



Unipark-1000

An Easy to Install Vehicle Parking Sensor



KENNY LAM – CEO

EDMOND MO – CFO

WILL ZHANG – COO

HAMIDREZA HAGHSHENAS – CTO



OUTLINE

- INTRODUCTION
 - TEAM, MISSION, TARGET CUSTOMER, FEATURES
- PROJECT MANAGEMENT
 - SCHEDULE, BUDGET, GROUP DYNAMICS
- DESIGN
- IMPLEMENTATION AND TESTING
- INDIVIDUAL INVOLVEMENT
- DEMO SECTION
- QUESTIONS



INTRODUCTION

TEAM MEMBERS

- KENNY LAM – CEO
- EDMOND MO – CFO
- HAMIDREZA HAGHSHENAS – CTO
- WILL ZHANG – COO

MISSION STATEMENT

TO MITIGATE THE HASSLES OF VEHICLE PARKING BY PROVIDING DRIVERS WITH EASY ACCESS TO ADVANCED PARKING ASSISTANCE TECHNOLOGY.



TARGET MARKET/CUSTOMER

- NON SKILLED INDIVIDUAL SHOULD BE ABLE TO INSTALL THIS PRODUCT WITH ONLY ONE SCREW DRIVER IN LESS THAN 15 MINUTES.
- COMMERCIAL TRUCKS WILL BE AVOIDING LONG WIRINGS.
- CANNOT AFFORD EXPENSIVE PARKING SENSORS

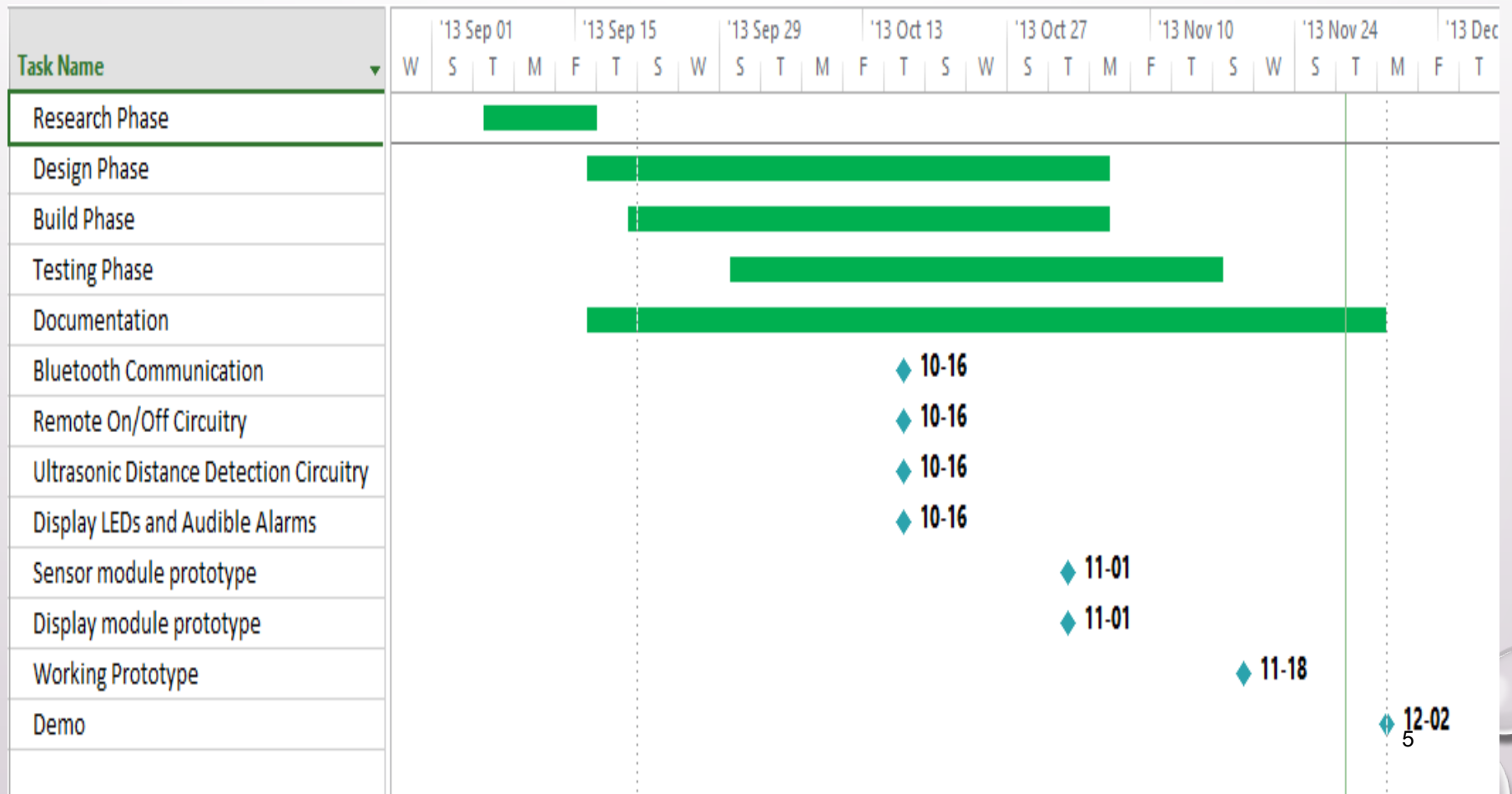


ADVANTAGE/NEEDS

- NO DAMAGE OR ANY DRILLING NEEDED TO INSTALL THE DEVICE.
- AVOID ANY WIRINGS
- WILL MAKE THE PARKING EASIER FOR SOME PEOPLE
- CHEAPER



PROJECT MANAGEMENT: THE SCHEDULE





PROJECT MANAGEMENT: THE BUDGET

Budget summary throughout the project:

- Funding from ESSS		+\$500.00
- Total spending on R&D effort	-\$777.65	
- Budget exceed by		+\$277.65

For more detail about the spending, please refer to the expense report.



PROJECT MANAGEMENT: GROUP DYNAMICS

- GROUP MEETING EVERY WEEK
- SEPARATE TASKS
- WORK TOGETHER TO SOLVE PROBLEM
- TEAM WRITING (GOOGLE DOC)
- COMMUNICATION THROUGH EMAILS, PHONE CALL AND CANVAS
- ENCOURAGE EACH OTHER
- TEAM PLANNING
- EMBRACING DIVERSITY



SYSTEM DESIGN: FUNCTIONALITY

- SYSTEM CONSISTS OF 2 SENSOR MODULES AND 1 DISPLAY MODULE
- COMMUNICATES DISTANCE DATA WIRELESSLY
- REFRESHES DATA 3 TO 4 TIMES PER SECOND
- REMOTELY POWERS SENSOR MODULES ON
- ULTRASONIC DISTANCE DETECTION

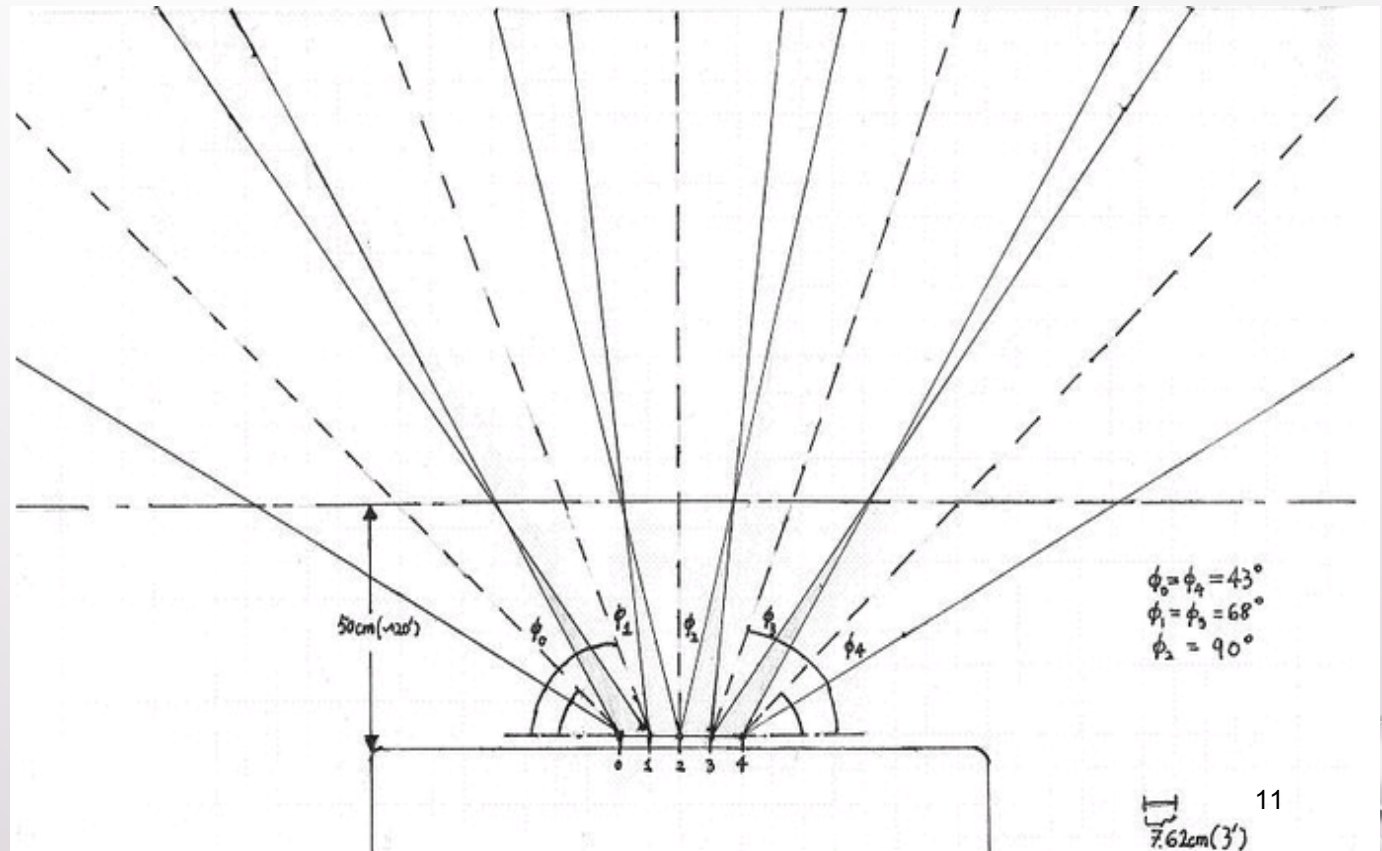
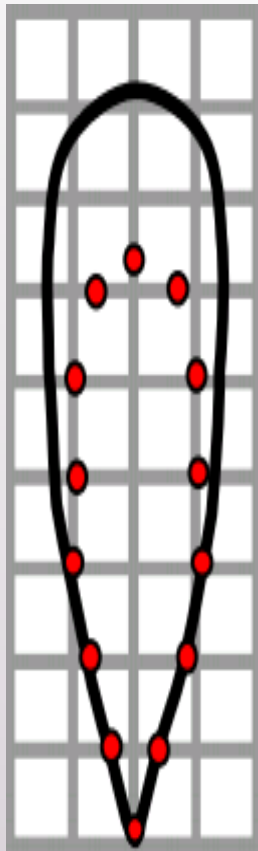


SYSTEM DESIGN: PARKING SENSOR TECHNOLOGY-1

- **ULTRASOUND VERSUS MAGNETORESISTIVE** DECIDED TO CHOOSE
ULTRASOUND TECHNOLOGY OVER MAGNETORESISTIVE DUE TO THE FORM FACTOR OF THE
SENSORS

USING ULTRASONIC SENSOR ALLOW A MORE COMPACT DESIGN

SYSTEM DESIGN: PARKING SENSOR TECHNOLOGY-2





SYSTEM DESIGN: INSTALLATION PROCESS

-> INSTALLATION VIDEO



SYSTEM DESIGN: REMOTE CIRCUIT

- WHY REMOTE CIRCUIT?
- USING 433MHZ RADIO FREQUENCY TRANSMITTER AND RECEIVER
- WHY RF ?
 - GOOD RANGE
 - SIMPLICITY
 - LOSS CHANGE OF INTERFERENCE PROBLEMS

PAIR TRANSMITTER AND RECEIVER WITH ENCODER AND DECODER TO BUILD A SIMPLE RF COMMUNICATION

- TRANSMITTING CIRCUIT - DISPLAY MODULE
- RECEIVING CIRCUIT - SENSOR MODULE



SYSTEM DESIGN: BLUETOOTH COMMUNICATION

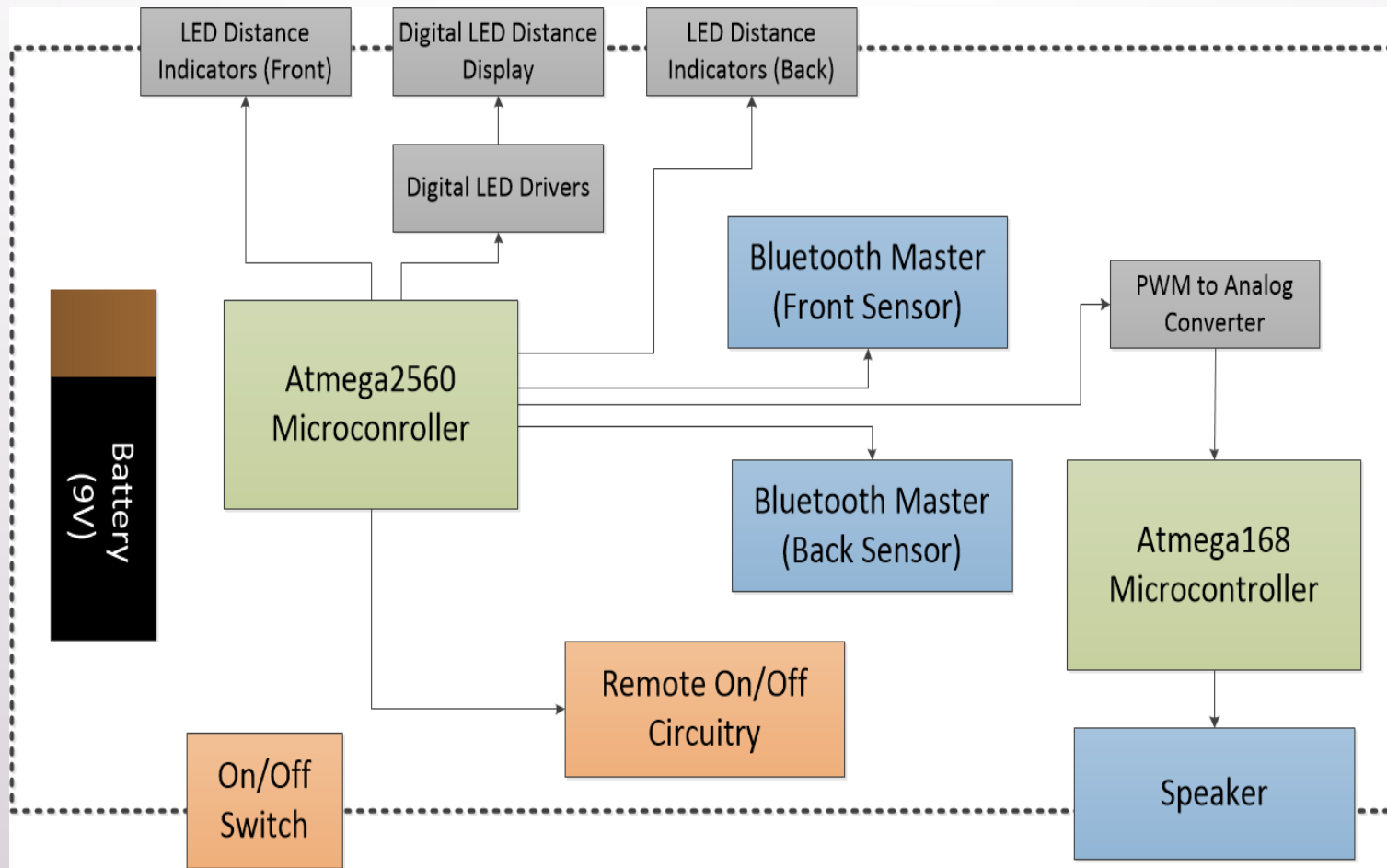
WHY BLUETOOTH COMMUNICATION?

- LOW POWER
- WELL DOCUMENTED
- EASY TO USE
- OTHER OPTIONS (WIFI, RF)

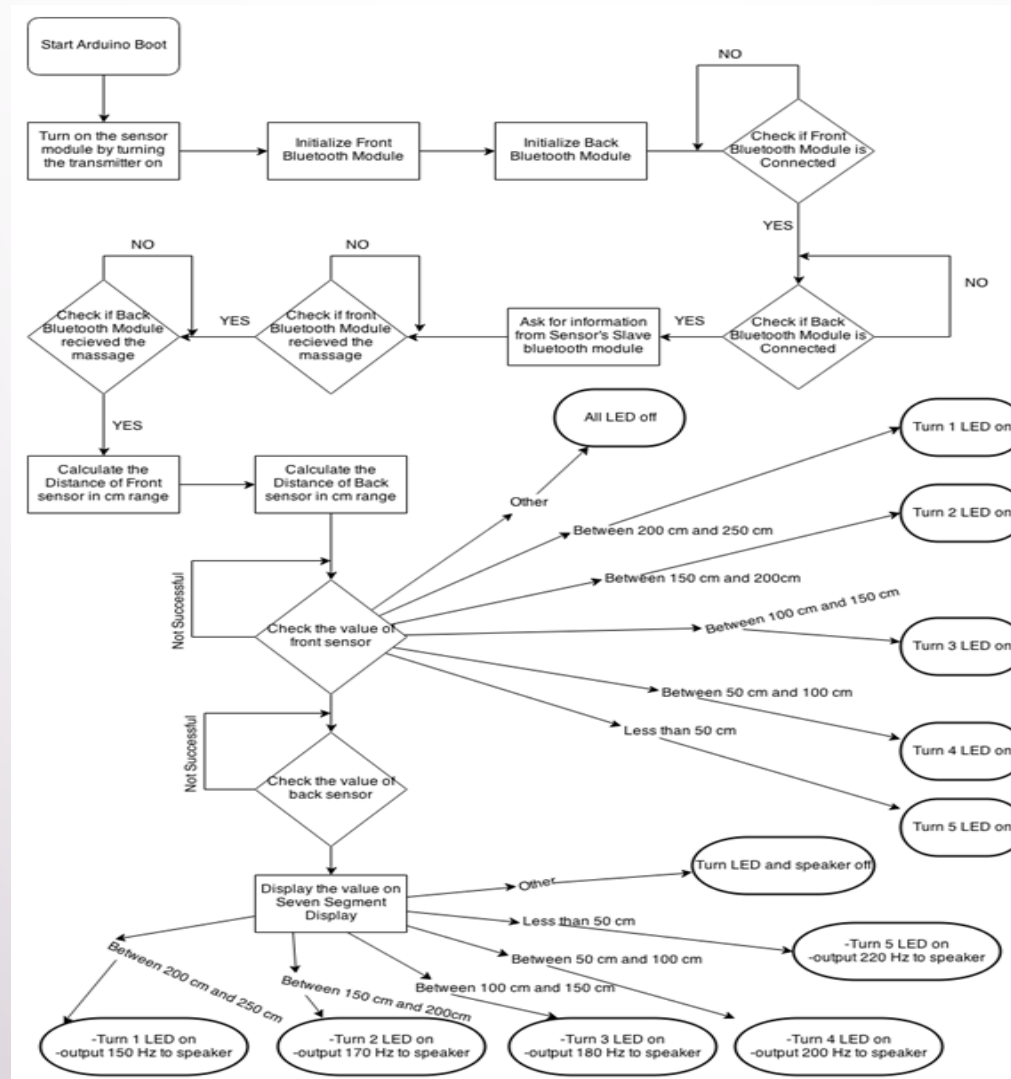


TECHNICAL INFORMATION

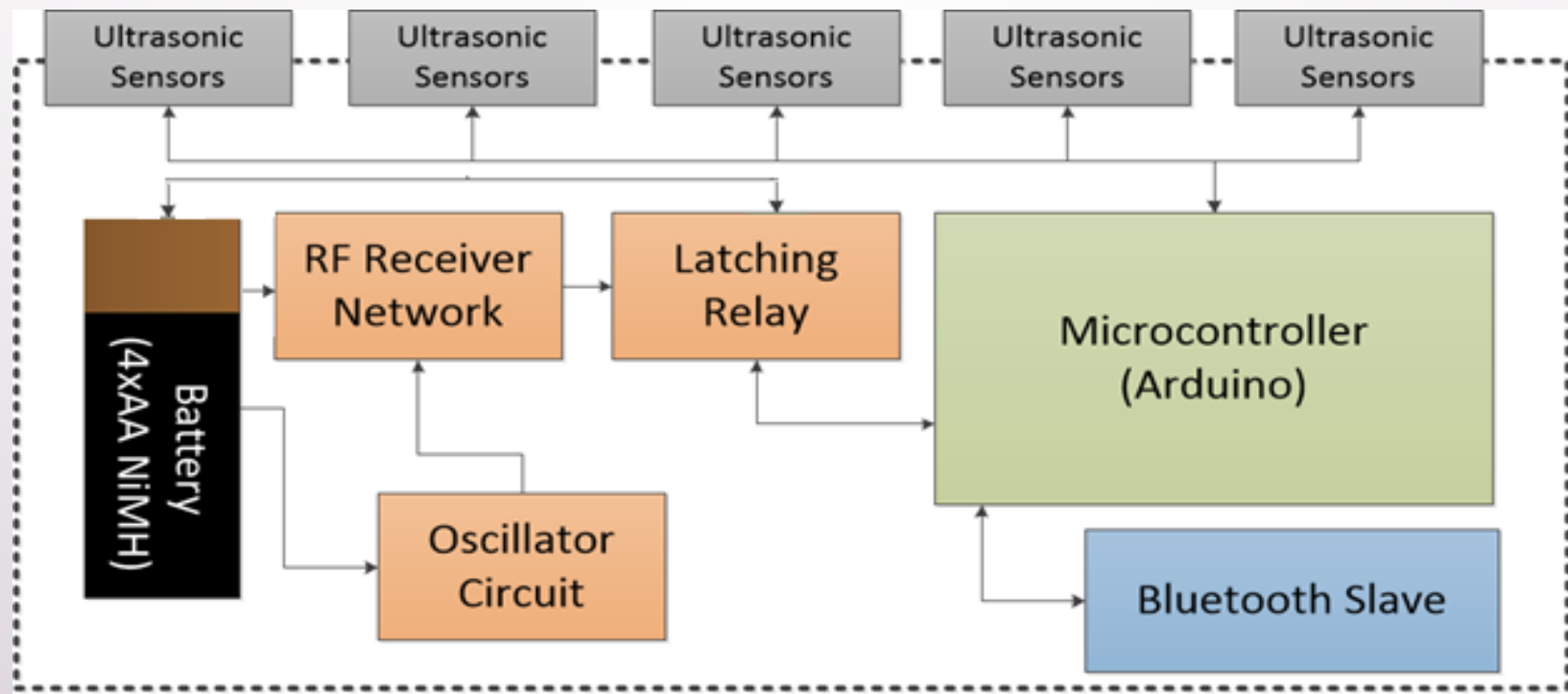
DISPLAY MODULE HARDWARE



SOFTWARE-DISPLAY MODULE



SENSOR MODULE HARDWARE



SENSOR MODULE SOFTWARE - 1

Pseudocode of application code on uController

```
void main() {  
    uint32 sensor_array[5];  
    float shortest_d;  
  
    while ( ;; ) {  
        sensor_array = read_range();  
        shortest_d = calculate_shortest_distance( sensor_array );  
        if ( bt_request_from_display_module() ) {  
            bt_send_data( shortest_d );  
        } else {  
            if ( no_bt_request_for_longer_than_60s() ) {  
                power_off();  
            }  
        }  
    }  
}
```

SENSOR MODULE SOFTWARE - 2

PSEUDOCODE CONTINUE

```
float calculate_shortest_distance(uint32 *sensors_array) {  
  
    float shortest_distance, temp_f;  
  
    shortest_distance = (float)*(sensors_array)*0.6820;  
    for ( int i=0, i<5; i++) {  
        if (i==1 || i==3) {  
            temp_f = (float)*(sensors_array+i)*0.9272;  
            if (temp_f < shortest_distance) { shortest_distance = temp_f;}  
        }  
        else if ( i==2 ) {  
            temp_f = (float)*(sensors_array+i);  
            if (temp_f < shortest_distance) { shortest_distance = temp_f;}  
        }  
        else if ( i==5 ) {  
            temp_f = (float)*(sensors_array+i)*0.6820;  
            if (temp_f < shortest_distance) { shortest_distance = temp_f;}  
        }  
    }  
  
    return shortest_distance;  
}
```



IMPLEMENTATION

- DESIGN AND TESTING OF COMPONENTS
- INTEGRATION OF COMPONENTS ONTO BREADBOARD
- CONSTRUCTION OF PROOF-OF-CONCEPT PROTOTYPE
- INSTALLATION OF THE PROTOTYPE ONTO A CAR



TESTING

- TESTED DIFFERENT SCENARIOS (FRONT IN, BACK INTO THE PARKING SPOT AND PARALLEL PARKING, PEDESTRIAN WALKING AROUND THE CAR, SUDDENLY JUMPING INTO THE SENSOR RANGE, WITHIN A DISTANCE OF 15M, THE DISPLAY MODULE CAN STILL TURN ON THE SENSOR MODULE)
- EASY TO INSTALL FEATURE WORKED GREAT
- ACCURATE MEASUREMENTS
- STABILITY



DESIGN ISSUES

- Audio Alarm beeps only for back sensor
- Location of the Sensors need to be changed for the purpose of making the device compatible on variety of cars
- Reduce the System start up time of Bluetooth communication
- Use Color LED for different distances
- Dead spots
- Spiking
- No Power button
- 9V battery

DESIGN ISSUES

- Display module should display 50cm when object comes closer than 50cm and there should be constant beep
- Antenna for transmitter and receiver circuit
- Sensor module should not display anything for distances greater than 200 cm.



FUTURE WORK

Bluetooth Communication

Range Detection

Range display Unit

Remote on/off switching Unit

Module Casing

Sensor Module Battery Life

PCB design for Display module

PCB design for Sensor

Complete test plan for prototype and final product

Better test method for object detection

Patenting Sensor/Display Module Design

Planning For Mass Production

Cost Analysis of Prototype

Market Research

Sustainability Consideration



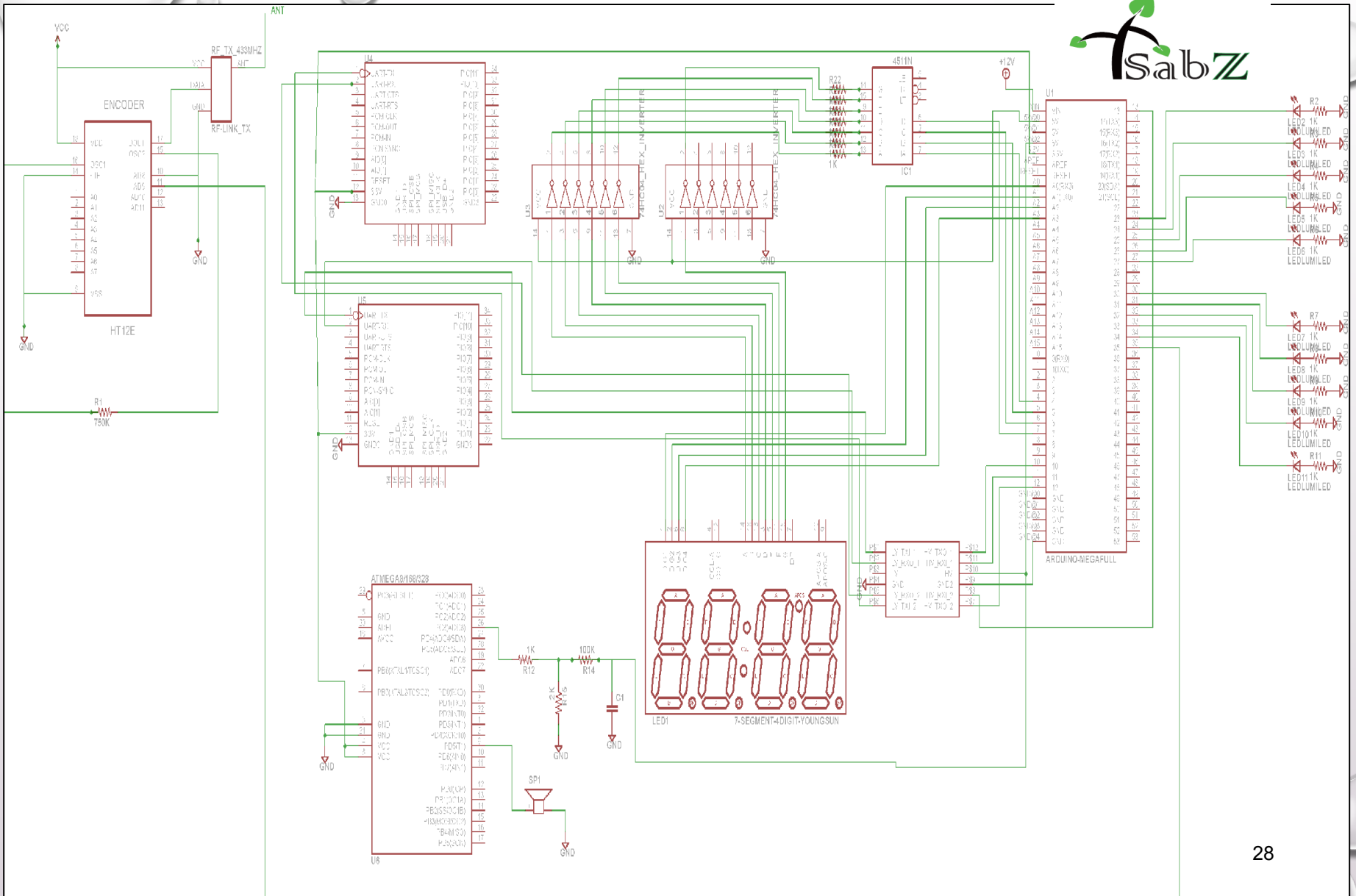
SUB-DIVISIONS

- DIVIDED INTO 4 PARTS AND EACH MEMBER IS RESPONSIBLE FOR THEIR PART
- KENNY – BLUETOOTH COMMUNICATION PROTOCOL
- EDMOND – ULTRASONIC DISTANCE DETECTION CIRCUITRY
- HAMID – DISPLAY AND AUDIBLE ALARM
- WILL – REMOTE ON/OFF CIRCUITRY



HAMID

- DOCUMENTATION
- RESPONSIBLE FOR DESIGN AND INTEGRATION OF ALL COMPONENTS IN DISPLAY MODULE





HAMID

- IMPLEMENT THE DESIGN INTO SOLDERABLE BREAD BOARD AFTER ALL THE TESTING WERE DONE ON BREAD BOARD.
- GROUP MEETINGS 3 TIMES A WEEK FOR 2 HOURS EACH(PROJECT WORKLOAD).
- 10 HOURS A WEEK FIRST 2 MONTHS
- 24 HOURS A WEEK LAST 1 MONTHS
- TWO OTHER COURSES
- READING THE MANUALS(IMPROVE PRODUCTIVITY)
- TIME MANAGEMENT
- ARDUINO WEBSITE
- ENSC 225,325,351,427,CMPT128



KENNY

RESPONSIBILITIES AND DUTIES

- DOCUMENTATION
- BLUETOOTH COMMUNICATION
- DISPLAY AND SENSOR MODULE CASING
- PROJECT MANAGEMENT
- DESIGN CONSULTATION AND TROUBLESHOOTING



KENNY

PROJECT WORKLOAD

- AVERAGE 10 HOURS PER WEEK FOR THE FIRST TWO MONTHS
- AVERAGE 25 HOURS PER WEEK IN THE LAST MONTH

FACTORS THAT INFLUENCED THE WORK LOAD

WAYS TO IMPROVE MY PRODUCTIVITY

USEFUL COURSES:

CMPT 128 + 225, ENSC 325, ENSC 489

COMMUNICATION AND WRITING COURSES



EDMOND - 1

RESPONSIBILITIES AND DUTIES

- DOCUMENTATION
- HARDWARE&SOFTWARE INTERFACE OF ULTRASOUND SENSOR
- PCB FOR SENSOR MODULE
- OSCILLATOR CIRCUITRY IN SENSOR MODULE

EDMOND - 2

PROJECT WORKLOAD

- AVERAGE ~15 HOURS/WEEK

FACTOR INFLUENCE WORKLOAD

- MAJORITY TIME SPENT IN RESEARCHING ON TOPIC

WAYS TO IMPROVE MY PRODUCTIVITY

- TAKE A BREAK ONCE IN AWHILE TO REVITALIZE

USEFUL COURSES

- CMPT128, ENSC452, ENSC350, ENSC450



WILL

RESPONSIBILITIES AND DUTIES

- DOCUMENTATION, MEETING MINUTES
- REMOTE ON/OFF CIRCUITRY

HOW TO IMPROVE YOUR PRODUCTIVITY

- SCHEDULE AHEAD
- DO MORE RESEARCH
- TEST MORE

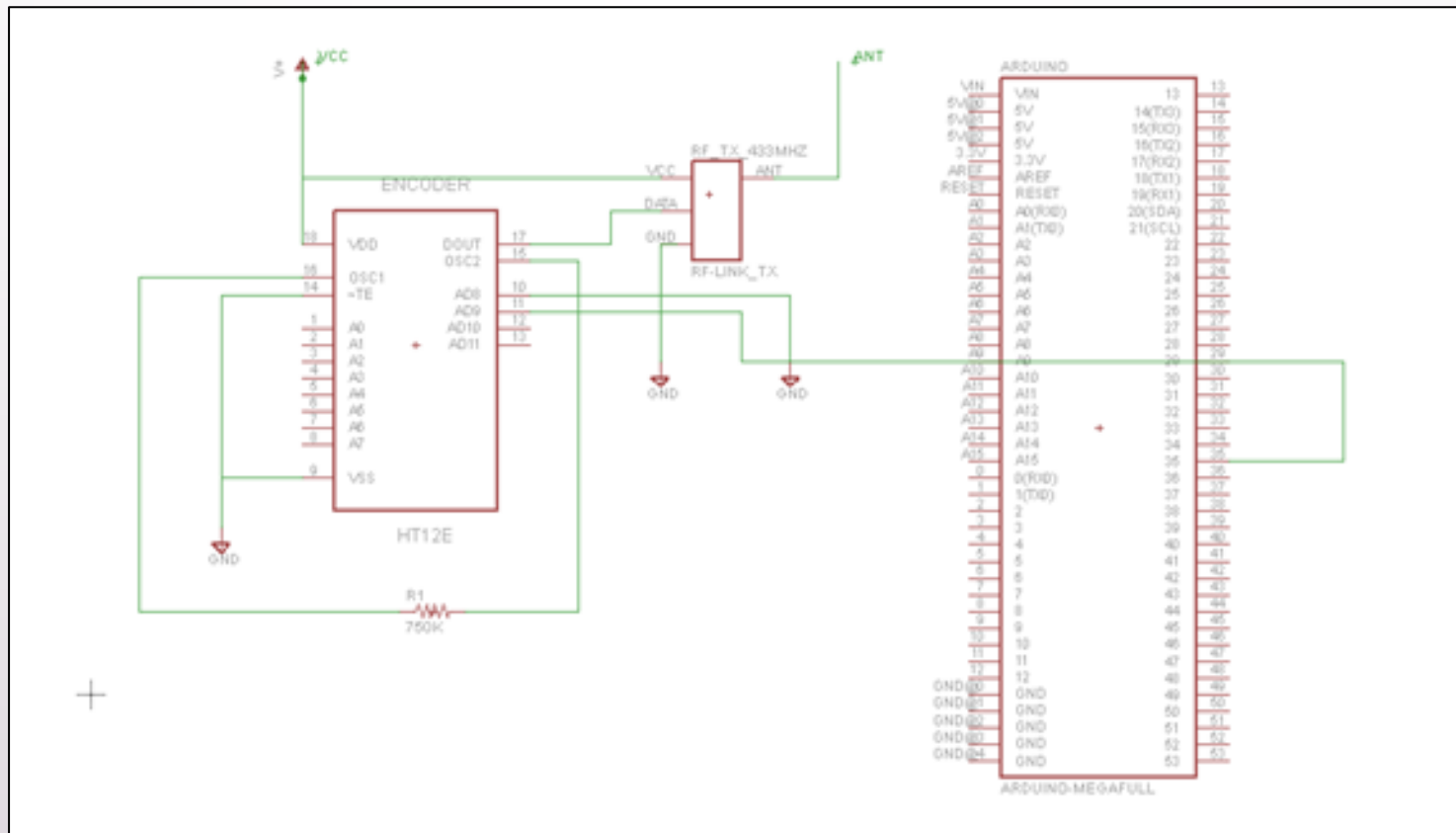


RESPONSIBILITIES

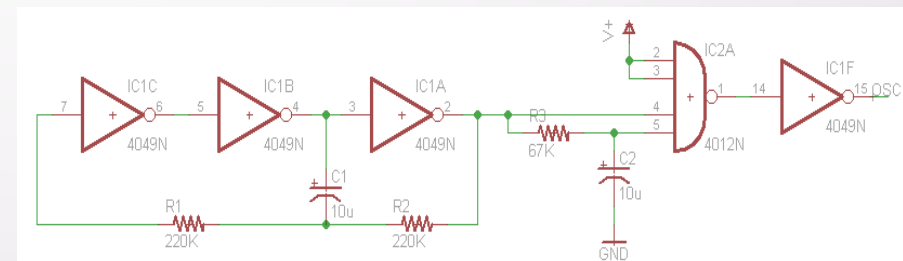
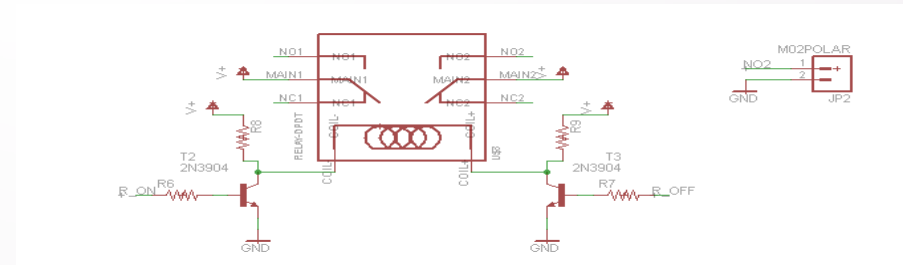
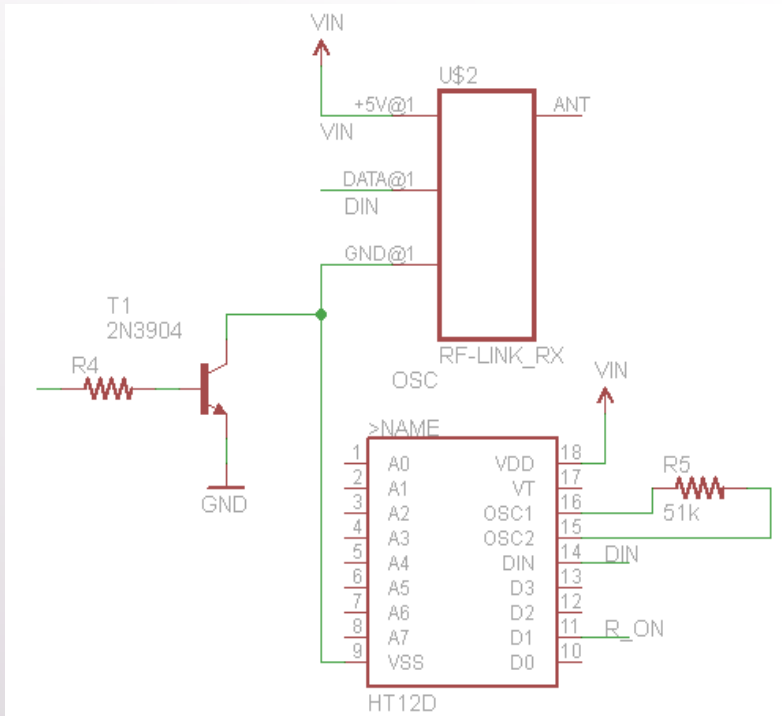
WORK LOAD

- 8-10 HOURS PER WEEK IN FIRST TWO MONTHS
- 20-30 HOURS PER WEEK IN LAST MONTH
- LAST TERM
- ENSC 220, 225,325

TRANSMITTER NETWORK



RECEIVER NETWORK





DEMO

- VIDEO OF CAR PARKING
- PARKING TRIAL AT CAR



ACKNOWLEDGEMENT AND REFERENCE

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[HTTP://ARDUINO.CC/EN/MAIN/ARDUINOBOARDMEGA](http://arduino.cc/en/Main/ArduinoBoardMega)



QUESTIONS?