Verifynd

Outdoor Asset Tracking Solutions

Many cities are in North America are experiencing an epidemic of intravenous drug use and overdose deaths [1].

Photographed in Yaletown, June 2020



Clean syringe dispensaries offer a life saving service, unfortunately, many used needles are discarded in public spaces.[2]

Photographed in East Vancouver, July 2020

Frustrated Citizens



94% "Concerned" or "Very Concerned"

The Urban Needle Locator



Our RFID-based system for geolocating used syringes is designed for increasing the efficiency & accuracy of cleanup.

A Tale of Two Systems



Chief Operations Officer

Madhu Udayakumar

Hardware Embedded Systems

- The main components of the Urban Needle Locator:
 - Passive tags embedded in syringes (sourced)
 - Active Mobile Antenna
 - Cloud-based maps for displaying
 Syringe locations



Passive RFID tags

Bella Xu Electronic Power Systems

- Manufacture-produced passive tags embedded in syringes are pinged by active antenna
- Unique identification and Received Signal Strength Indicator(RSSI) value are acquired



Passive RFID embedded in syringe [3]

Transport System



Liam Goundrey

Mechanical Design

- System reads randomly oriented tags in a radius of 8m
- Antenna rotates at a constant rate controlled by PID feedback

Cloud Sync

Alex Makasoff Software Embedded Systems

- RFID Antenna, Motor system, and GPS sensor need to work together to determine the location of the RFID tag
- UNL Mark I needs to respond to events in real-time and be able to operate in a uncontrolled environment



Google Maps Platform



Eric Kwok

- Mobile antenna system collects syringe location data which is uploaded to the Google Maps API
- Locations can be displayed individually, or it can be displayed as a heatmap for a broader overview
- Private, secure, customizable

Algorithm

Matthew Schilling

Design Integration & Algorithms

- RFID does not directly measure location
- We are exploiting aspects of RFID signals to predict where a tag is located within a few feet of estimation







Main Functions

- Drive system will provide constant speed to rotate RFID antennas
- RFID system will detect tags with unique ID
- Characteristic received signal strength (RSSI) and unique phase will be used to identify location
- GPS coordinates will be uploaded to Google Maps Platform

Project Modules

- Drive System
 - DC Motor
 - Motor Driver
 - Rotary Encoder
 - Gearing
 - Slip Ring
- RFID antenna & reader
- Accelerometer module
- GPS module







Software Development

- Triangulation can be done through GPS coordinates
- RFID system will detect tags with unique ID
- Characteristic received signal strength (RSSI) and unique phase will be used to identify location
- GPS coordinates will be displayed through Google Maps

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Cradle to Cradle

- ABS plastic as component materials
- Electronic components recycled by Electronic Recycling Association



Cradle-to-Cradle Design [4]

Budgeting

- Initial budgeted values were based off of accessible prices of components outlined in the design specification
- Verifynd maintains an inventory containing all purchased parts, receipts and current holders
- The uncertain nature of the project has led to several budgetary changes.



Budget Breakdown



Market Analysis



Case Study: Harm Reduction Fund [5]

- \$7M
- \$7M CAD funded annually to support projects across Canada reducing HIV and hepatitis C among drug users

- 20%
- Of federal funding goes toward BC organizations to support injection drug users

24 hrs

Current goal by VCH is to recover all needles within 24 hours via a hotline

Vancouver: Break-Even Cost Analysis



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7.33% it will save the city money.

Ideal Customer

A tool within established workflows



Spikes on Bikes [6]

- Vancouver's Spikes on Bikes program gives needed supplies, including syringes, to community members.
- The UNL could be easily added as a bike trailer for passive operation during their usual 8am-8pm 7 day per week rides.

Adherence to Standards

- RFID Technology
- Electrical designs
- Software designs
- Safety considerations

Adhering to Engineering standards ensures UNLmkl can be used by consumers in the Canadian market.









Standards

RFID Technology

- Radio Frequency bandwidth:ISO/IEC 18000-6:2010 [7]
- UHF RFID identification and capture techniques: CAN/CSA-ISO/IEC 29143:2011 [8]
- Design parameters of item tagging information: ISO 17367:2013 [9]
- Data and data management of RFID passive tags: ISO/IEC 15961-3:2019 [10]

Electrical

- Computing and electrical design: ICES-003 [11]
- Rechargeable Batteries: 1625-2004 IEEE [12]

Software

- Software used in the device or end user: ISO/IEC TR 25060:2010 [13]
- Design of the cloud computing service: ISO/IEC TR 23188:2020 [14]
- Google Cloud Maps: ISO/IEC TS 23167:2020 [15]

Safety

- Electronic components: IEC TR 62824:2016 [16]
- Electronics enclosure: CAN/CSA-C22.2 No. 94.2-07 (R2012) [17]
- Safety Requirements for Medical device: ISO/TR 24971:2020 [18]

Risks



tagged syringes

effectively

individuals

Risk Management



Schedule 405W

1	Jun	Jul	Aug	Sep	2020
Design Specifications and UI	Jun 22 - Jul 10 Jun 29 - Jul 4 Jul 8 - Jul 8	Research on Drive Research on integrated Jul 13 Research on vo I 13 - Jul 20 Research	er system I RFID system Itage regulator on Google API		
Proposal		Jul 23 - Jul 25 📒 Final	lize project costs		
Proof-of-Concept	Jun 19 - Jul 10 Implement software algori Successfully de	Buy components Jul 23 - Aug 3 Jul 26 - Aug 6 Achieve a read distance of 9 thms for identifying tag loca termine an RSSI position es Systematic inte Acceptance	Build motor system Set up RFID system 5 m Aug 6 ation Aug 7 - Aug 10 stimate Aug 10 sgration Aug 10 - Aug e Testing Aug 11 - Au PoC demo Aug 21	3 18 Ig 19	

Schedule for 440



Hardware

- Implement another RFID reader.
- Design efficient and reliable power sourcing circuits.
- Implement reliable button control system.

Plan for 440

Software

- Improve Algorithm for precisely identifying the location of each tag.
- Improve Google Maps API

Integration

- Implement easy to use interface for tag locations on maps.
- Fine tune PID control and external user control features.







Lessons Learned

- Time management in coordination with group
- Use online writing aids to improve written English
- Public speaking

Self-Reflection:

• Importance of precise Technical Knowledge

Self-Reflection: Improvement for ENSC 440

 Communication and coordination is a major difficulty without common scheduling at the SFU campus; weekly group meetings have been beneficial but we need to find a better way to production manage the project

Time management and goal actualization have been difficult to manage in a work from home environment

Self-Reflection: Improvement for ENSC 440

- Open ended problem solving, and operationalization of tasks has been a challenge, and requires more experience
- Purchasing equipment and supplies has been more expensive than anticipated as multiple pieces are often required to ensure work is productive and physically distant
- Planning for hardware modules malfunctioning and buying equipment and supplies at the same time to save on delivery time

Conclusion



ENSC 405W has been challenging and rewarding, learning valuable lessons about group work and overcoming setbacks in real world applications.

We look forward to applying all we have learned here to a successful implementation of the Urban Needle Locator prototype in 440.

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Faculty of Applied Sciences



Questions

Additional information:

verifynd.ca

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