Vp2  $Vp3$ 'gridRSquare\*gridLength/gridWidth'  $x$ inv4 in4 out4  $Vp4$  inv  $M=1$ xwire4 out4 in5 signalWire rgrid4 Vp3  $Vp4$ 'gridRSquare\*gridLength/gridW idth'  $x$ inv $5$  in $5$ out<sub>5</sub>  $Vp5$  inv  $M=1$ xwire5 out5 in6 signalWire rgrid5 Vp4  $Vp5$ 'gridRSquare\*gridLength/gridWidth' xinv6 in6 out<sub>6</sub> Vp6 inv M=l xwire6 out6  $in7$ signalWire rgrid6 Vp5 'gridRSquare\*gridLength/gridW idth'  $Vp6$  $xinv7$  in $7$ out7 Vp7 inv M=1 xwire7 out7 in<sub>8</sub> **signalWire** 'gridRSquare\*gridLength/gridWidth' rgrid7 Vp6  $Vp7$ xinv8 in8 out<sub>8</sub>  $Vp8$  inv  $M=1$ 

xwire8 out8 in9 signalWire rgrid<sub>8</sub> Vp7  $Vp8$ 'gridRSquare\*gridLength/gridWidth' xinv9 in9 out9 Vp9 inv M=l xwire9 out9 in10 signalWire rgrid9 Vp8 Vp9 'gridRSquare\*gridLength/gridWidthl  $xinv10$  in10 out10  $Vp10$  inv  $M=1$ xwire 10 out 10 in 11 signal Wire rgrid10 Vp9 Vp10 'gridRSquare\*gridLength/gridWidth'  $xinv11$  in11 out11  $Vp11$  inv  $M=1$ xwire11 out11 in12 signalWire rgrid11 Vp10 Vp11 'gridRSquare\*gridLength/gridWidth' xinvl2 in12 out12 Vp12 inv M=l  $xwire12 out12$  in13 signalWire rgrid12 Vp11 Vp12 'gridRSquare\*gridLength/gridWidth'  $xinV13$  in13 out13  $Vp13$  inv  $M=1$ xwire 13 out 13 in 14 signal Wire rgrid13 Vp12 Vp13 'gridRSquare\*gridLength/gridWidth' xinv14 in14 out14 Vp14 inv M=1<br>xwire14 out14 in15 signalWire  $xwire14$  out  $14$  in  $15$ rgridl4 Vp13 Vp14 'gridRSquare\*gridl,ength/gridWidth'  $xinv15$  in 15 out 15 Vp15 inv M=1 xwire15 out15 in16 signalWire rgrid15 Vp14 Vp15 'gridRSquare\*gridLength/gridWidth' xinvl6 in16 out16 Vp16 inv M=l xwire 16 out 16 in 17 signal Wire rgrid16 Vp15 Vp16 'gridRSquare\*gridLength/gridWidth' xinvl7 in17 out17 Vp17 inv M=l xwire17 out17 in18 signalWire rgrid17 Vp16 Vp17 'gridRSquare\*gridLength/gridWidth' xinvl8 in18 out18 Vp18 inv M=l xwire 18 out 18 in 19 signal Wire rgrid18 Vp17 Vp18 'gridRSquare\*gridLength/gridWidth' xinvl9 in19 out19 Vp19 inv M=l xwire19 out19 in20 signalWire rgrid19 Vp18 Vp19 'gridRSquare\*gridLength/gridWidth'

xinv20 in20 out20 Vp20 inv M=l xwire20 out20 in21 signalwire rgrid20 Vp19 Vp20 'gridRSquare\*gridLength/gridWidth'  $xiny21$  in21 out21  $Vp21$  inv  $M=1$ xwire21 out21 in22 signalwire rgrid21 Vp20 Vp21 'gridRSquare\*gridLength/gridWidth' xinv22 in22 out22 Vp22 inv M=l xwire22 out22 in23 signalWire rgrid22 Vp21 Vp22 'gridRSquare\*gridLength/gridWidth' xinv23 in23 out23 Vp23 inv M=l xwire23 out23 in24 signalwire rgrid23 Vp22 Vp23 'gridRSquare\*gridLength/gridWidth'  $xinv24$  in24 out24 Vp24 inv  $M=1$ xwire24 out24 in25 signalWire rgrid24 Vp23 Vp24 'gridRSquare\*gridl-ength/gridWidthl xinv25 in25 out25 Vp25 inv M=l xwire25 out25 in26 signalwire rgrid25 Vp24 Vp25 'gridRSquare\*gridl-ength/gridWidthl xinv26 in26 out26 Vp26 inv M=l xwire26 out26 in27 signalwire rgrid26 Vp25 Vp26 'gridRSquare\*gridl-ength/gridWidthl  $xinv27$  in27 out27  $Vp27$  inv  $M=1$ xwire27 out27 in28 signalwire rgrid27 Vp26 Vp27 'gridRSquare\*gridLength/gridWidthl xinv28 in28 out28 Vp28 inv M=l xwire28 out28 in29 signalwire rgrid28 Vp27 Vp28 'gridRSquare\*gridLength/gridWidth' xinv29 in29 out29 Vp29 inv M=l xwire29 out29 in30 signalwire rgrid29 Vp28 Vp29 'gridRSquare\*gridLength/gridWidthl xinv30 in30 out30 Vp30 inv M=l xwire30 out30 in31 signalwire rgrid30 Vp29 Vp30 'gridRSquare\*gridLength/gridWidth'  $x$ inv31 in31 out31 Vp31 inv  $M=1$ 

xwire31 out31 in32 signalWire rgrid31 Vp30 Vp31 'gridRSquare\*gridLength/gridWidth' xinv32 in32 out32 Vp32 inv M=l xwire32 out32 in33 signalwire rgrid32 Vp31 Vp32 'gridRSquare\*gridLength/gridWidth' .tran 6p 600p .plot tran V(Vp32)

.end

# **References**

1. Behzad Razavi, "Design of Analog CMOS Integrated Circuits", McGraw-Hill Science/Engineering/Math, 15 August, 2000

**2.** David A. Johns and Ken Martin, "Analog lntegrated Circuit Design", John Wiley & Sons Inc., 1997

**3.** Jan M. Rabaey, "Digital lntegrated Circuits", Prentice Hall Electronics and VLSI Series, 1996

4. Phillip E. Allen and Douglas R. Holberg, "CMOS Analog Circuit Design", **2nd**  Edition, Oxford University Press Inc., **2002** 

5. Res Saleh, D. Hodges, H. Jackson, "Analysis and Design of Digital lntegrated Circuits: In Deep Submicron", **3rd** Edition, McGraw-Hill, **2003**