

# TEAM OBELXTECH



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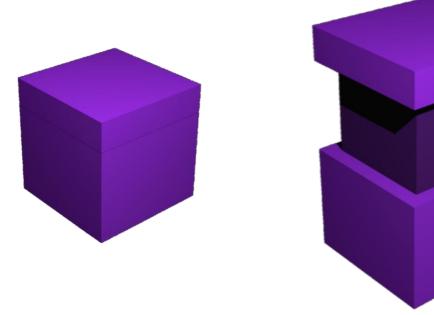
# Outline

- Overview
- Motivation and Market
- System Overview
- Scheduling
- Finances
- Project Summary
- Future Goals
- Challenges and Change in Scope
- Lessons Learned

#### LumenX<sup>3</sup> Overview

The next addition to everyone's smart device portfolio

- Screen-less Projection
- Touch Gesture Recognition
- Windows 8.1
- Portability and Durability



#### Motivation

#### Disadvantages of current smart devices

- Screens fragile and easily crack
- Requires physical touch







#### Motivation

Disadvantages of current smart devices

- Does not completely replace mouse
- Cannot be both portable and collaborative

#### Can we find a better way to interact with our devices?

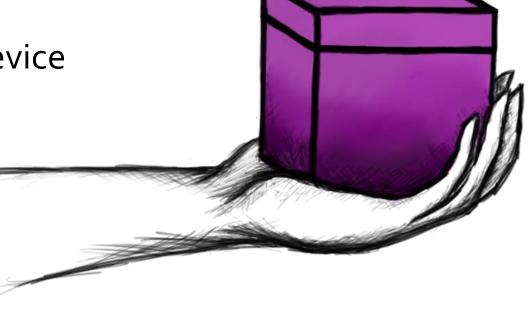


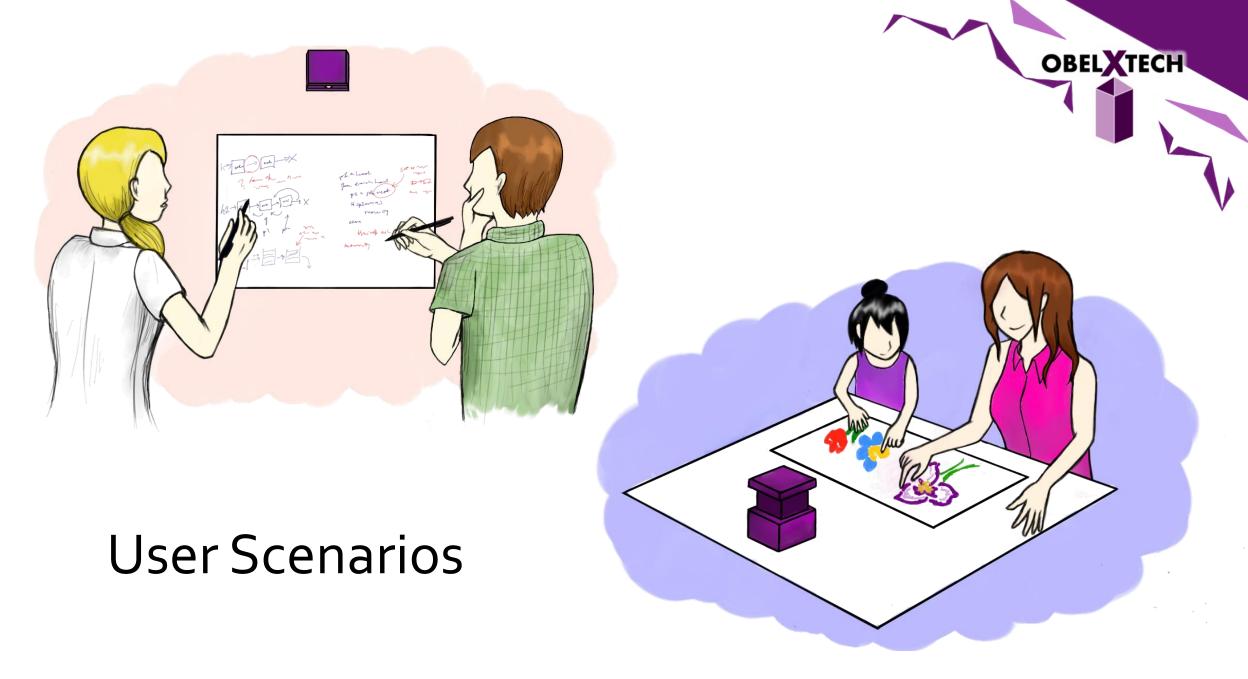




#### LumenX<sup>3</sup> as the new Smart Device

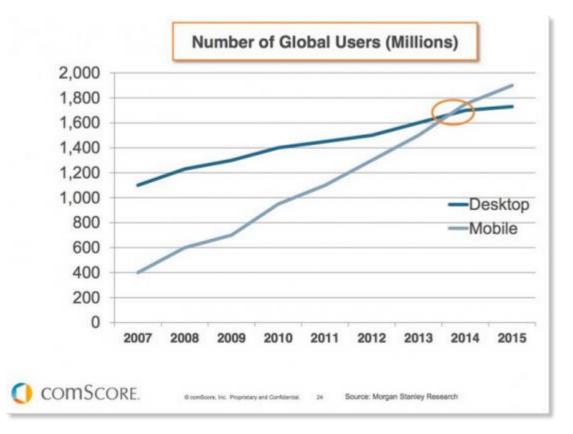
- Entire 3D space under your control
- Removes screen size limitations and fragility
- Collaboration on a portable device





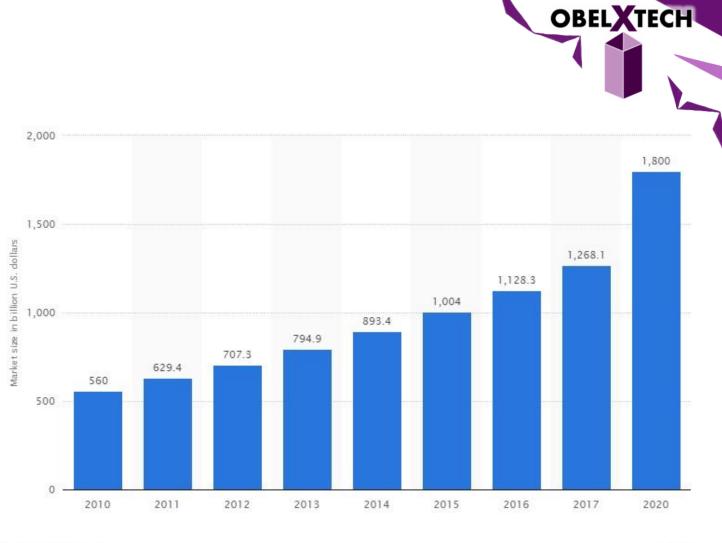
#### Market Research

- 2014 was an extremely important shift in dominant platform
- Mobile devices are the preferred method for people to purchase, and consume content
- We spend more time on our mobile devices than the TV
- 80% projected growth in global market for connected devices by 2020



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Additional Information Sign Up for Free Basic Account Source: Sign Up for Free Basic Account © Statista 2015

#### Target Market

- Groups and Individuals that embrace new technology
- Consumers who work/play in environments where touch screens don't work
- Those who value multi-user collaboration on a single device



#### Competition





Promethean ActivTable	Apple iPad	Dos-Owls ODIN
\$6799 USD	\$500 - \$800 USD + Accessories	\$675 USD
<ul><li>Great for collaboration</li><li>Great Content consumption</li><li>Touch Input</li></ul>	<ul><li>Very portable</li><li>Good content consumption</li></ul>	<ul><li>Very portable</li><li>Good content consumption</li></ul>
Not portable Expensive	Tablets have fragile screens Physical collaboration is HARD	Requires keyboard and mouse

# **Cost and Financing**

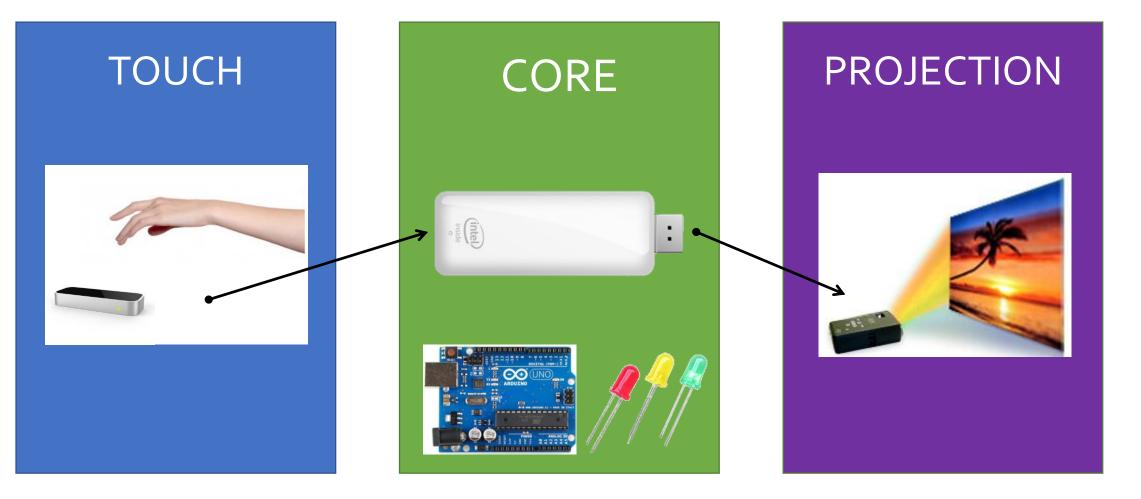
- Target price for production model \$800 \$1100
- Cost of production model reduced significantly
  - Decrease in cost of parts
  - Production efficiencies
  - Economies of scale
- Plans for VC funding (Y-Combinator)
- Consider Crowd Funding (Kickstarter, Indiegogo)

# Y Combinator

# KICKSTARTER

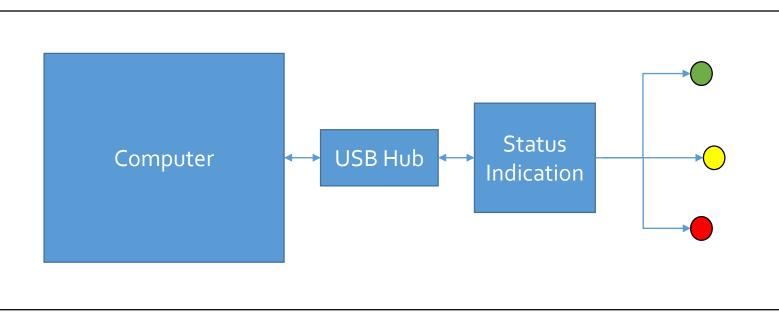


#### System Overview



# Core Subsystem

- Miniature computer that runs powerful desktop touch-friendly computer OS, Windows 8.1
- Combination of Windows Service and Microcontroller for status indication



# Core Subsystem

- MeegoPadTo1
  - Intel Atom Processor x86 Instruction Set to run Windows
  - 2GB Ram/Quad Core to run our software algorithms
- Arduino Uno R3
  - Communicates with MeegoPad through serial interface
  - LED status according to IEEE
  - Automatic rising/falling of LumenX<sup>3</sup> using servo motors not yet implemented

# **Projection Subsystem**

- AAXA P3 Pico Projector
  - Selected for its small size, bright and high resolution
- Windows 8.1 Display Driver
  - Performs perspective correction







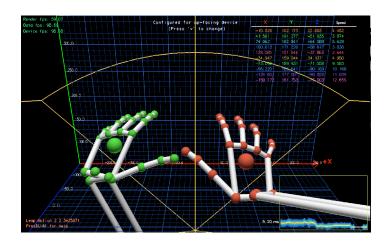
# **Touch Gesture Recognition Subsystem**

What is the Leap Motion Controller?

What is the Touch Software?

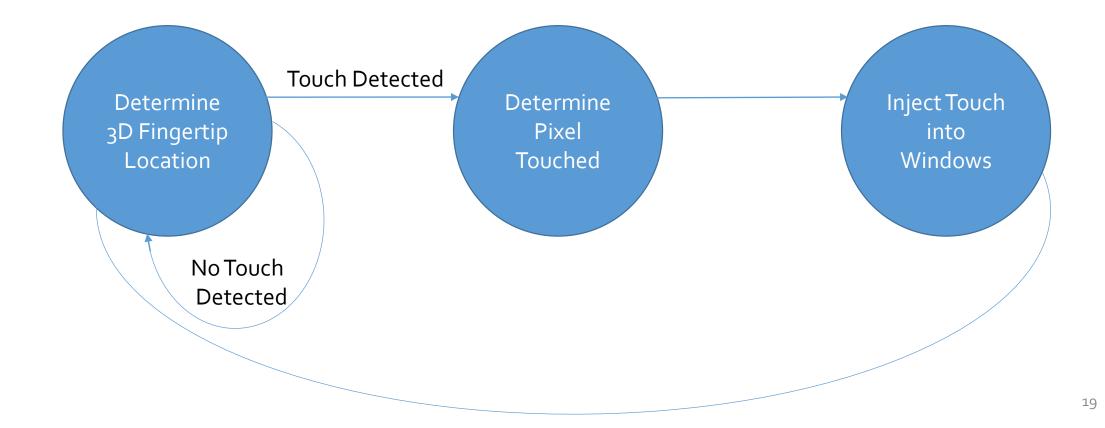
- Touch Software runs on 2 major algorithms:
  - 1. Touch Determination
  - 2. 2D Location Translation
- Both Algorithms utilize the Leap Motion SDK





#### **Touch Gesture Recognition Subsystem**

How does the Touch Software work?



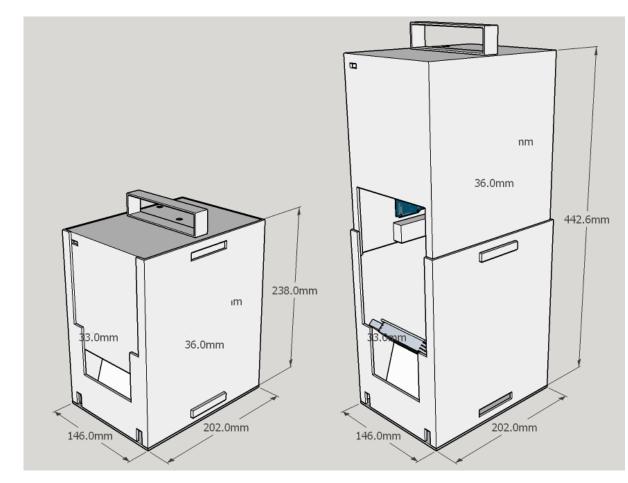
# **Mechanical Case**

- Robust and aesthetically pleasing
- Portable
- Height and placement requirements
  - Pico Projector: 29 cm @ 60°
  - Leap Motion Controller: 10 cm @ 45°
- Openings for Pico Projector and Leap Motion



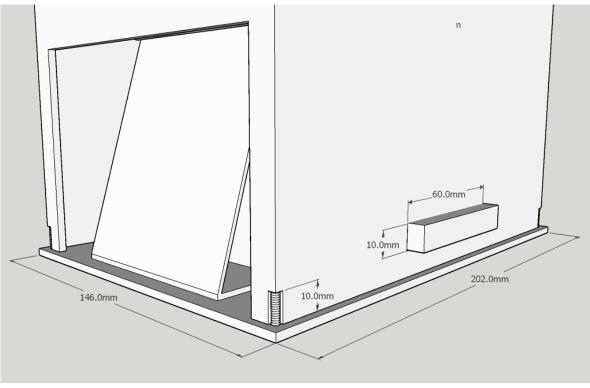
# Two-shell Design

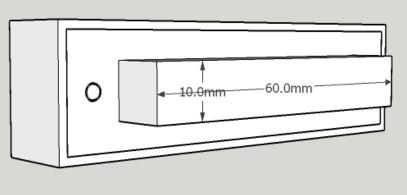
• Use case itself as rising mechanism

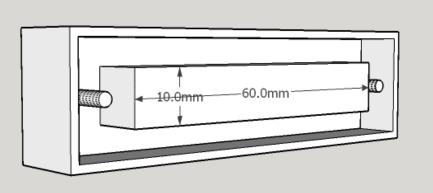


# Locking Mechanism

 Self-locking buttons on top and bottom (add pic of other part of button)

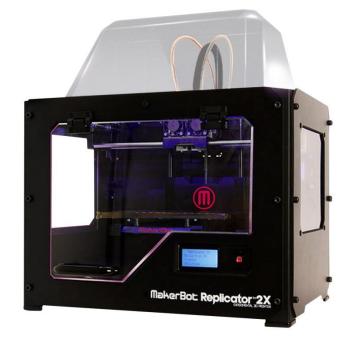






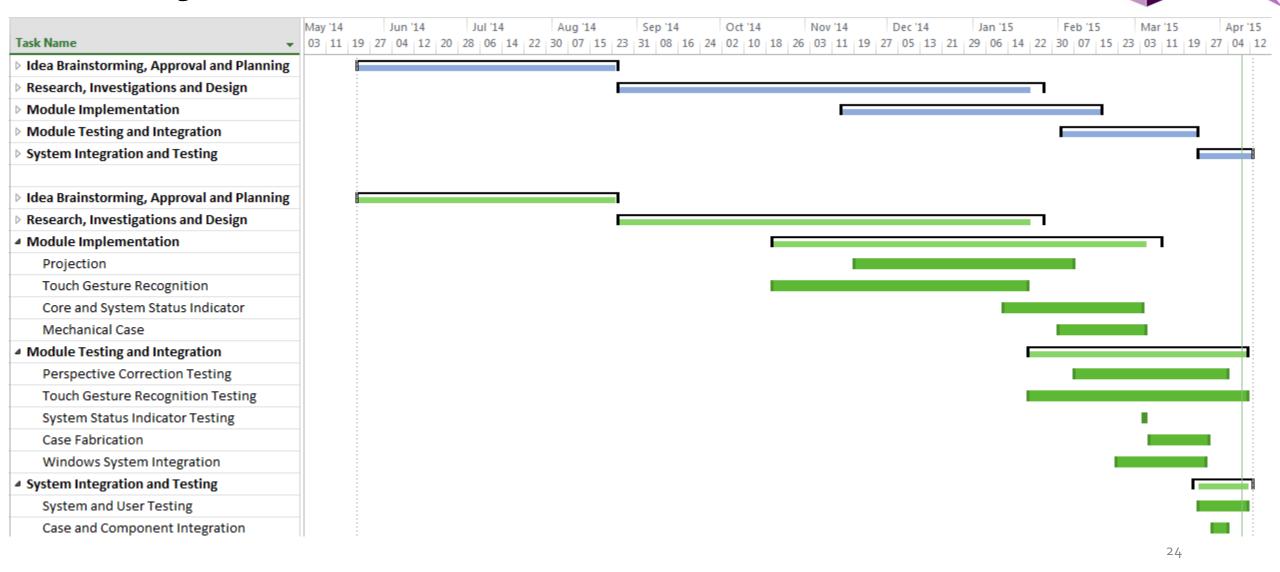
# Manufacturing

- 3D printed small parts
- Too expensive for larger shells
- Acrylic sheets traced with laser cutter
- Meld panels together





#### Project Schedule



# Finances – Proof-of-Concept Model

ltem	Estimated	Actual	Difference
Microsoft Windows 8.1	\$119.99	\$0.00	+\$119.99
AAXA P3 Pico Projector	\$184.91	\$184.91	\$0.00
MeegoPad To1	\$138.03	\$138.03	\$0.00
Leap Motion Controller	\$89.59	\$79.68	+\$9.91
Arduino Uno	\$30.00	\$35.00	-\$5.00
Minor Electronics and other Accessories	\$55.60	\$72.82	-\$17.22
Plastic Enclosure	\$30.00	\$41.43	-\$11.43
Contingency (15%)	\$100.00	\$131.43	-\$31.43
Total Cost	\$748.12	\$683.30	+64.82
ESSEF Funding		\$705.00	
IEEE Funding		\$622.85	
Total Funding		\$1327.85	
Net Cash		\$644.55	

# **Project Summary**

- Fully integrated and packaged device
- Working driver and projection
- Single tap and drag detection in hand tracking
- Compressed and Expanded mode



#### Future Development

- Wide angle projection via lens and filters
- Fully custom circuit
- Integrated battery
- Unibody casing
- Improved hand tracking via point cloud
- More computational resources
- Super compact form factor



# Challenges Faced Along the Way

- Perspective Correction using OpenCV
- Compatibility between MeegoPad and Projector hardware
- LeapMotion not meant to be used with current orientation
- 3D printing the case
- Connecting everything and fitting in the case was difficult

# Changes in Scope

- Stereo vision with IR emitter and receiver
- Android OS for touch friendly
- Jetson TK1 for more powerful computational hardware
- Raspberry Pi for for data routing and resource distributing between Jetson and other hardware

#### Practical Lessons Learned

- Development may take longer than expected
- Sometimes things do fall in place
- Should have been constantly looking for alternatives and researching other things in the early investigation stages
- Going out and de-stressing with each other often helps bonds

# Technical Knowledge Acquired

How to:

- Write a Windows display driver
- Use the Leap Motion SDK
- Touch Inject actions into Windows
- Write a Windows service
- Make a physical case
- Work around hardware limitations

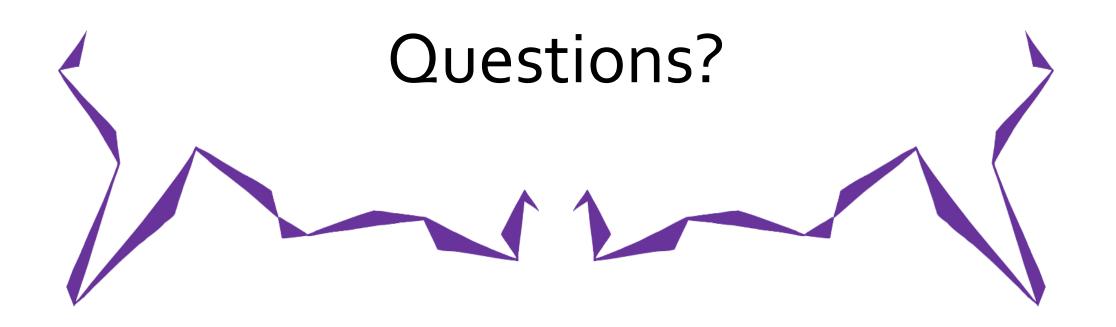
# Acknowledgements

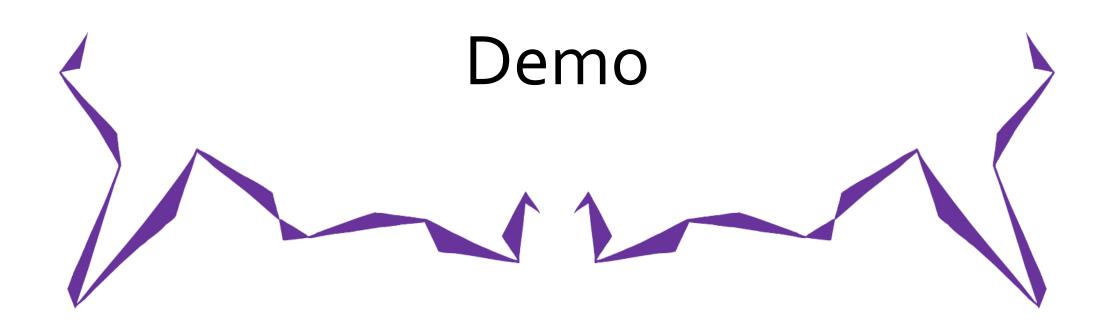
- Andrew Rawicz and Steve Whitmore
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- Lakshman One, Dr. Michael Hayden, Dr. Ash Parameswaran, Sergiy Baidachniy, Kenneth Koothrappali

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#### Videos

• Touch Demonstration:

https://www.dropbox.com/s/afj3zi861gpmg51/Hand%20Gestures.mp4 ?dl=o