

Test Plan for SkySeed

Panalloon Systems

Prepared for

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SkySeed Test Plan

SkySeed Test plan (Proof-of Concept) Revision 1.1	
Tester's Name:	
Test Date:	
Test Case Results	Comments
A. Aerial System Testing	
A.1. No entanglement of tether and netting	
□Pass □Fail	
A.2. Reel-able tether stays intact with SkySeed	
□Pass □Fail	
A.3. Successfully lift 1.1 kg to 20 m	
□Pass □Fail	
A.4. Netting lays fitted on balloon while securing	
payload:	
□ Pass □ Fail	
B. Modularity B.1. Camera mount must be easily disassembled	
when required:	
□Pass □Fail	
B.2. Camera mount must be securely fastened to	
enclosure during operation:	
□Pass □Fail	
B.3. Enclosure can be easily disconnected from	
netting:	
□Pass □Fail	
C. Power Testing	
C.1. Battery current output does not exceed 1.1 A:	
□Pass □Fail	
C.2. Power wire stays intact:	
□Pass □Fail	
C.3. LED is On to express power delivery to system: □Pass □Fail	
C.4. Battery lasts up to 3.5 hours:	
Pass Pail	
C.5. Motor must not exceed 1 A of current drawn at	
full stall:	
□Pass □Fail	
D. Wireless Signal Strength	
D.1. Consistent network communication:	
□Pass □Fail	
D.2. Network stable within 15 m from client to server:	
□Pass □Fail	



D.3. Wireless speed of 100 Mbps within 15 m for	
video stream:	
□Pass □Fail	
D.4. Video stream with 1 sec delay:	
□Pass □Fail	
E. Software Testing	
E.1. Program remains responsive:	
□Pass □Fail	
E.2. Appropriate status messages:	
□Pass □Fail	
E.3. User able to rotate video capture:	
□Pass □Fail	
E.4. "Connection time out" status shown in video box:	
□Pass □Fail	
E.5. Video file saved in default location:	
□Pass □Fail	
E.6. Recorded video file can be opened and viewed:	
□Pass □Fail	
E.7. Video record terminated at 10 min time stamp:	
□Pass □Fail	
E.8. User notified when recording terminates:	
□Pass □Fail	
E.9. Video saved when user exits program while	
recording:	
□Pass □Fail	
E.10. Status updated upon disconnection:	
□Pass □Fail	
E.11. Direction of motion as expected:	
□Pass □Fail	
E.12. Camera is idle when arrow key not pressed:	
□Pass □Fail	
E.13. User speed selection corresponds with motor	
speed:	
□Pass □Fail	
E.15. Real-time motion response:	
□Pass □Fail	