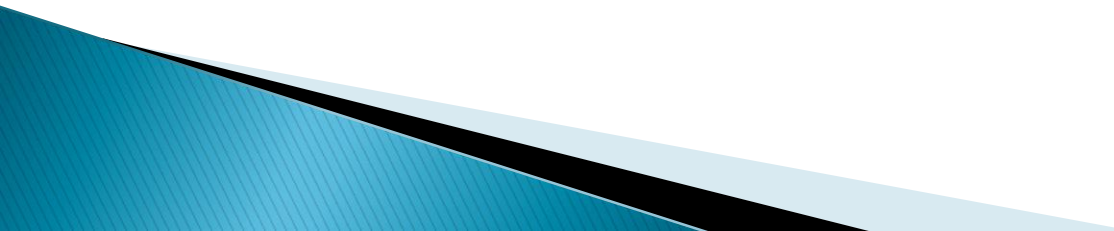




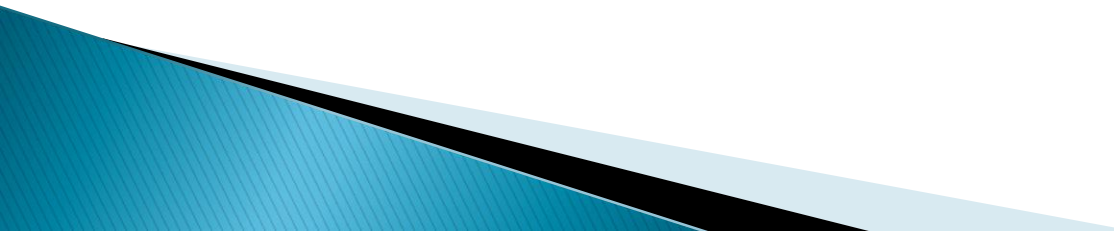
Urban Wheel Blind Spot Detection System

CEO Howard Sun
CFO David LiLi Cao
CTO Emmanuel Yeung
COO David Zhong

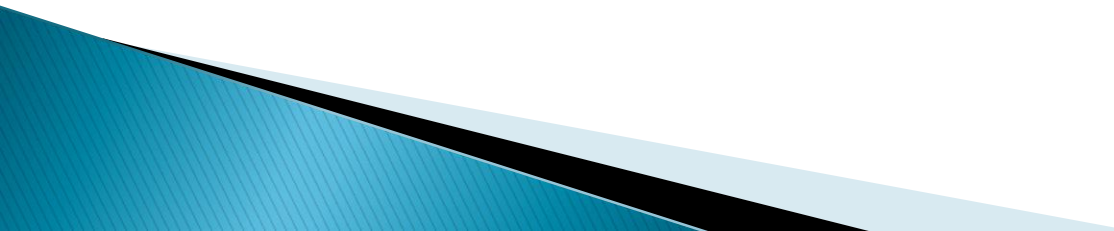
Presentation Outline

- ▶ Team Introduction
 - ▶ Project Objective
 - ▶ Product Design
 - ▶ High-Level Project Details
 - ▶ Future Work
 - ▶ Conclusion
- 

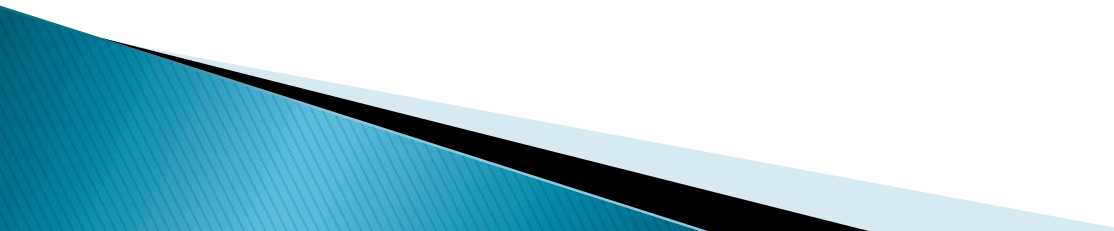
Team Introduction

- ▶ Howard Sun
 - Software, Warning system and User interface
 - ▶ Emmanuel Yeung
 - Software, Sensor system and Board communication
 - ▶ David Zhong
 - Advisory, documentation and SolidWorks design
 - ▶ David Cao
 - Case design, mounting and Circuit analysis
- 

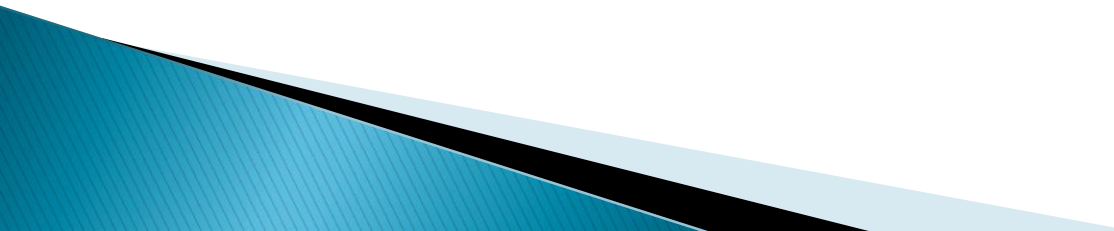
Project Objective

- ▶ Motivation
 - ▶ Current Solution
 - ▶ Goals
 - ▶ Our Solution
- 

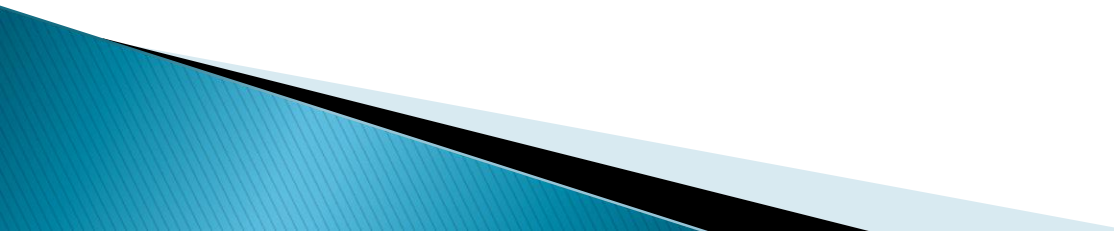
Motivation

- ▶ Blind spot related accident
 - 840,000 collisions / year
 - 300 fatalities / year
 - ▶ High demand
 - ▶ Enjoying multi-functioning system ourselves
- 

Current Solution

- ▶ Manufacture options expensive
 - More than \$2000
 - ▶ Not available to cheap or existing cars
 - ▶ System functionality is limited
- 

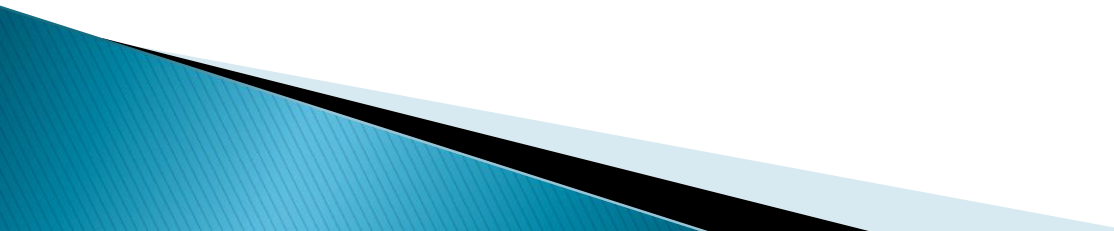
Goals

- ▶ Universal system
 - Cut down manufacturing cost
 - Easy to modify and integrate
 - ▶ Low cost
 - Low cost and multi-functioning
 - Benefit non-luxury vehicle owners
 - ▶ Easy to install system
- 

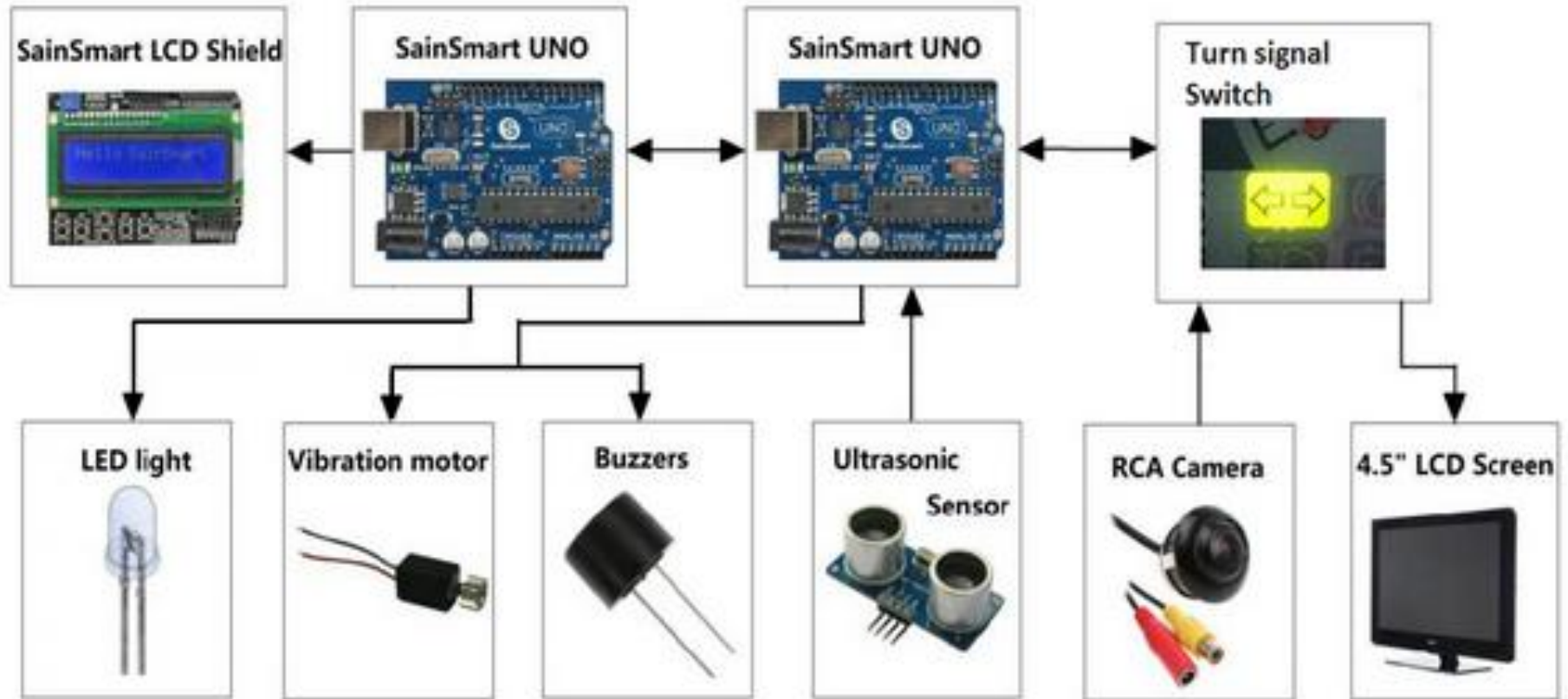
Our Solution



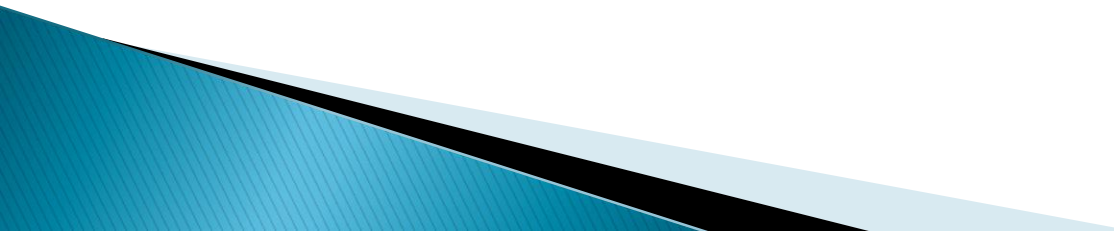
Product Design

- ▶ Overview
 - ▶ System Logic
 - ▶ Software
 - ▶ Electronics
 - ▶ Mounting
 - ▶ Safety
 - ▶ Usability
 - ▶ Sustainability
- 

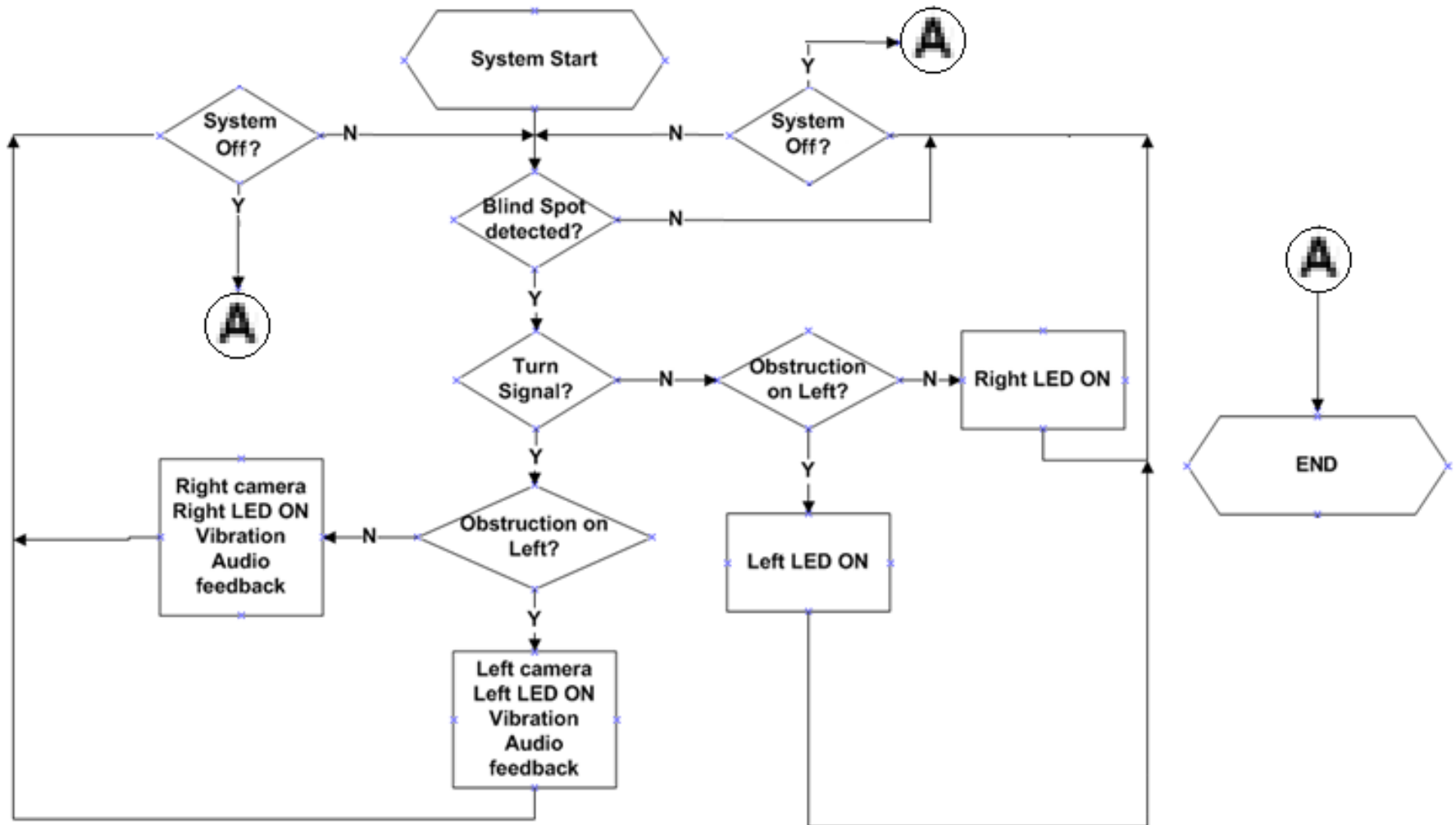
System Overview



Electronics

- ▶ Choosing Arduino over Raspberry Pi
 - ▶ Ultrasonic sensor over Radar and Infrared
 - ▶ Miscellaneous
- 

System Logic



Software

- ▶ **Arduino programming language**
 - Easy to program (C Style)
 - Reprogrammable
- ▶ **Controlling all of the functions**
 - Ultrasonic sensor library
 - Board communication

Mounting

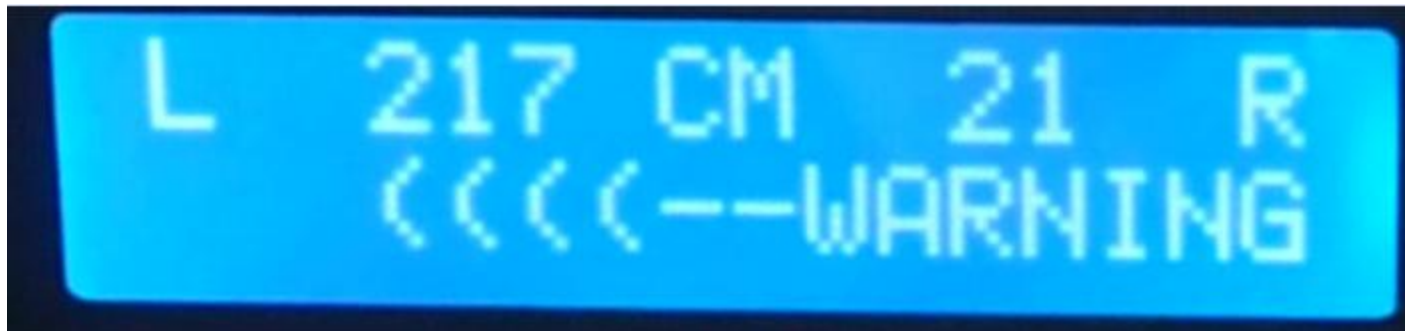


Safety

- ▶ Fuse protection
- ▶ Can be easily unplugged from power source

Usability

- ▶ Warning system easily understood
- ▶ Different language settings
- ▶ Both Imperial and Metric system



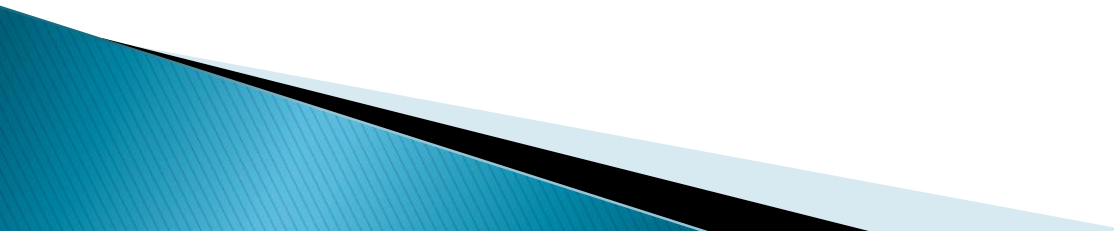
Sustainability

- ▶ C2C – Reduce, reuse, recycle
- ▶ reduce e-waste (when possible)

Video



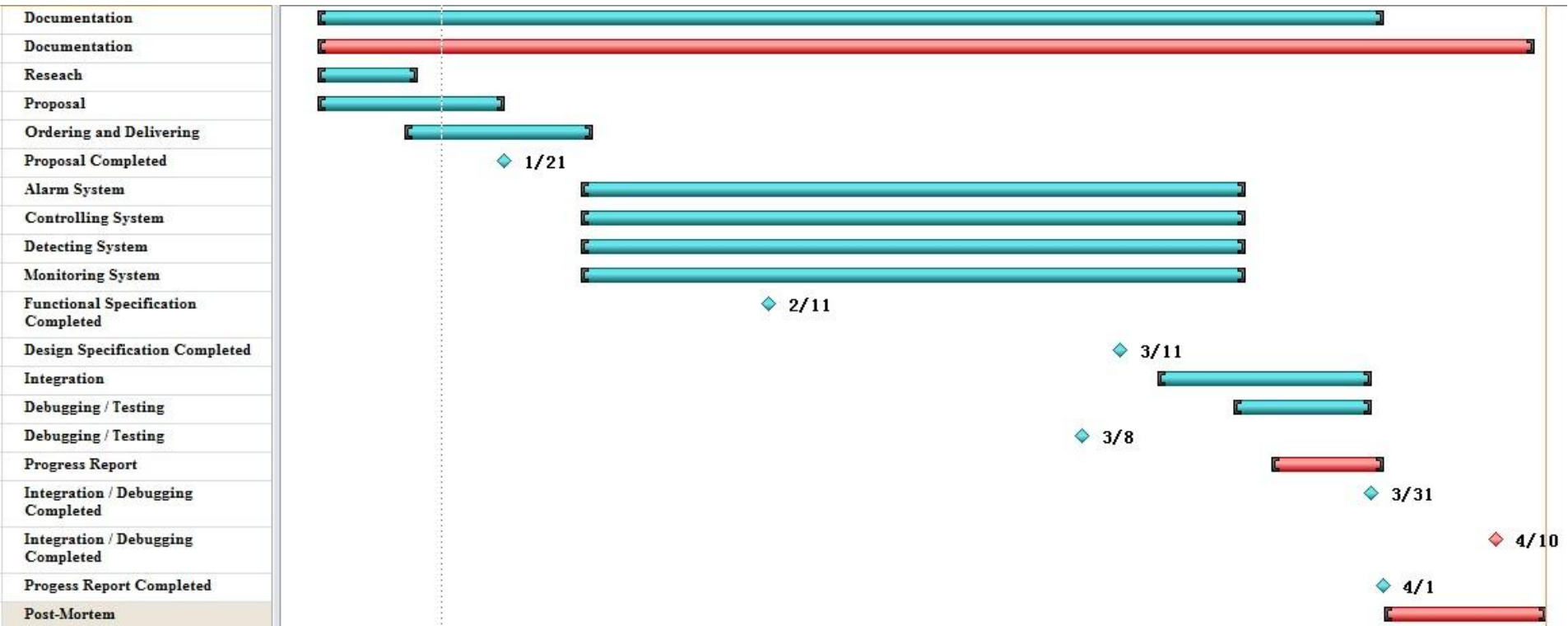
High Level Project Details

- ▶ Costs
 - ▶ Time Management
 - ▶ Lessons Learned
 - ▶ Future work
- 

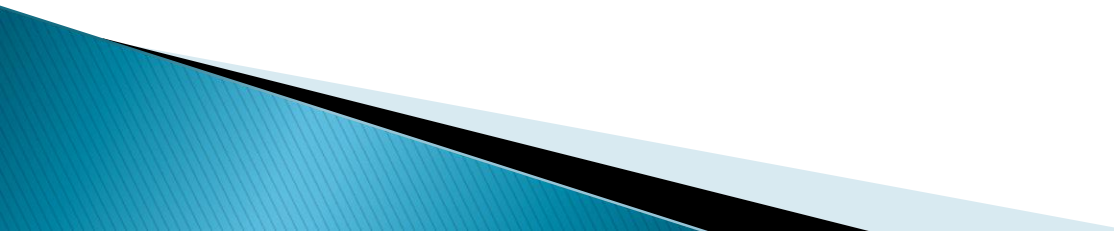
Cost

	Estimate Cost (\$)	Actual Cost (\$)
Electronic Parts		
SainSmart UNO + LCD package	60	75
OSEPP™ UNO R3 Plus	25	33
Ultrasonic Sensors x6	60	20
Night Vision Camera x3	90	45
Monitor	45	30
Raspberry Pi	55	N/A
Mechanical Parts		
Foam	1	15
Plastic board	2	10
Miscellaneous Parts		
Wire	Free	10
Charger	10	10
Grand total	293	248

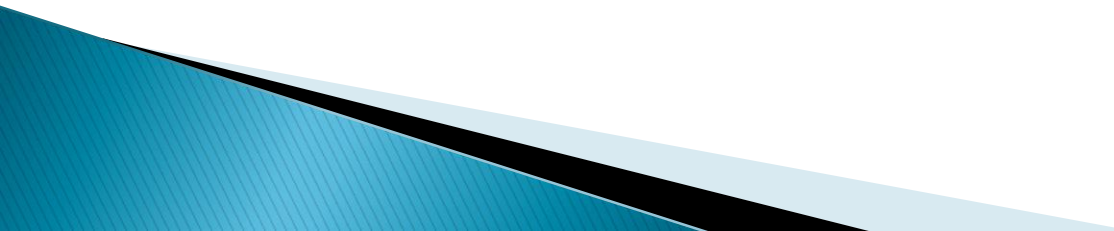
Time Management



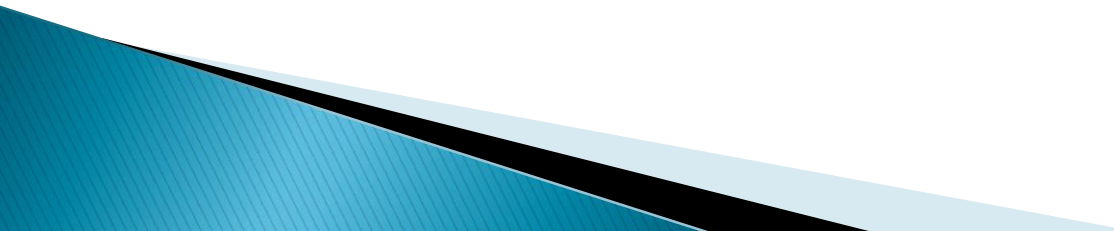
Lessons Learned

- ▶ Time management
 - ▶ Parts choice are essential
 - ▶ Team communication are essential
 - ▶ Never park at loading zone for more than 30 minutes ;)
- 

Future Work

- ▶ Integrate the circuit into a single PCB (for compact design)
 - ▶ Combine LCD and Monitor (enhance user interface)
 - ▶ Use better quality material for casing
 - ▶ Sensor upgrade
 - ▶ Flexible wires
- 

Acknowledgement

- ▶ Andrew for “A perfectly done easy project is no better than an unfinished project that is worth doing.”
 - ▶ ESSEF for project funding
 - ▶ Fred Heep for electronic components
 - ▶ Special thanks to John Jones, Steven Whitmore and all the TAs who attended our presentations and inspired us with their questions and ideas.
- 

Questions ?

Thank you for your listening

“All I want for Christmas is a blind spot monitor” – the internet

Misc

