



BABY ROCK – SMART BABY CRADLE

GROUP 20

### MEET THE TEAM

- Fanchao Meng (Randy) Chief Executive Officer
- Xiaoye Lu (Eric) Chief Technology Officer
- Yu Liu (Nick) Chief Financial Officer
- Kiru Sri Chief Information Officer

## BACKGROUND & PURPOSE



### Rocking

- A stepper Motor rotates back and forth
- We used two gears to amplify torque
- Controlled by microcontroller
  - Arduino Mega



### Monitoring

- We used an ArduCam
- Allows for real time video monitoring
  - We couldn't decode video



### Cry Recognition

- A Microphone Shield was used to assist the microcontroller
- Sound Database
- Sound is received by Microphone
- Voice Recognition Software





### Comforting

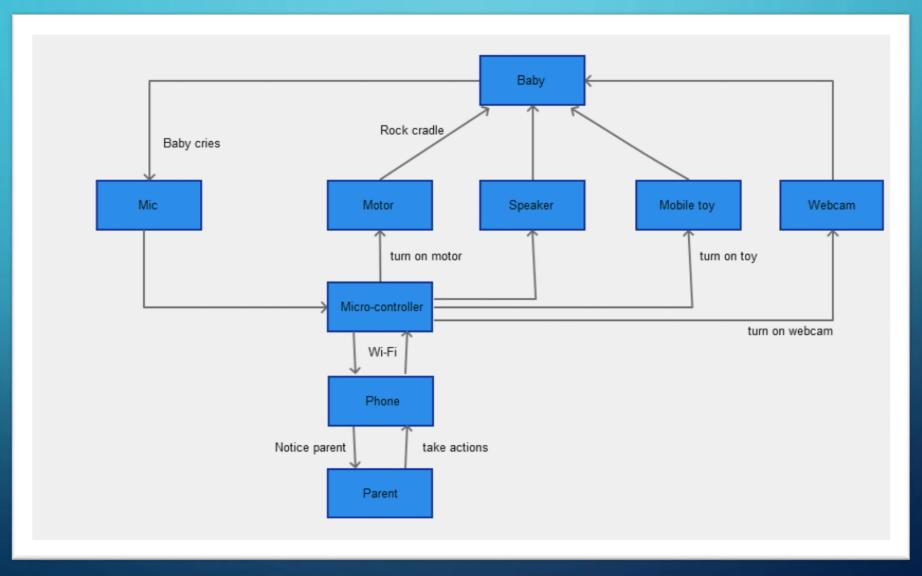
- Uses Microphone shield to play Audio
- Audio is controlled by Android App



### **Android Application**

- It allows parents to control the previous functions
- Receives Notification when the baby is Crying
- Connects to the Microcontroller through a Wi-Fi network

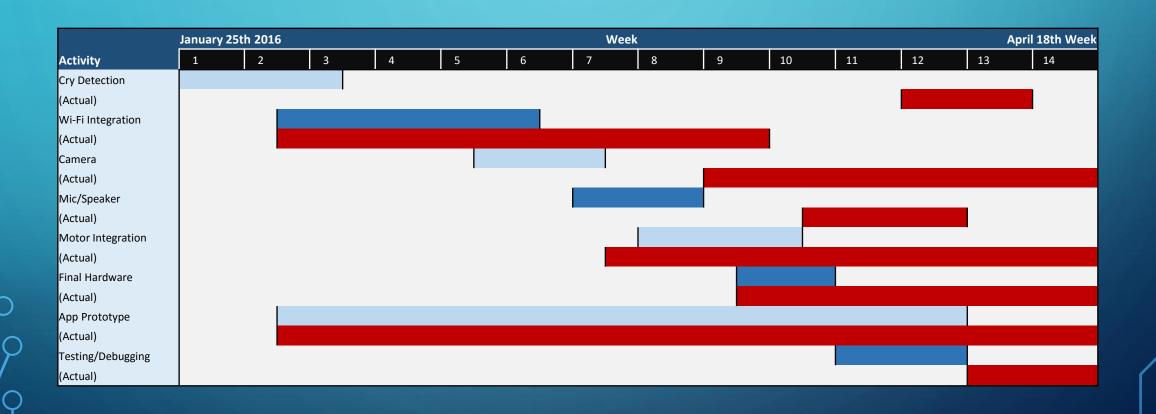
### BLOCK DIAGRAM OF SMART BABY CRADLE SYSTEM



### MATERIALS AND COST

Components	Estimated	Actual	Difference
Baby Cradle	\$95	\$25	\$70
Stepper Motor	\$105	\$38	\$67
(Old)			
Stepper Motor	0	\$55	\$-55
(New)			
Motor Driver	\$25	\$30	\$-5
Power Adapter	\$25	\$25	\$0
Microcontroller	\$34	\$68	\$-34
Camera	\$32	\$43	\$-11
Microphone	\$19	\$74	\$55
Speaker	\$6	\$6	\$0
Wifi Module	\$76	\$15	\$61
Mobile Toy	\$10	N/A	\$10
Others	\$75	\$31	\$44
(wires, belts, hardware)			
Total	\$502	\$410	\$92

### TIMELINE



### MARKET & COMPETITION

- The average parent is Around 29 years old
- Most People especially the younger generation have smartphones

### Competition

- Fisher Price 4 in 1 Smart Cradle'N'Swing
  - \$362.35 in Amazon (USD)



### PRICE AND ESTIMATED SALES

- Cost of Prototype: \$410
- Expected Price after Mass Production: \$300
- 390, 000 estimated New Parents in Canada
- \$9,700,000 Estimate Profit if 20% of New Parents purchased BabyRocks 'Smart Baby Cradle.

### PROBLEMS WE FACED

- We initially used an Arduino Uno
  - It couldn't handle more than one Shield
- Limitations in Hardware
  - Couldn't implement multithreaded functions
- We initially ordered the wrong motor.
- The webcam we ordered needed decoding.
- We had Budgeting Issues due to the lack of available funding.

### CONCLUSION

### REFERENCES

- Statistics Canada "Births, estimates, by province and territory" <a href="http://www.statcan.gc.ca/tables-tableaux/sum-som/101/cst01/demo04a-eng.htm">http://www.statcan.gc.ca/tables-tableaux/sum-som/101/cst01/demo04a-eng.htm</a>
- "Robot Shop" <a href="http://www.robotshop.com/blog/en/how-to-make-a-robot-lesson-5-motor-controller-3695">http://www.robotshop.com/blog/en/how-to-make-a-robot-lesson-5-motor-controller-3695</a>
- "What is Torque" <a href="https://www.physics.uoguelph.ca/tutorials/torque/Q.torque.intro.html">https://www.physics.uoguelph.ca/tutorials/torque/Q.torque.intro.html</a>
- "Getting Started" <a href="http://developer.android.com/training/index.html">http://developer.android.com/training/index.html</a>

# QUESTIONS