



Test Plan of the blind spot monitoring and parking-assisting device **Safe Direction™**

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## *Test Plan*

### *1 Individual Testing*

#### *1.1 Ultrasonic sensor*

The ultrasonic sensor will be tested on the given specifications for the accuracy in sensing range and width with respect to object size and distance based on the calculated values [R52\_II] [R53\_II]. Testing on the ultrasonic sensor will include but not limited to:

- I. Accuracy of the sensing range and width
- II. Interference between sensors
- III. Signal delay for multiple sensors
- IV. Testing sensors for false detection
- V. Measuring the maximum accurate sensing distance on different obstacle size

#### *1.2 Battery*

After combine all the individual modules together, the system will be tested on the power consumption while using battery as the supply. Testing on the power consumption will include but not limited to:

- I. The maximum continuous operation time duration
- II. The best trade between duration and battery size
- III. The consumption level while in sleep mode

#### *1.3 Wireless module - Transmitter and receiver:*

The wireless modules will be tested under the given specification and the accuracy and limitation of the signal distance, interference level, and accuracy of transmitted signal. Testing on the wireless module will include but not limited to:



- I. Accuracy of the signal transferred
- II. Interference with other products near by
- III. The accuracy of the signal transfer under different weather conditions

### ***1.4 Buzzer***

The buzzer evaluation will be based on the strength of the notification and adjusting it to the most comfortable level for the user **[R68\_III]**. Testing on the buzzer will include but not limited to:

- I. Frequency of the buzzer sound
- II. Accuracy of the buzzer

### ***1.5 LEDs***

The LED lights will be tested on the functionality and the warning notifications provided **[R66\_II]** **[R67\_III]**.

## ***2 Arduino UNO+ Transmitter and receiver***

The Arduino board and transmitter/ receiver will be used to test the wireless communication for the system. Considering the RF transmitter and receiver is the cheapest wireless communication method out there, the liability of the product needs to be extensively tested in the following areas:

- I. Accuracy of the signal transferred
- II. The signal transferred interval
- III. The delay between signals send

## ***3 Arduino UNO+ Buzzer***

The Arduino and buzzer will test with variations of buzzer response time wirelessly and the level of notification that it provides.



#### ***4 Arduino UNO+ Ultrasound sensor***

The Arduino board and ultrasonic sensor tests the programmable limitation of the sensor and code. It will be tested under conditions to ensure that the microcontroller will be able to handle multiple sensor data and analysis it in a timely manner. The testing will include:

- I. Ensure all data transferred for multiple sensors are accurate
- II. Test the interference between multiple sensor and microcontroller

#### ***5 Power consumption testing***

Test and evaluate the power consumption of the system, evaluating the battery power usage and the accuracy of the signal under different power levels left in the battery. The test will include:

- I. Buzzer noise level in lower battery condition
- II. Single transfer accuracy in lower battery condition
- III. Warning system for low battery

#### ***6 User interface Testing***

- I. Recognizable warning system
- II. Comfortable level of notification

#### ***7 Unit Testing***

Combining all individual parts and testing on real environments:

- I. Ease of installation
- II. Accuracy of the sensor
- III. The possible interference
- IV. Wireless delay between microcontrollers
- V. Waterproof level