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LARGE SAMPLE PROPERTIES OF THE COX
TECHNIQUE IN SURVIVAL TIME ANALYSIS

by
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A THESIS SUBMITTED IN PARTIAL FULFILLMENT OF
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LARGE SAMPLE PROPERTIES OF THE COX TECHNIQUE IN SURVIVAL TIME ANALYSIS

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ABSTRACT

The Cox partial likelihood technique is explored in a large sample setting. For a variety of parametrizations of the proportional hazard rate model, consistency and asymptotic normality of the Maximum Partial Likelihood estimators are proved. The covariates are taken to be random and observations are censored on the right. Previous assumptions on the distribution of the covariates are relaxed. An extension to the case of non-random covariates is considered.

RESUME

Les propriétés asymptotiques de l'estimateur obtenu en maximisant la fonction de vraisemblance partielle de Cox sont étudiées. Sa convergence et sa normalité asymptotique sont prouvées pour diverses paramétrisations du modèle. Les covariates sont assumées aleatoires. Les hypothèses sur leur distribution faites dans les articles parus à ce jour sont supprimées. Enfin le cas où les covariates sont des constantes non-aleatoires est explorée.
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Introduction

In a carcinogenic experiment, the cancer-inducing properties of a substance (for example a new food additive) have to be evaluated. This substance is injected into mice in different doses. The times of appearance of a tumor are recorded. Some mice might die before developing cancer. In cancer research a new drug is found, but its effectiveness seems to depend on several covariates: for example the age of the patient, its sex, its blood count at the beginning of the experiment, etc... Then an experiment is designed and the times of death, for example, are recorded. Some patients might decide to leave the experiment before the end. Some might die of causes other than cancer. These two examples are censored survival data: some subjects are withdrawn from the experiment for causes other than those of interest.

A useful tool to analyse survival data is the hazard rate. It gives the "intensity of risk" of failure at any time t, given that the individual has not failed prior to t. More formally the hazard rate at time t among subjects with covariate Z is defined as:

$$\lambda(t, z) = \lim_{\Delta t \to 0} \frac{p[t \leq T < t + \Delta t | T > t, z]}{\Delta t}$$

where T is the time of failure of the subject (time at which the mouse develops a tumor, time at which the individual dies), Z in our examples would be the dose of substance, the age of the patient, etc... A model commonly accepted is the
proportional hazard rate model in which the hazard rate can be factored into one term depending on \( t \) and one term depending on the covariate.

Cox (1972) assumes a partly parametrized proportional hazard rate model according to:

\[
\lambda(t, z) = \lambda_0(t) h(p, z)
\]

where \( \lambda_0(t) \) is an unspecified function of \( t \) and where \( h(p, z) \) is usually \( e^{\beta z} \). However in carcinogenic experiments, where only small doses are considered, \( h(p, z) \) is commonly a polynomial in the dose \( z \). Then Cox introduces the partial likelihood function. At a time \( t \), the risk set \( R(t) \) at that time is the set of all subjects still in the experiment. Let us consider a failure time \( t_i \). Given the fact that one subject failed at that time and given \( R(t_i) \), the conditional probability that subject \( j \) failed is

\[
\frac{h(p, z_j)}{\sum_{k \in R(t_i)} h(p, z_k)}
\]

Simply multiplying these terms gives Cox's partial likelihood. This function is not really a likelihood function since the factor related to the intervals between two failure times is ignored. Nor is it a conditional or marginal likelihood except in special cases.

Therefore the classical results on the asymptotics of maximum likelihood estimates cannot be used. Cox (1972) gave a rather informal justification of the consistency and asymptotic normality. Since then no fully satisfying
paper has been published. Tsiatis (1978) proves consistency and asymptotic normality for bounded real-valued covariates drawn from a continuous population. In his argument, the experiment is stopped at some prespecified time $T_f$. Liu and Crowley (to appear) assume their covariates to be drawn from a finite set of possible values. Their argument is conditional on the observed values of the covariates.

Our first chapter will be a literature survey on the hazard rate models with covariates. It will give us an idea on how to analyze our two examples of survival data. The following chapter will give some more precise formulation of the model, assumptions and notations used thereafter. We shall then prove consistency and asymptotic normality for vector-valued covariates drawn from a continuous population. The proof of the consistency in the exponential case

$$h(\beta, z) = e^{\beta^T z}$$

will need no assumption on the boundedness of the covariates, only on their moments. Furthermore we will not assume that the experiment is stopped after the prespecified time.

In the case of other parametrizations of $h(\beta, z)$ it will be proved that the maximum partial likelihood equation has a consistent root when the experiment is stopped at some prespecified time.

The asymptotic normality will be proved for vector-valued covariates not bounded but with some further assumptions on the function $h$ and its first, second and third
order derivatives.

Then an extension of our arguments to the case where the covariates are give constants is considered.
Literature survey on hazard rate models with covariates

The analysis of time to occurrence or "failure data" is of considerable interest for medical experiments. The growing importance of medical research has triggered numerous papers on specialized methods to analyze this kind of data. The classical notion of hazard function is a tool commonly used. The hazard function \( \lambda(t, z) \) gives the "risk" of failure at any time of a subject having covariates \( z \), given that the subject has not failed prior to \( t \). In his pioneering paper in 1972, Cox assumed (as we do in the following chapters) that the hazard function could be factorized in one term depending on \( t \) and one term depending on \( z \) and a parameter \( \beta \) according to:
\[
\lambda(t, z) = \lambda_0(t) h(\beta, z)
\]
More precisely, Cox specified \( h(\beta, z) = e^{\beta z} \) as do the majority of papers. Another fruitful partially parametric model was introduced by Prentice and Kalbfleisch (1979):
\[
\lambda(t, z) = \lambda_0(t e^{\beta z}) e^{\beta^2 z}
\]
The covariates then act multiplicatively on the time of failure itself. A prospective type of sampling is usually considered. A population of subjects is given at some specified origin of time measurement and followed forward to observe their respective times of failure. Kalbfleisch and Prentice (1979) investigated the case of retrospective studies in which subjects are selected on the basis of
their time of failure after which one "looks back" to ascertain the corresponding covariates values or covariates functions.

I) Analysis of the models:

There are several approaches to the analysis of the above models. The most natural one is to parametrize them completely, by using for example a two-parameter Weibull regression model for model (1) with $\lambda(t) = \lambda_0(t)^{q} \exp(\beta t)$. Other parametric special cases of (2) include the log-normal, the log-logistic and the generalized gamma regression models (e.g. Farewell and Prentice 1977). Then standard methods such as maximum likelihood can be used.

The other approach to deal with model (1) is the technique considered in the following chapters: 'Cox's partial likelihood method.

II) Cox's partial likelihood technique:

Cox's technique is a partial parametrization of model (1) where $\lambda(t)$ is allowed to be arbitrary. The main interest is in the regression parameters: for example we want to know if the substance studied induces tumors. Cox's likelihood function is then introduced and the vector of estimates of the regression parameters is the maximum of this likelihood function. Cox (1972) gave a rather informal justification to this likelihood function. In 1975 he considered it in more detail under the term partial likelihood. Kalbfleisch and Prentice (1973) showed that in the absence
of censoring, Cox's likelihood is precisely the likelihood based on the marginal distribution of the ranks of the failure times. A group invariance argument showed the rank vector to be "partially" sufficient, in the sense of Barnard (1963), for in the "absence of knowledge" of . Their group invariance argument breaks down with censored data. In this case they showed only that it is the likelihood corresponding to the marginal probability of the set of possible underlying rank vectors consistent with the observed data. There are no classical results on this "likelihood".

No tied failure times are assumed in the above models. Unfortunately the data will often be recorded with ties. If the number of ties is small, an ad hoc modification of the above procedures is satisfactory (Cox 1972, Kalbfleisch and Prentice 1979). Otherwise it is preferable to use a discrete failure time model. Kalbfleisch and Prentice (1973) showed that grouping the continuous model (1) gives a discrete model with simple properties. Cox (1972) introduced a generalized partial likelihood function.

III) Asymptotics:

Two main papers, still unpublished, deal with consistency and asymptotic normality of the estimator obtained by using Cox's technique. These are Tsiatis's (1978) and Liu-Crowley's (to appear) but neither of them can be considered as fully satisfactory. Liu and Crowley consider a discrete approach to the problem: their covariates take values in a finite set of possible values.
Their argument is conditional on the observed values of the covariates. This is an interesting step towards proving consistency and asymptotic normality when the covariates are not assumed to be drawn from a population but are given constants. The main drawback is that they consider a finite set of possible values and their argument seems to be difficult to extend to an infinite set of possible values. Tsiatis considers as we do a continuous approach. He assumes that the real-valued covariates are bounded and that the experiment is stopped at a prespecified time. We remove both these assumptions and consider vector-valued covariates.

Cox's technique is asymptotically fully efficient only in special circumstances. However, the amount of information lost in any specific data, with the function restricted, is usually small. Many have tried to give some more formal basis to that argument. Kalbfleisch (1974) assumes that there is no censoring, that the covariate vector has dimension 1 and does not depend on time. He then shows that the Cox likelihood estimator has full efficiency with respect to the M.L.E. relative to any parametric model in (1) of the form \( \lambda_0(t) = \lambda \lambda_0(t) \) with \( \lambda_0(t) \) known and \( \lambda \) scale parameter to be estimated if the true value \( \beta \) is equal to 0. He then derives the approximate expression \( \exp\left\{-\beta \frac{1}{\lambda} \text{Var}(z)\right\} \) for the asymptotic relative efficiency valid near \( \beta = 0 \). The dependance of
efficiency on the regression parameter is a situation unfamiliar to ordinary linear regression. In an important paper, Efron (1977) attacks the problem from an interesting viewpoint. Taking the covariate functions and censoring times to be fixed, he derives expressions for the finite sample information matrices and gives conditions for Cox's method to be asymptotically fully efficient. In his parametrization he introduces a notional "average hazard if all items are on test". In his formulation, the underlying hazard function may depend on the regression coefficients as well as the nuisance parameters. He then discusses the relative efficiency in the two-sample problem and gives some simulation results in this case.

This thesis provides a rigorous foundation for some of the efficiency calculations.

An attractive feature of inference based on Cox's likelihood is the robustness implied by the arbitrariness in the $\lambda$ function. Steve Samuels, in a 1977 unpublished doctoral dissertation at the University of Washington has examined the robustness of $\hat{\lambda}$ more formally.

IV) Other parametrizations of the hazard rate—Parametrizations of $h(\beta, z)$

In the preceding sections we factorized the hazard rate $\lambda(t, z)$ according to $\lambda(t, z) = \lambda(t) h(\beta, z)$. The most common parametrization for $h(\beta, z)$ is the exponential
model. Feigl and Zelen (1965) treated the case \( \lambda_0(t) = \lambda \) constant, and proposed several forms for \( h \), notably the exponential model and \( h(p, z) = \frac{1}{1 + p^2 z} \). In carcinogenic testing, scientists are interested in the relationship between the dose of a potential cancer inducing substance injected into an animal and the time at which that animal develops cancer. In this field, many workers stipulate the Weibull form \( \lambda_0(t) = \lambda(t - \alpha)^{\beta-1} \) in which \( \alpha \) is usually taken as known and hence without loss of generality taken to be 0. Hartley and Sielken (1977) introduced a polynomial form for \( \lambda_0 \) according to \( \lambda_0(t) = \beta_r t^r \) with \( \beta_r > 0 \) and some standardization rules. The model form of the dose dependent \( h(p, z) \) has been of particular concern, as the interest is usually in small doses (see Mantel and Bryan (1961)) and it is in this dose range that monitoring data is difficult, particularly if the spontaneous rate is zero. The multiphase models of Armitage and Doll (1961) and Armitage (1974) specify \( h(p, z) \) as a polynomial of the dose level \( z \) of the form \( h(p, z) = \sum_{s=1}^{q} \alpha_s (1 + \chi_s z) \) in which all \( \chi_s \) are strictly positive. Peto (1974) adopts a more general model of the form \( h(p, z) = \alpha s^{\chi s} \), \( \alpha, s > 0 \).

In this thesis Cox's technique is studied with more general parametrization of \( h \) such as those mentioned here.

Hartley and Sielken (1975b) dropped the polynomial form and stipulated only that \( h(p, z) \) is a smooth positive
convex function (unpublished paper). As in this case
\[ \lambda_o(t) \] is parametrized, their technique is a partly
parametric one similar to Cox's.

V) Survivor function estimation:

Surprisingly little attention has been given
to the estimation of the survival function and its standard
error. The underlying survivor function \( F(t, z) = P[\tau \geq t, z] \)
can be written \( F(t, z) = F_o(t)^{h(p, z)} \) where
\[ F_o(t) = \exp\left(-\int_0^t \lambda_o(u) \, du\right) = \exp(-\Lambda_o(t)) \]

At any specified \( p \) a non-parametric maximum likelihood
estimation can be carried out (Kalbfleisch and Prentice
1973) to give an estimator of \( F_o(t) \). Breslow and Crowley
(1974) consider a continuous case, where there are no ties
among observations. Using likelihood arguments, they
introduce an empirical integrated hazard function according
to
\[ \hat{\Lambda}_o(t, \hat{p}) = \frac{1}{\lambda \in D(t)} \left[ \sum \exp(\beta z_j) \right] \]

They then establish that if the true value of \( p \) is 0
the random function \( \sqrt{n} \left[ \hat{\Lambda}_o(t) - \Lambda_o(t) \right] \) converges to a
mean zero Gaussian process, \( \Lambda_o(t) \) being the true
integrated hazard function. Tsiatis has extended that
result to \( \hat{\Lambda}_o(t, \hat{p}) \) where \( \hat{p} \) is Cox's partial likelihood
estimate again under rather severe restrictions such as
bounded covariates.

We have not studied the problem of extending
this result to the more general setting of this thesis.
Chapter 1: Model, Assumptions, Notation

In this chapter we shall give a precise mathematical formulation of the model and introduce the notation and assumptions needed later on. In the examples given in the introduction, the available data were the covariates for each subject, the time at which each subject left the experiment, the reason why it left and the size of the population. Let us introduce the following notation:

- let $Z_i$ be the vector of observed covariates for subject $i$.
- let $Y_i$ be the time of disappearance of subject $i$ from the experiment.
- we define an indicator variable $\delta_i$ to indicate for which reason the subject $i$ left the experiment according to $\delta_i = 0$ if subject $i$ was censored, $\delta_i = 1$ otherwise.
- let $N$ be the size of the population at the start of the experiment.
- let $\beta_0$ be the true value of the regression parameter.

**Distribution of the random variables:**

Let us assume that for each subject $i$ we have two underlying random variables: $T_i$, the true underlying survival time, and $S_i$ time of censoring. The observed variable $Y_i$ is just the minimum of $T_i$ and $S_i$. $T$ and $S$ will
be assumed independent given the vector of covariate $Z$. This is not a mild assumption. For example, in a medical experiment, a person cured (very late time of death) may leave the experiment early. It seems very hard to remove this assumption as a censoring dependent on the time of death could grossly mislead the statistician by concealing all the information relative to some values of the covariates.

To solve our problem, we shall take a continuous approach. The covariate vectors will be assumed to be of dimension $p$ and to be drawn from a continuous population. It is our conviction that the method we use in the following chapter can be extended to the case where the covariates are given constants drawn from an infinite population of possible values.

Let us introduce the notation: 
$$ G(t|z) = P[S > t|z] $$

$G(t|z)$ is an unknown function of $t$. $S$ does not necessarily have a conditional hazard function. We have the freedom to allow censoring in groups, even to assume that, at a certain time $T_f$, everyone still in the experiment is censored. For technical reasons, we shall assume that there is only a finite number of mass-points in the density of $S$ given $Z$.

The model for the hazard rate:

We shall assume that the random variable $T$ has a conditional hazard rate $\lambda(t,z)$. We shall assume a commonly accepted form of the hazard rate $\lambda(t,z) = \lambda_\theta(t) h(p,z)$
where $\lambda_o(t)$ depends only on $t$ and is otherwise unspecified, and $h(\beta, z)$ depends on a parameter $\beta$ and the covariate vector $z$. $\beta$ is the parameter of interest and has dimension $p$. This model is called the proportional hazard rate model since the ratio of the hazard rates of two subjects depends on the covariates and not on time. Following Cox (1972) we shall use a partial parametrization of $\lambda(t, z)$.

$\lambda_o(t)$ is assumed unknown and without any constraint.

On the other hand $h(\beta, z)$ is assumed to be a known function of $\beta$ and $z$. Usually $h(\beta, z)$ is assumed to be $e^{\beta'z}$.

In the following we shall assume only that $h(\beta, z)$ is such that $h(\beta, z), \frac{\partial h(\beta, z)}{\partial \beta^k} (k=1, \ldots, p)$ are monotone functions of $\beta$ for each $z$ and each $l$. This assumption is satisfied for all the parametrizations mentioned in the literature survey.

Assumptions on the moments of $h(\beta, z)$:

Tsiatis (1978) assumed that the covariates are bounded. Instead we shall make assumptions only on the moments of $h(\beta, z)$ and $\left\| \frac{\partial h}{\partial \beta} \right\|$:

$$E[h(\beta, z)^r]$$ exists for $r = -3, -2, -1, 1, 2, 3$ and for every $\beta$. In what follows there is actually some freedom of choice in which moments of $h$ are assumed to exist. For instance we could assume $E[h(\beta, z)^r] < \infty$ for each $\beta$ and $-1 < r < 5$. (See page 38.)

$$E\left[ \left\| \frac{\partial h}{\partial \beta} \right\|^r \right]$$ and $E\left[ \left\| \frac{\partial h}{\partial \beta} \right\|^l \right]$ exist for every $\beta$. 
Although it would be desirable to do so it seems difficult to eliminate the assumptions about inverse moments of \( h \).

Obviously in the exponential case it is sufficient that \( E[e^t] \) exists for every \( \rho \).

**Classical results:**

Let \( \varphi_z(t) \) be the density of \( T \) given \( Z \). We know that:

\[
\lambda(t, z) = \frac{\varphi_z(t)}{1 - P[T < t | z]}
\]

Straightforward computations yield that:

\[
\varphi_z(t) = h(\rho_z, z) \lambda_0(t) \exp\left(-\int_0^t \lambda_0(u) h(\rho_z, z) \, du \right)
\]

The conditional probability of surviving until time \( t \) without being censored given that \( Z = z \) is:

\[
H(t | z) = G(t | z) \exp\left(-\int_0^t \lambda_0(x) h(\rho_z, z) \, dx \right)
\]
Chapter 2: Consistency

In this chapter we shall prove the consistency of the estimate obtained by maximizing Cox's partial likelihood function. More precisely we shall prove the following theorem:

- In the exponential case, Cox's partial likelihood has only one local maximum and this maximum converges in probability to the true value of the parameter.

- In the general case where $h(\boldsymbol{\beta}, z)$ is such that $h(\boldsymbol{\beta}, z)$ and $\frac{\partial h(\boldsymbol{\beta}, z)}{\partial \beta_k} (K = 1, \ldots, p)$ are monotone functions of $\beta_1$ for each $z$ and each $k$, if the time of censoring is bounded by a finite time $T_f$, and if this time $T_f$ is such that $\mathbb{P}[Y > T_f] > 0$, then there is a root of the maximum Cox's partial likelihood equation (a local maximum of Cox's likelihood function) that is consistent in probability.
The log of Cox's partial likelihood is:

\[ \log L_c = \sum_{i=1}^{N} \delta_i \log h(p, z_i) - \sum_{i=1}^{N} \delta_i \log \left[ \sum_{j=1}^{N} 1(y_j \geq T_i) h(p, z_j) \right] \]

Let us consider

\[ \Phi_n(p) = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log h(p, z_i) = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log \left[ \frac{1}{N} \sum_{j=1}^{N} 1(y_j \geq T_i) h(p, z_j) \right] \]

\( \Phi_n(p) \) and \( \log L_c \) have the same shape. Studying the maxima of \( \Phi_n(p) \) is equivalent to studying the maxima of \( \log L_c \). From now on we will study \( \Phi_n(p) \) instead of \( \log L_c \).

\( \Phi_n(p) \) is a sum of dependant random variables.

Let \( f_n(t) = \frac{1}{N} \sum_{j=1}^{N} 1(y_j \geq t) h(p, z_j) \)  

By the strong law of large numbers, for fixed \( t \), \( f_n(t) \) converges to \( f(t) = E[h(p, z) 1(y \geq t)] \). We will prove that we can replace \( f_n(T_i) \) by \( f(T_i) \) in \( \Phi_n(p) \). \( \Phi_n(p) \) is then a sum of i.i.d random variables. We then shall apply the strong law of large numbers to prove that \( \Phi_n(p) \) converges point-wise to a function \( \Phi(p) \).

We shall then study the function \( \Phi(p) \). We shall prove two important results:

1) \( p_0 \) is an extremum of \( \Phi(p) \)

2) \( \Phi(p) \) is concave on a small neighbourhood of the true value \( p_0 \).

The exponential case and the general case will then be distinguished.
In the exponential case, we shall prove is concave on the whole domain of \( p \). Then \( \Phi_n(p) \) has only one local maximum \( \hat{p}_n \). In a neighbourhood \( V \) of the true value \( p_0 \), \( \Phi_n(p) \) and \( \Phi(p) \) are two continuous concave functions. We shall prove (lemma 7) this implies that the location of the maximum of \( \Phi_n \) in \( V \) converges to the location of the maximum of \( \Phi \), that is \( p_0 \). \( \Phi_n(p) \) has only one local maximum. This implies the consistency of \( \hat{p}_n \).

In the general case, we will have to reduce our study to the neighbourhood \( V \) of \( p_0 \). As we don't know anything about the shape of \( \Phi_n \) in \( V \) we shall need to prove the uniform convergence of \( \Phi_n \) to \( \Phi \) in \( V \). We will then prove that \( \Phi_n \) has a local maximum in \( V \) and that this local maximum converges to \( p_0 \). To prove the uniform convergence, we shall prove that the sequence is equicontinuous. In order to do so, we shall have to assume that the censoring time, \( S \), for an individual is bounded by a prespecified time \( T_f \). This assumption is needed more for mathematical reasons than real statistical ones. Anyway it is a mild one, since most survival studies are ended after some prespecified time \( T_f \).
A) **Lemmas:**

The four following lemmas are mainly computations needed later on. First let us introduce the following notations: Let \( k(z', t) \) be a function of \( z \) and \( t \):

\[ E_{z,t}(k(z', t)) \] means expectation of \( k(z', t) \) where the summation is done over \( z \) and \( t \).

\[ E_{t}(k(z', t)) \] means conditional expectation of \( k(z', t) \) given \( z \).

The proofs of these lemmas are given in the appendix.

**Lemma 1:**

\[
E_S(z) = \int_{t=0}^{t=\infty} \lambda_0(t) h(p, z) e^{\int_0^t \lambda_0(u) h(p, z) du} G(t|z) dt
\]

\[
E_S(z) = E_t[G(t|z)]
\]

**Lemma 2:**

Let \( f(w) = E[h(p, z) 1(y \geq w)] \)

\[
f(w) = E_{z} \left[ h(p, z) \left( \exp \int_0^w \lambda_0(u) h(p, z) du \right) G(w|z) \right]
\]

**Lemma 3:**

\[
E \left[ S \log f(t) \right] = E_{z,t} \left[ \log f(t) G(t|z) \right]
\]

**Lemma 4:**

\[
E_S(1(y \geq w)|z) = \int_{t=w}^{t=\infty} \lambda_0(t) h(p, z) \left( \exp \int_0^t \lambda_0(u) h(p, z) du \right) G(t|z) dt
\]
Lemma 5: Let $\{a_n\}$ a sequence of real numbers converging to 0, let $h(p,z)$ be a known function of $p$ and $z$.

Then

$$\sup_t \left\{ a_n \sqrt{n} \left| \frac{1}{n} \sum_{j=1}^{n} 1(y_j \geq t) h(p,z_j) - E[1(y \geq t) h(p,z)] \right| \right\}$$

converges to 0 in probability, for $p$ fixed.

Proof: First let us give some definitions. Let $D$ be the space of functions on $[0, \infty)$ that are right continuous and have left-hand limits. Let us define the Skorokhod topology on $D$. Let $\mathcal{D}$ be the $\sigma$-field generated by the open sets of $D$. Let $x$ and $y$ be 2 functions of $D$. We want to define a distance $d(x,y)$. The idea is that we cannot measure time with perfect accuracy anymore than we can position.

Definition: Let $\Lambda$ denote the class of strictly increasing, continuous mappings of $[0, \infty)$ onto itself. If $\lambda \in \Lambda$ then $\lambda(0) = 0$ and $\lambda(\infty) = \infty$. Then set $d(x,y) = \inf \epsilon \epsilon \in S$ where

$$S = \left\{ \epsilon : (\exists \lambda \in \Lambda) \left( \sup_t |\lambda(t) - t| \leq \epsilon \right) \wedge \sup_t |x(t) - y(\lambda(t))| \leq \epsilon \right\}$$

Let us consider the random process $Z_n(t) = \frac{1}{n} \sum_{j=1}^{n} 1(y_j \geq t) h(p,z_j) - E[1(y \geq t) h(p,z)]$$

The random process $Z_n$ is an application from $(\Omega, \mathcal{B}, P)$ where $\Omega$ is the sample space, to $D$. Then for $\omega$ belonging to $\Omega$, $Z_n(\omega)$ is an element of $D$. The random process $Z_n$ induces a probability measure $P_n$ on $(\Omega, \mathcal{D})$ according to:

$P_n(A) = P_n(Z_n(\omega) \in A)$

where $A$ is a
measurable subset of $D$.

We shall prove that the sequence $\{Z_n\}$ of random processes converges in distribution to a Gaussian process $Z$ which has mean 0. By definition this means that the distribution $P_n$ of the $Z_n$ converge weakly to the distribution of $P$ of $Z$: $P_n \rightarrow P$. From Billingsley (1968), we have to prove that the finite dimensional distributions of $Z_n(t)$ are asymptotically multivariate normal with mean zero and that the sequence of distributions of $Z_n(t)$ is tight.

**Step 1:** A simple application of the multivariate central theorem yields that the finite dimensional distributions of $Z_n(t)$ are asymptotically distributed as a multivariate normal with mean zero.

**Step 2:** The sequence $\{P_n\}$ is tight. From Billingsley (1968) p. 128, it suffices to show that:

$$
E \left[ \left( Z_n(t) - Z_n(t_1) \right)^2 \left( Z_n(t_2) - Z_n(t) \right)^2 \right] \leq C_4 \left[ F(t_2) - F(t_1) \right]^{4/3}
$$

where $F(t) = P[Y < t]$, $0 \leq t_1, t \leq t_2$.

The proof is given in the appendix. Therefore we have:

$$
P_n \rightarrow P
$$

Now let us prove it implies that

$$
\sup_t \left\{ a_n \sqrt{n} \left[ \frac{1}{n} \sum_{j=1}^{n} 1(y_j > t) h(p, z_j) - E[1(y > t) h(p, z)] \right] \right\}
$$

converges to 0 in probability.
Let us give first some further results and definitions:

- Let us define the supremum norm according to, for \( x \) belonging to \( D \):
  \[
  \rho(x) = \sup_t |x(t)|
  \]

- Result: (Billingsley) convergence to a continuous limit (such as \( Z(w) \)) in \( \rho \) is equivalent to convergence in the Skorokhod metric. Therefore, if \( A_\varepsilon \) is the subset of \( D \) such that
  \[
  A_\varepsilon = \{ x \in D; \rho(x) > \varepsilon \},
  \]
  then
  \[
  P_n( Z_n(\omega) \in A_\varepsilon) \rightarrow P(Z(\omega) \in A_\varepsilon)
  \]

Similarly,
  \[
  P_n( a_n Z_n(\omega) \in A_\varepsilon) \rightarrow P(a_n Z(\omega) \in A_\varepsilon)
  \]

The sequence of real numbers
  \[
  y_n = P(a_n Z(\omega) \in A_\varepsilon)
  \]

converges to 0. We then have proved the result:

\[
\sup_t a_n \sqrt{\frac{n}{\rho}} \sum_{j=1}^{n} I(y_j > t) h(p, z_j) - E[I(y > t) h(p, z)]
\]

converges to 0 in probability.
Lemma 6: Let us consider the i.i.d random variables

$$\log h(\beta, z_j)$$

We have: $$\max_{j=1}^{N} \left| \log h(\beta, z_j) \right|$$ converges almost surely to 0 when $$N \to +\infty$$ with $$p$$ large. Later on we shall need to know "how fast" the maximum over the whole population of $$\left| \log h(\beta, z_j) \right|$$ goes to $$+\infty$$. This lemma gives us an upper bound.

Proof:

Note: Borel-Cantelli lemma: given events $$A_n$$; $$n=1,2,\ldots$$, \(\sum \mathbb{P}(A_n) < \infty\) then $$\mathbb{P}(\limsup A_n) = 0$$ (to be read "$$A_n$$'s occur infinitely often").

First by using the Borel-Cantelli lemma we shall prove that for any $$\varepsilon$$

$$\mathbb{P}\left( \max_{j=1}^{N} \left| \log h(\beta, z_j) \right| > \varepsilon \right) \to 0$$

$$\left| \log h(\beta, z_n) \right|$$ being the value of $$\log h(\beta, z)$$ for the Nth subject. We shall then prove it yields that

$$\mathbb{P}\left( \max_{j=1}^{N} \frac{\left| \log h(\beta, z_j) \right|}{N^{\frac{1}{2}} - \frac{1}{\sqrt{p}}} > \varepsilon \right) \to 0$$

Let us introduce the following notation: $$x_j = \left| \log h(\beta, z_j) \right|$$ and $$M_n = \max_{j=1}^{N} x_j$$. Let $$A_n$$ be the event $$\frac{X_n}{N^{\frac{1}{2}} - \frac{1}{\sqrt{p}}} > \varepsilon$$

Let us prove $$\sum \mathbb{P}(A_n) < \infty$$

The Tchebitchchev inequality yields

$$\mathbb{P}(y > \varepsilon) \leq \frac{\mathbb{E}[y^k]}{\varepsilon^k}$$

Then

$$\mathbb{P}\left( \max_{j=1}^{N} x_j > \varepsilon \right) \leq \frac{\mathbb{E}\left[ \left( \max_{j=1}^{N} x_j \right)^k \right]}{\varepsilon^k} \max_{j=1}^{N} x_j$$

provided $$\mathbb{E}(X^k)$$ exists.

Then

$$\sum \mathbb{P}(A_n) \leq \frac{\mathbb{E}\left[ x_j^k \right]}{\varepsilon^k} \max_{j=1}^{N} x_j$$

Then

$$\sum \mathbb{P}(A_n) \leq \frac{\mathbb{E}\left[ x_j^k \right]}{\varepsilon^k} \max_{j=1}^{N} x_j$$
To have convergence of $\varepsilon \text{ PAn}$ it is sufficient that
\[
\frac{K - \frac{K}{p}}{3} > 1
\]
for example $K = 3 + \delta$, where $\delta$ is an arbitrary small number. As
\[
\left| \log h(\beta, z) \right| \leq h(\beta, z) + \frac{1}{h(\beta, z)}
\]
the existence of $E \left[ |\log h(\beta, z)|^{\lambda + \varepsilon} \right]$ is implied by the existence of $E \left[ h(\beta, z)^{\lambda + \varepsilon} \right]$ and $E \left[ h(\beta, z)^{(\lambda + \varepsilon)} \right]$

Therefore there is convergence of $\varepsilon \text{ PAn}$. (Recall our assumption in chapter 1) The Borel-Cantelli lemma implies then that
\[
P \left[ \frac{X_n}{\eta^{\frac{1}{3}} - \frac{1}{p}} > \varepsilon \right. = O
\]

Let us prove by contradiction this implies:
\[
P \left[ \frac{M_n}{\eta^{\frac{1}{3}} - \frac{1}{p}} > \varepsilon \right. = O
\]

Let us assume there exists a sequence $\{M_n\}$ such that
\[
\frac{M_n}{\eta^{\frac{1}{3}} - \frac{1}{p}} > \varepsilon
\]
Consider first $\eta_0 \in \mathbb{N}$ such that
\[
\frac{M_{\eta_0}}{\eta^{\frac{1}{3}} - \frac{1}{p}} > \varepsilon
\]
If $X_{\eta_0} \leq \varepsilon \eta^{\frac{1}{3}} - \frac{1}{p}$ then $M_{\eta_0} > \varepsilon \eta^{\frac{1}{3}} - \frac{1}{p}$

$n$ is not the first $n$ such that $M_n > \varepsilon \eta^{\frac{1}{3}} - \frac{1}{p}$ it is a contradiction. Then
\[
X_{\eta_0} > \varepsilon \eta^{\frac{1}{3}} - \frac{1}{p}
\]

$\exists \eta^* \text{ such that } \frac{M_{\eta_0}}{\eta^{\frac{1}{3}} - \frac{1}{p}} \leq \varepsilon (\eta^*)^{\frac{1}{3}} - \frac{1}{p}$
\[
(\exists n \in \mathbb{N}) \left\{ \begin{array}{l}
\eta' > \eta^* \\
M_{\eta'} > \varepsilon (\eta')^{\frac{1}{3} - \frac{1}{p}}
\end{array} \right.
\]
As $\frac{M_{\eta_0}}{\eta^{\frac{1}{3}} - \frac{1}{p}} \leq \varepsilon (\eta^*)^{\frac{1}{3}} - \frac{1}{p}$ it implies $\{X_i\}_{i \geq 1}$ are such that $X_i \leq \varepsilon (\eta^*)^{\frac{1}{3} - \frac{1}{p}}$. 

\[
\frac{K - \frac{K}{p}}{3} > 1
\]
But \( M_{n^*} > \varepsilon (n')^{1/2 - 1/\rho} \) implies there is \( \eta_{(2)} \) such that

\[
\begin{cases}
\eta_{(3)} < \eta_{(2)} < n' \\
X_{\eta_{(2)}} \geq \varepsilon \eta_{(3)}^{1/2 - 1/\rho}
\end{cases}
\]

And so on...

We can build in this way a sequence \( \{ X_{\eta_{(i)}} \} \) such that

\[
(\forall \eta_{(i)}) \quad \frac{X_{\eta_{(i)}}}{\eta_{(i)}^{1/2 - 1/\rho}} > \varepsilon
\]

This yields a contradiction with the earlier result:

\[
P\left[ \frac{X_{n^*}}{n^{1/2 - 1/\rho}} > \varepsilon \right] = 0
\]

Then

\[
(\exists N_2) \left( \forall N > N_2 \right) \quad \frac{M_N}{N^{1/2 - 1/\rho}} < \varepsilon
\]

Since \( \varepsilon \) was arbitrarily chosen this gives:

\[
\max_{j=1,N} \left| \log h(\beta, z_j) \right| \quad \frac{1}{n^{1/2 - 1/\rho}} \quad \text{a.s.} \quad \to 0
\]
Lemma 7:
R.T. Rockafellar (1970) proved that if the continuous functions $F_n$ are convex on an open set $S$, if they converge pointwise to a function $F$ on a subset $D$ dense in $S$, then the functions $F_n$ converge uniformly to $F$ on any compact set included in $S$.

As this result is not widely known, we have included in the appendix a proof of the following simpler result: if the continuous functions $F_n$ are convex on an open set $S$, if they converge pointwise to a function $F$ on $S$, then the location of the maximum of $F_n$ converges to the location of the maximum of $F$. 
B. \( \Phi_N(\rho) \) converges point-wise to \( \Phi(\rho) \) when \( N \to \infty \)

We know that:

\[
\Phi_N(\rho) = \frac{1}{N} \sum_{i=1}^{N} S_i \log h(\rho, z_i) - \frac{1}{N} \sum_{i=1}^{N} S_i \log \left[ \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_i) h(\rho, z_j) \right]
\]

Let us first consider the first term

\[
\frac{1}{N} \sum_{i=1}^{N} S_i \log h(\rho, z_i)
\]

The terms \( S_i \log h(\rho, z_i) \) are i.i.d random variables. Therefore we can apply the strong law of large numbers to prove that

\[
\frac{1}{N} \sum_{i=1}^{N} S_i \log h(\rho, z_i)
\]

converges to

\[
E[\sum_{i=1}^{N} S_i \log h(\rho, z_i)]
\]

which has been computed in Lemma 1.

Now let us consider

\[
\frac{1}{N} \sum_{i=1}^{N} S_i \log \left[ \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_i) h(\rho, z_j) \right]
\]

That term is a sum of dependant random variables, we want to replace it by a sum of i.i.d random variables. More precisely, let

\[
f_n(w) = \frac{1}{N} \sum_{j=1}^{N} 1(y_j > w) h(\rho, z_i)
\]

and let

\[
\beta(w) = E[h(\rho, z) 1(y > w)]
\]

\[
\hat{\alpha}_n = \frac{1}{N} \sum_{i=1}^{N} S_i \log f_n(T_i), \quad \alpha_n = \frac{1}{N} \sum_{i=1}^{N} S_i \log f(T_i)
\]

Let us prove that \( \hat{\alpha}_n \) converges point-wise to \( \alpha_n \).

(i.e. \( \hat{\alpha}_n - \alpha_n \) converges to 0 pointwise as function of \( \rho \) ) The proof of this convergence is an essential part of this chapter on Consistency. This proof follows. Then we can apply the strong law of large numbers to

\[\alpha_n\]

to prove that \( \alpha_n \) converges point-wise to

\[E[\sum_{i=1}^{N} S_i \log \beta(T_i)]\]

which has been computed in Lemma 3.
Proof of the convergence of $\hat{\alpha}_n$ to $\alpha_n$:

Remember that we used the notation $f(t) = E[1(y > t) h(p, z)]$

As we allowed mass-points in the density of the censoring time, $f(t)$ is only assumed to be left-continuous. But we shall assume there is only a finite number of discontinuities after a certain time $f(t)$ is continuous. Let us give an example of the function $f(t)$. Consider a medical experiment, where sex and age are among the covariates. At a specified time $T$, all the women, for example, are withdrawn from the experiment, at $T_0$ all the men over 40 years are withdrawn. In this example $f(t)$ would have the graph (G1):

![Graph of f(t)](image)

In order to prove the convergence of $\hat{\alpha}_n$ to $\alpha_n$, we shall have to consider different cases depending on the shape of $f(t)$.

**Case A**: There is a time $T_f$ such that

$$\left( \forall t > T_f \right) f(t) = 0$$

The experiment is stopped at a certain specified time $T_f$. We shall have to consider two different subcases:
Subcase A1: \( f(t) \) is continuous at \( T_f \) which yields \( f(T_f) = 0 \)

Subcase A2: \( f(t) \) is not continuous at \( T_f \), \( f(T_f) > 0 \)

At \( T_f \) we stop the experiment, every subject not withdrawn is censored. This Subcase A2 is the only case studied by Tsiatis (1978). It is the most commonly encountered situation.

Case B: \( (\forall t) f(t) > 0 \)

It is in this case that the proof of the convergence of \( \hat{\alpha}_n \) to \( \alpha \) is the most difficult. To prove the consistency in this case is interesting first for theoretical reasons.

If we stop an experiment at \( T_f \), we obtain by Cox's technique an estimate \( \hat{\beta}^*_n \). But we didn't consider what is happening after \( T_f \). The theoretical estimate \( \hat{\beta}^*_n \) obtained by
observing the experiment till $t \rightarrow \infty$ is the estimate using all the information useful for Cox's technique. It would be quite worrisome if $\hat{B}_n$ was not consistent. Furthermore, if the asymptotic approximations are to be applied in situations where the experiment ends with the death or failure of virtually all the subjects, then we will not have confidence in the approximations unless we can establish consistency in this case B.
Case A there is a time $T_f$ such that $(\forall t>T_f) f(t)=0$

**Subcase A1:** $f(T_f) = 0$

Let us prove that this subcase A1 can be treated as a case B by changing the time axis. For example let us change $t$ in $t'$ according to $t' = \frac{1}{T_f - t} \cdot \frac{1}{T_f}$, the range of $t'$ is then $[0, +\infty)$.

The order of times of death is unchanged. As Cox's likelihood uses only the order of time of death, Cox's likelihood is unchanged.

Let us prove that the structure of the model is not changed: we still have a proportional hazard rate model.

Let us compute the hazard rate $\lambda^*(t', z)$ of the subject with covariate $z$ at time $t'$.

Remember the density of $t$ given $z$ is:

$$\varrho_z(t) = \lambda_0(t) h(p_o, z) \exp{-\int_0^t \lambda_0(u) h(p_o, z) du}$$

We have $t = T_f - \frac{1}{t' + \frac{1}{T_f}}$, this gives $dt = \frac{1}{\left(t' + \frac{1}{T_f}\right)^2} dt'$. Then density of $t'$ given $z$ is:

$$\varrho^*_z(t') = \lambda_0\left( T_f - \frac{1}{t' + \frac{1}{T_f}} \right) h(p_o, z) \exp{-\int_0^{t'} \lambda_0(u) h(p_o, z) du} \frac{1}{T_f - t' + \frac{1}{T_f}}$$

Let $F(y^*) = P[t' < y^*] = \int_{y^*}^{T_f} \varrho^*_z(t') dt' = \int_{y^*}^{T_f} \varrho_z(u) du = 1 - \exp{-\int_0^{y^*} \lambda_0(u) h(p_o, z) du}$

Therefore:
\[ \hat{\lambda}(t', z) = \frac{\Psi_x(t')}{1-F(t')} \], we have

\[ \hat{\lambda}(t', z) = \frac{\lambda_0 \left( \frac{T_F - \frac{t'}{x + V_T}}{x} \right)}{h(x, z)} \]

We still have a proportional hazard rate model with the same parametrization \( h \).

**Subcase A2:** \( f(T_F) > 0 \)

We want to prove that \( \hat{\alpha}_n = \frac{1}{N} \sum_{i=1}^{N} \log f_n(T_i) \) converges in probability to \( \alpha_n = \frac{1}{N} \sum_{i=1}^{N} \log f(T_i) \)

We have:

\[ \left| \hat{\alpha}_n - \alpha_n \right| \leq \frac{1}{N} \sum_{i=1}^{N} \left| \log \frac{f_n(T_i)}{f(T_i)} \right| \]

We know that

\[ \left| \log \frac{f_n(T_i)}{f(T_i)} \right| = \left| \frac{f_n(T_i) - f(T_i)}{f(T_i)} \right| + R \left( \frac{f_n(T_i) - f(T_i)}{f(T_i)} \right) \]

\( R(x) \) means a function of \( x \) of smaller order than \( x \).

\[ (\forall T_i) f(T_i) > f(T_F) \]

as \( f(t) \) is a decreasing function of \( t \), and \( T_i < T_F \)

Therefore

\[ \left| \frac{f_n(T_i) - f(T_i)}{f(T_i)} \right| \leq \left| \frac{f_n(T_F) - f(T_F)}{f(T_F)} \right| \]

But lemma 5 and the Skorokhod construction yields that

\[ \sup_{t} \left| f_n(t) - f(t) \right| \]

converges to 0 almost surely.

Therefore

\[ (\exists N_0) (\forall N > N_0) \left| \frac{f_n(T_i) - f(T_i)}{f(T_F)} \right| < \epsilon \]

This proves the convergence in probability of \( \hat{\alpha}_n \) to \( \alpha_n \) in this subcase A2.
Case B

Remember \( \hat{\alpha}_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f_n(T_i) \), \( \alpha_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f(T_i) \).

The difficulty here comes from the fact that when \( T_i \to +\infty \), \( f(T_i) \to 0 \), \( \log f(T_i) \to -\infty \).

To overcome that difficulty, we are going to divide \( \hat{\alpha}_n \) and \( \alpha_n \) in two terms: \( \hat{\alpha}_n = \hat{\alpha}_n + \hat{b}_n \), \( \alpha_n = \alpha_n + b_n \)

with

\[
\hat{\alpha}_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f_n(T_i) I(T_i < t_n), \quad \hat{b}_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f_n(T_i) I(T_i > t_n)
\]

\[
\alpha_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f(T_i) I(T_i < t_n), \quad b_n = \frac{1}{n} \sum_{i=1}^{n} \delta_i \log f(T_i) I(T_i > t_n)
\]

We are going to choose the sequence \( \{t_n\} \) going fast enough to \( +\infty \) so that \( \hat{b}_n \) and \( b_n \) converges to 0, and slow enough so that \( \hat{\alpha}_n \) converges to \( \alpha_n \). In this case B, the theorem will be proved in 3 steps.

Step 1: \( \hat{b}_n \to 0 \) for a suitable sequence \( \{t_n\} \).

Step 2: \( b_n \to 0 \) for any \( \{t_n\} \) such that \( t_n \to \infty \).

Step 3: \( \hat{\alpha}_n \to \alpha_n \) point wise in \( p \) for the sequence \( \{t_n\} \) (step 1).

We have to point out that the convergence of \( \hat{\alpha}_n \) to \( \alpha_n \) is quite straightforward when \( t_n \) is fixed; it is nothing else than the case A2.

Step 1: Let \( \{T_i\} \) set of times of deaths such that \( \delta_i = 1 \). Let us assume first that \( t_n < \text{Sup} T_i \).

Then there are \( \{T_n\} \) such that \( T_n > t_n \).
We are going to find a lower-bound and an upper-bound for $f_n(T_K)$.

$$f_n(T_K) = \frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_K) h(p, z_j)$$

Let $m(T_k)$ be the number of individuals in the experiment such that $y_j \geq T_k$. Obviously $1 \leq m(T_k) \leq m(t_n)$.

Then

$$\min_{j=1,N} h(p, z_j)^{m(T_k)} \leq f_n(T_K) \leq \min_{j=1,N} h(p, z_j)^{m(T_k)}$$

which gives $f_n(T_K) \geq \min_{j=1,N} h(p, z_j)$

We have found a common lower-bound. Now let us find a common upper-bound.

Let $\varepsilon$ given. There exists a compact $K_{p, \varepsilon}$ depending on $p$ such that $E[h(p, z)1(z \notin K_{p, \varepsilon})] \leq \frac{\varepsilon}{2}$ as $E[h(p, z)]$ exists.

$$f_n(T_K) = \frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_K) h(p, z_j)^{1(z_j \in K_{p, \varepsilon})} + \frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_K) h(p, z_j)^{1(z_j \notin K_{p, \varepsilon})}$$

We can prove that the 2nd term is bounded by $\varepsilon$ as:

$$\frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_K) h(p, z_j)^{1(z_j \notin K_{p, \varepsilon})} \leq \frac{1}{N} \sum_{j=1}^{N} h(p, z_j)^{1(z_j \notin K_{p, \varepsilon})}$$

$$(\exists N_0(p)) \left( \forall N > N_0(p) \right) \left| \frac{1}{N} \sum_{j=1}^{N} h(p, z_j)^{1(z_j \notin K_{p, \varepsilon})} - E[h(p, z)1(z \notin K_{p, \varepsilon})] \right| < \frac{\varepsilon}{2}$$

From the bounds of $f_n(T_K)$, we shall deduce
bounds on $b_n$

$$\log \left[ \min_{j=1}^{N} h(\beta, z_j) \right] - \log N \leq \log f_w(T_n) \leq \log \left[ \epsilon + \max_{z \in K_{\delta, p}} h(\beta, z) \right]$$

Remember

$$b_n = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log f_w(T_i) \mathbb{1}(T_i > t_n)$$

Consider $M^*(t_n)$, the number of individuals such that $S = 1$ and $T > t_n$. Then:

$$\left( \log \left[ \min_{j=1}^{N} h(\beta, z_j) \right] - \log N \right) \frac{M^*(t_n)}{N} \leq b_n(t_n) \leq \frac{M(t_n)}{N} \left( \log \left[ \epsilon + \max_{z \in K_{\delta, p}} h(\beta, z) \right] \right)$$

Remember we want to prove that $b_n(t_n) \to 0$ for a sequence $\{t_n\}$. It is sufficient to choose $\{t_n\}$ such that $\frac{\log N}{M^*(t_n)} \to 0$ and $\frac{\log \left[ \min_{j=1}^{N} h(\beta, z_j) \right] M^*(t_n)}{N} \to 0$.

In the remainder of the theorem it will be shown we need to choose the sequence $\{t_n\}$ such that $\sqrt{n} f(t_n) \to +\infty$.

Let us choose $\{t_n\}$ such that $\sqrt{n} f(t_n) = \log n$. This is possible as there is a finite number of discontinuities and we are in the case $(\forall t) f(t) > 0$.

$$f(t_n) = \mathbb{E}[h(\beta, z) \mathbb{1}(y > t_n)] = \frac{\log n}{\sqrt{n}}$$

We need two more steps to prove that $b_n(t_n)$ converges to 0 almost surely.

Step 1(a): $\frac{\log n}{h} M^*(t_n) \to 0$ in probability

Step 1(b): $\log \left[ \min_{j=1}^{N} h(\beta, z_j) \right] M^*(t_n) \to 0$ in probability

Step 1(a):

Let $M(t_n)$ be the number of individuals such that $y > t_n$. $M^*(t_n) < M(t_n)$.
When $N$ goes to $+\infty$, $\frac{m(t_N)}{n}$ converges to $E[1(y \geq t_N)]$

But $E[1(y \geq t_N)] = E[h(p, z)^{-\frac{1}{2}}] h(p, z)^{\frac{1}{2}} 1(y \geq t_N)]$

Remember Hölder's inequality: $E[xy] \leq E[x^r]^{\frac{1}{r}} E[y^s]^{\frac{1}{s}}$

where $\frac{1}{r} + \frac{1}{s} = 1$

Let $r = 6$, $s = 6/5$

Then we obtain

$$E[1(y \geq t_N)] \leq E[h(p, z)^{-\frac{3}{6}}] E[h(p, z)^{\frac{3}{5}}] 1(y \geq t_N)]^{5/6}$$

But:

$$E[h(p, z)^{\frac{3}{5}} 1(y \geq t_N)] = E[h(p, z)^{\frac{1}{5}} 1(y \geq t_N)] h(p, z)^{\frac{1}{5}}$$

Let us apply again Hölder's inequality: $r = 5/4$, $s = 5$

Then:

$$E[h(p, z)^{\frac{3}{5}} 1(y \geq t_N)] \leq E[h(p, z)^{\frac{5}{4}} 1(y \geq t_N)] E[h(p, z)^{\frac{1}{5}}]^{\frac{1}{5}}$$

Therefore:

$$E[1(y \geq t_N)] \leq E[h(p, z)^{-\frac{3}{6}}] E[h(p, z)^{-\frac{1}{6}}] E[h(p, z)^{-\frac{1}{6}}]^{1/3}$$

We assumed that $E[h(p, z)^{-\frac{3}{6}}]$ and $E[h(p, z)^{-\frac{1}{6}}]$ existed.

Therefore if $c = E[h(p, z)^{-\frac{3}{6}}]^{1/6} E[h(p, z)^{-\frac{1}{6}}]^{1/6}$, as

$$E[h(p, z)^{-\frac{1}{6}} 1(y \geq t_N)] = \frac{\log n}{n}$$

we have:

$$E[1(y \geq t_N)] \leq c \left(\frac{\log n}{n}\right)^{1/3}$$

Therefore $\log n E[1(y \geq t_N)]$ converges to 0.

Lemma 5 yields that

$$\sup_{w} \left| \log n \left\{ \frac{m(w)}{n} - E[1(y \geq w)] \right\} \right| \rightarrow 0 \text{ in probability}$$

Therefore $\log n \frac{m(t_n)}{n} \rightarrow 0$

But $m(t_n) \leq m(t_n)$

Therefore we proved step (1a): $\log n \frac{m(t_n)}{n} \rightarrow 0 \text{ in probability}$
The assumptions we made on the moments of \( h(\beta, z) \)
\[ (E[h(\beta, z)^{-3}], E[h(\beta, z)^{1}], E[h(\beta, z)^{3}]) \] are only a compromise between the assumptions needed in this step 1(a) and those needed in lemma (6) where \( \sum_{n=1}^{\infty} \left( \frac{1}{n^{1/2 - 1/p}} \right)^k \) has to converge. By using different values of \( r \) and \( s \) in Holder's inequalities, we could obtain different necessary values of the order of moments assumed converging. It must be pointed out that in the exponential case, this problem is of no importance as all moments exist if we simply assume \( E[e^{2\beta^2}] \) for all \( \beta \).

Step 1(b): We want to prove that
\[ \log \left[ \frac{\min_{j=1}^{N} h(\beta, z_j)}{\eta} \right] M^*(t_n) \] converges to 0. We have
\[ \left| \log \left( \frac{\min_{j=1}^{N} h(\beta, z_j)}{\eta} \right) \right| \leq \frac{\max_{j=1}^{N} \left| \log h(\beta, z_j) \right|}{\eta} \]
We know \( M^*(t_n) \leq M(t_n) \)
Therefore
\[ 0 \leq \frac{\left| \log \left( \frac{\min_{j=1}^{N} h(\beta, z_j)}{\eta} \right) \right|}{\eta} \frac{M(t_n)}{\eta} \]
But
\[ \left( \max_{j=1}^{N} \frac{\left| \log h(\beta, z_j) \right|}{\eta} \right) \frac{M(t_n)}{n^{1/3}} \leq \frac{\max_{j=1}^{N} \left| \log h(\beta, z_j) \right|}{\eta} \left( E[1(y \geq t_n)] + \sup_{w} \left| \frac{M(w)}{n} - E[1(y \geq w)] \right| \right) \]
Remember \( E[1(y \geq t_n)] \leq C \frac{\log n}{n^{1/3}} \)
Therefore
\[ \frac{\max_{j=1}^{N} \left| \log h(\beta, z_j) \right|}{\eta} \frac{E[1(y \geq t_n)]}{n^{1/3}} \leq \frac{\max_{j=1}^{N} \left| \log h(\beta, z_j) \right|}{\eta^{1/3 - 1/p}} \frac{n^{1/3 - 1/p}}{n^{1/3}} \cdot C (\log n)^{1/3} \]
lemma 6 proved \( \max_{j=1}^{N} \left| \log h(\beta, z_j) \right| n^{-1/3 - 1/p} \) converges to 0.
Moreover from lemma 6:
\[ \sup_{w} \left\{ \max_{j=1}^{N} \left| \log h(\beta, z_j) \right| \sqrt{n} \left| \frac{M(w)}{n} - E[1(y \geq w)] \right| \right\} \rightarrow 0 \]
Then step 1(b) is proved. Step 1(a) and 1(b) yield that:
\[ \hat{b}_n(t_n) \rightarrow 0 \]
Step 2: \[ b_n \rightarrow 0 \]

Remember \[ b_n = \frac{1}{N} \sum_{i=1}^{N} \delta_i \delta \log f(t_i) 1(t_i > t_n) \] We can apply the S.L.L.N. to prove \( b_n \) converges to \( E[\delta \log f(t) 1(t > t_n)] \) for \( t_n \) fixed. But \( E[\delta \log f(t)] \) exists. Then when \( t_n \rightarrow +\infty \), \( E[\delta \log f(t) 1(t > t_n)] \) converges to 0. Thus \( b_n \rightarrow 0 \).

Step 3: \( \hat{a}_n \rightarrow a_n \), point wise in \( p \) :

Remember

\[ \hat{a}_n = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log f_n(t_i) 1(t_i \leq t_n) ; \quad a_n = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log f(t_i) 1(t_i \leq t_n) \]

Therefore

\[ |\hat{a}_n - a_n| \leq \frac{1}{N} \sum_{i=1}^{N} |\log \frac{f_n(t_i)}{f(t_i)}| 1(t_i \leq t_n) \]

We know that:

\[ |\log \frac{f_n(t_i)}{f(t_i)}| = \left| \frac{f_n(t_i) - f(t_i)}{f(t_i)} \right| + R \left( \frac{f_n(t_i) - f(t_i)}{f(t_i)} \right) \]

\( R(x) \) means a function of \( x \) of smaller order than \( x \).

\( (\forall t_i \leq t_n) f(t_i) \geq f(t_n) \)

therefore

\[ \left| \frac{f_n(t_i) - f(t_i)}{f(t_i)} \right| \leq \left| \frac{f_n(t_i) - f(t_i)}{f(t_n)} \right| \]

But \( \frac{1}{f(t_n)} = \frac{\sqrt{n}}{\log n} \)

then

\[ \left| \frac{f_n(t_i) - f(t_i)}{f(t_i)} \right| = \sqrt{n} \left| \frac{f_n(t_i) - f(t_i)}{f(t_i)} \right| \]

But lemma 5 yields:

\[ \sup_{t} a_n \sqrt{n} \left| f_n(t) - f(t) \right| \rightarrow 0 \text{ in probability provided that } a_n \rightarrow 0 \text{. Let } \epsilon \text{ be fixed.} \]

Then:

\[ \left( \exists N_0 \right) \left( \forall n > N_0 \right) \frac{f_n(t_i) - f(t_i)}{f(t_n)} < \epsilon \text{. It yields } \frac{f_n(t_i) - f(t_i)}{f(t_i)} < \epsilon \]
Then \( \left| \log \frac{f_N(\tau_i)}{f(\tau_i)} \right| < 2\varepsilon \)

Then \( |\hat{\alpha}_n - \alpha_n| \leq \frac{2}{N} \varepsilon \quad \forall N \)

We have proved step 3: \( \hat{\alpha}_n \) converges to \( \alpha_n \). Therefore, steps 1, 2, 3, imply that \( \hat{\alpha}_n \) converges to \( \alpha_n \) in case B.

We then have proved:

\[
\phi_n(\beta) = \frac{1}{N} \sum_{i=1}^{N} \log \mathbb{E}[h(\beta, z_i)] - \frac{1}{N} \sum_{i=1}^{N} \log \left[ \prod_{j=1}^{N} \mathbb{E}[h(\beta, z_j)] \right]
\]

converges point wise in probability to

\[
\Phi(\beta) = \mathbb{E}_z \left[ \log h(\beta, z) \right] - \mathbb{E}_z \left[ \log f(t) G(t|z) \right]
\]

with

\[
f(w) = \mathbb{E} \left[ h(\beta, z) 1(y \geq w) \right] = \mathbb{E}_z \left[ h(\beta, z) G(w|z) \exp \int_0^w d_0(u) h(\beta_0, z) du \right]
\]

In the next two paragraphs we shall study the function \( \Phi(\beta) \). As we don't know the shape of \( h(\beta, Z) \), we will only be able to prove some results in the neighbourhood of \( \beta_0 \), namely:

(i) \( \beta_0 \) is an extremum of \( \Phi(\beta) \), and

(ii) \( \Phi(\beta) \) is concave in a neighbourhood \( \mathcal{V} \) of \( \beta_0 \).
C \( p_0 \) is an extremum of \( \Phi(\beta) \)

We shall prove \( \frac{\partial \Phi}{\partial \beta_i} \bigg|_{p_0} = 0 \)

Let \( \beta_i \) the \( i \)th coordinate of \( \beta \). Let us prove \( \frac{\partial \Phi}{\partial \beta_i} \bigg|_{p_0} = 0 \)

\[
\frac{\partial \Phi}{\partial \beta_i} \bigg|_{p_0} = E_z \left[ E \left[ \delta | z \right] \frac{\partial h(\beta, z)}{\partial \beta_i} \bigg|_{p_0} \right] - E_{t,z} \left[ G(t | z) \frac{\partial f(t)}{\partial \beta_i} \bigg|_{p_0} \right] = A - B
\]

Remember: density of \( t \) given \( z \) is:

\[
\lambda_0(t) h(p_0, z) \left( \exp - \int_0^t \lambda_0(u) h(p_0, z) \, du \right) \, dt
\]

- density of \( z \) is \( \chi(z) \, dz \)

\( B \) is a double integral in \( t \) and \( z \). By using Fubini's theorem, we can express it as:

\[
\int_{t=0}^{t=\infty} \lambda_0(t) \left( \frac{\partial f(t)}{\partial \beta_i} \right) \bigg|_{p_0} \left[ \int_{z=-\infty}^{z=\infty} h(p_0, z) \left( \exp - \int_0^t \lambda_0(u) h(p_0, z) \, du \right) G(t | z) \, \chi(z) \, dz \right] \, dt
\]

The term inside the brackets is nothing else than \( f(t) \).

Then

\[
B = \int_{t=0}^{t=\infty} \lambda_0(t) \left( \frac{\partial f(t)}{\partial \beta_i} \right) \bigg|_{p_0} \, dt
\]

Now let us consider

\[
A = E_z \left[ E \left[ \delta | z \right] \frac{\partial h(\beta, z)}{\partial \beta_i} \bigg|_{p_0} \right] \cdot \frac{E_{t,z} \left[ G(t | z) \frac{\partial f(t)}{\partial \beta_i} \bigg|_{p_0} \right]}{h(p_0, z)}
\]

Remember we proved in lemma 1 that:
\[ E[S|z] = \int_{t=0}^{t=\infty} \lambda_0(t) h(\rho_0, z) \left( \exp \int_0^t \lambda_0(u) h(\rho_0, z) du \right) g(t|z) dt \]

We can express as before \( A \) in a double integral in \( t \) and \( z \):

\[
A = \int_{t=0}^{t=\infty} \left[ \int_{z=-\infty}^{z=\infty} \left( \frac{\partial h}{\partial \beta_i} \right) \rho_0 \left( \exp \int_0^t \lambda_0(u) h(\rho_0, z) du \right) g(t|z) \xi(z) dz \right] dt
\]

But the term inside brackets is \( \left( \frac{\partial f(t)}{\partial \beta_i} \right) \rho_0 \). Thus \( A = B \) and so

\[
\left( \frac{\partial \phi}{\partial \beta_i} \right) = 0
\]

\( \rho_0 \) is an extremum of \( \Phi(\beta) \).

As yet, we do not know if it is a maximum or minimum nor do we know if it is the only extremum of \( \Phi(\beta) \).
D Concavity of \( \Phi(p) \) in a neighbourhood \( V(p_o) \) of \( p_o \).

We assumed that \( \frac{\partial^2 \Phi}{\partial p^2} \) was continuous. Therefore to prove that there is a neighbourhood \( V(p_o) \) of \( p_o \), on which \( \Phi(p) \) is concave, it is sufficient to prove that \( \left( \frac{\partial^2 \Phi}{\partial p^2} \right) \) is a positive definite matrix at \( p = p_o \).

Let us consider \( \frac{\partial \Phi}{\partial p_i \partial p_k} \)

\[
\frac{\partial \Phi}{\partial p_i \partial p_k} = E_z \left[ \frac{\partial}{\partial p_i} \left( \frac{\partial^2}{\partial p_k \partial p_k} \right) \right] - E_z \left[ \frac{\partial^2}{\partial p_i \partial p_k} \left( \frac{\partial h}{\partial p_i} \right) \left( \frac{\partial h}{\partial p_k} \right) \right] - \frac{G(t|z)}{f(t)} E_z \left[ \frac{\partial h}{\partial p_i} \left( \exp \left( - \int_0^t \lambda_o(u) h(p_o, z) du \right) \right) \right] G(t|z) \]

\[
+ E_z \left[ \frac{G(t|z)}{f(t)} \right] E_z \left[ \frac{\partial h}{\partial p_k} \left( \exp \left( - \int_0^t \lambda_o(u) h(p_o, z) du \right) \right) \right] E_z \left[ \frac{\partial h}{\partial p_i} \right] G(t|z) \exp \left( - \int_0^t \lambda_o(u) h du \right) \]

Let \( \frac{\partial \Phi}{\partial p_i \partial p_k} = A_{ik} - B_{ik} - C_{ik} + D_{ik} \)

We shall prove \( \left( \frac{\partial^2 \Phi}{\partial p_i \partial p_k} \right) \) is a positive definite matrix in two steps. In the first step we shall prove \( A_{ik} = B_{ik} \).

In the second step we shall prove \( [D_{ik}] - [B_{ik}] \) is a positive definite matrix under a mild assumption on the set of \( z \)'s.

**First step:** \( A_{ik} = C_{ik} \)

We shall use arguments similar to C. \( C_{ik} \) is a double integral in \( t \) and \( z \) that can be expressed as:
Remember that

\[ B(t) = E_z \left[ \lambda_0(t) h(p_0, z) \exp \left( \int_0^t \lambda_0(u) h(p_0, z) du \right) G(t|z) \right] \]

Therefore

\[ A_{ik} = E_z \left[ \frac{\partial \lambda_0}{\partial p_i} \frac{\partial G(t|z)}{\partial p_k} \right] \int_{t=0}^{t=+\infty} \lambda_0(t) G(t|z) \left( \exp \left( \int_0^t \lambda_0(u) h(p_0, z) du \right) \right) dt \]

By inverting the order of the integrals, \( A_{ik} \) can be transformed into \( C_{ik} \).

\[ A_{ik} = C_{ik} \]

**Second step:** \( (Dik) - (Bik) \) is a definite positive matrix.

By similar arguments as before, we can express \( B-D \) as:

\[ (Dik) - (Bik) = \int_{t=0}^{t=+\infty} \frac{\lambda_0(t)}{f(t)} \left[ E_z \left[ h(p_0, z) \exp \left( \int_0^t \lambda_0(u) h(p_0, z) du \right) G(t|z) \right] \right] E_z \left[ \frac{G(t|z)}{h(p_0, z)} \left( \frac{\partial \lambda_0}{\partial p} \right)^2 \exp \left( \int_0^t \lambda_0 h du \right) \right] G(t|z) dt \]

Let us call \( M(t) \) the term in large brackets. In the appendix A5 it will be shown that \( M(t) \) can be expressed as a double integral:
\[ M(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=x}^{z=+\infty} \left\{ \frac{\partial h(p,z)}{\partial \beta} \right\} \frac{\partial h(p,x)}{h(p,z)} \right\} \, dp(t,z,x) \]

Therefore \( B - D = \)

\[ B - D = \int_{t=0}^{t=+\infty} \frac{\lambda_0(t)}{f(t)} M(t) \, dt \]

- obviously \( B - D \) is positive.

- let us prove \( B - D \) is definite:

\[ V(z,x) = \frac{\partial h(p,z)}{\partial \beta} h(p,z) - \frac{\partial h(p,x)}{h(p,x)} \]

Let \( X \) be a vector.

\[ \chi' (B - D) X = 0 \iff (\forall x) (\forall z) \chi' \chi = 0 \iff (\forall x) (\forall z) \chi = 0 \]

\[ \iff (\forall z) (\forall x) \frac{\partial h(p,z)}{\partial \beta} \chi = \frac{\partial h(p,x)}{h(p,x)} \chi \]

Let us take \( x \) such that \( \frac{\partial h(p,x)}{\partial \beta} = 0 \).

This implies

\[ (\forall z) \frac{\partial h(p,z)}{\partial \beta} X = 0 \]

If there was such an \( X \), it would mean we didn't need so many dimensions for the parameter \( \beta \).

For example if \( h(p,z) = e^{\beta z} \), \( (\forall z) \frac{\partial h(p,z)}{\partial \beta} X = 0 \) means

\[ (\forall z) \frac{p}{k_{xi}} z_k X_k = 0 \]

i.e. the \( z \)'s are in a hyperplane.
A covariate can be expressed as a linear combination of the others. Then we have no reason to consider this covariate; we don't need as many dimensions for the parameter $\beta$. We shall assume there is no such $x$.

Then $B-D$ is positive definite. Therefore:

$$\left(\frac{\partial^2 \phi}{\partial \beta^2}\right)_{\beta_0}$$

is a positive definite matrix.

Hence there is a compact neighbourhood $V(\beta_0)$ of $\beta_0$, which $\phi(\beta)$ is strictly concave.

E Exponential case: $h(\beta, z) = e^{\beta' z}$

We are now considering the special case $h(\beta, z) = e^{\beta' z}$.

This case is the most used model, the one used by Cox in his original paper. Let us prove that in this case, $\phi_\beta(\beta)$ is concave everywhere. For obvious reasons $\phi_\beta(\beta)$ has the same concavity as the following function

$$\phi_\beta^*(\beta) = \sum_{i=1}^{N} \delta_i \beta' z_i - \sum_{i=1}^{N} \delta_i \log \left[ \sum_{j \in R_i} e^{\beta' z_j} \right]$$

Let us study $\frac{\partial \phi_\beta^*}{\partial \beta}$:

$$-\frac{\partial \phi_\beta^*}{\partial \beta} = \sum_{i=1}^{N} \delta_i \left[ \sum_{j \in R_i} \left( \frac{e^{\beta' z_j}}{e^{\beta' z_j}} \right) z_j \right] - \sum_{i=1}^{N} \delta_i \left[ \sum_{j \in R_i} \left( \frac{e^{\beta' z_j}}{e^{\beta' z_j}} \right) \right] \left[ \sum_{j \in R_i} \left( \frac{e^{\beta' z_j}}{e^{\beta' z_j}} \right) \right]'$$

Let

$$A_i = \sum_{j \in R_i} z_j z_j' \left( \frac{e^{\beta' z_j}}{e^{\beta' z_j}} \right) \quad \text{and} \quad B_i = \sum_{j \in R_i} z_j \left( \frac{e^{\beta' z_j}}{e^{\beta' z_j}} \right)$$

Then

$$-\frac{\partial \phi_\beta^*}{\partial \beta} = \sum_{i=1}^{N} \delta_i \left[ A_i - B_i B_i' \right]$$
Let $T_i$ be a time of death. Given the risk set $R_i$, the conditional probability that subject $k$ died is 

$$\frac{e^{\beta z_k}}{\sum_{j \in R_i} e^{\beta z_j}}.$$ 

We can define the conditional expection of $z$ given $R_i$ as: 

$$E\left[ z \mid R_i \right] = \sum_{j \in R_i} z_j \left( \frac{e^{\beta z_j}}{\sum_{j \in R_i} e^{\beta z_j}} \right).$$

$$E\left[ z \mid R_i \right] = B_i.$$ 

Similarly, 

$$E\left[ z z' \mid R_i \right] = A_i;$$ 

Therefore 

$$A_i - B_i B_i' = E\left[ z z' \mid R_i \right] - E\left[ Z \mid R_i \right] E\left[ Z \mid R_i \right]'$$ 

is the variance-covariance matrix of $z$ given $R_i$. 

$$\begin{align*} 
\frac{\partial^2 \phi^*}{\partial \beta_i \beta_j} &= \sum_{i=1}^N \delta_i \left[ (A_i - B_i B_i') \right], \\
\begin{pmatrix} -\frac{\partial^2 \phi^*}{\partial \beta_i \beta_j} \end{pmatrix} &\text{is a positive matrix.}
\end{align*}$$

Let us prove that under a mild assumption $-\frac{\partial \phi^*}{\partial \beta_i}$ is definite. Let us consider: 

$$M_k = E\left[ \left( z - E[z \mid R_k] \right) \left( z - E[z \mid R_k] \right)' \mid R_k \right].$$ 

Consider $\gamma$ a vector 

$$\gamma' M_k \gamma = 0 \iff E\left[ \gamma' \left( z - E[z \mid R_k] \right) \left( z - E[z \mid R_k] \right)' \gamma \mid R_k \right] = 0 \iff E\left[ \left( \gamma' \left( z - E[z \mid R_k] \right) \right)' \mid R_k \right] = 0 \iff (\forall z \in R_k) \gamma' \left( z - E[z \mid R_k] \right) = 0$$
It means all the \( z \) belonging to \( R^k \) are in a hyperplane.

Then as \( \frac{\partial \phi_n^*}{\partial \beta^i} \) is a sum of matrices \( M_k \), \( \frac{\partial \phi_n^*}{\partial \beta^i} \) is definite unless each of these \( M_k \) is not definite. That can happen only if all the \( z \)'s at \( t=0 \) are in a hyperplane.

As we are looking for the asymptotic properties of \( \Phi_n \), provided that the domain of definition of \( z \) is not a hyperplane (as in the discussion on the concavity of \( \phi \), it would mean that \( p^* \) has too many dimensions) for a sample size large enough, the matrix \( M_0 \) (\( M_k \) at \( t=0 \)) is definite.

Therefore \( \frac{\partial \phi_n^*}{\partial \beta^i} \) is positive definite.

This proves that:

\( \Phi_n \) is strictly concave on the whole domain of \( \beta \)

Then \( \Phi_n \) has only one maximum \( \hat{\beta}_n \). As we can't infer anything about the shape of \( \Phi_n \) in the general case, it might be interesting to study some other particular models. For example, for a particular model, if \( \Phi_n \) has only one local maximum and if \( \Phi_n \) is concave in the neighbourhood of the true value, the proof of the consistency is similar to the proof of the consistency in the exponential case.

Let us go back to this exponential case: we
have proved that $\Phi(\beta)$ is concave on a compact neighbourhood $V$ of its maximum $p_0$ (indeed in this case $\Phi$ is convex on all $\mathbb{R}^r$), that \( \{ \Phi_n(\beta) \} \) is a sequence of functions converging point-wise in probability to $\Phi(\beta)$ and concave on $V$.

To apply Lemma 7 we need to know $\Phi_n(\beta, \omega) \rightarrow \Phi(\beta, \omega)$ for all $\beta$ in some countable dense set and for all $\omega$ except for a set $N \subset \Omega$ with $\mathbb{P}[N] = 0$. The point is that $N$ must not depend on $\beta$.

We now argue that $\hat{\beta}_n \rightarrow p_0$ in probability by contradiction. If $\hat{\beta}_n$ does not converge to $p_0$ in probability, there is a subsequence $n'$ such that

\[ \mathbb{P}[|\hat{\beta}_{n'} - p_0| > \varepsilon] > \delta > 0 \]

for some fixed $\varepsilon, \delta > 0$. Since $\Phi_n(\beta) \rightarrow \Phi(\beta)$ in probability for each $\beta$, it is possible to choose a subsequence $n''$ of $n'$ such that

$\Phi_n''(\beta) \rightarrow \Phi(\beta)$ for all $\beta$ with rational coordinates (the set of such $\beta$ is a countable dense set) and for all $\omega$ except for a set $N \subset \Omega$, independent of $\beta$, with $\mathbb{P}(N) = 0$. For this sub-subsequence Rockafellar's theorem proves that $\Phi_n'' \rightarrow \Phi$ uniformly on compacts. Hence $\hat{\beta}_{n''} \rightarrow \beta$ almost surely. Then $\mathbb{P}[|\hat{\beta}_{n''} - p_0| > \varepsilon] \rightarrow 0$ which contradicts the selection of $n''$ as a subsequence of $n'$. Therefore:

$\hat{\beta}_n$ is consistent in probability.
General Case:

As we can prove very little about the shape of $\Phi_n(p)$ in the general case, we shall use another tack. We shall prove that the sequence $\{\Phi_n(p)\}$ is equicontinuous in a neighbourhood of $p_0$. This will yield the uniform convergence of $\Phi_n$ to $\Phi$. That will give us an "idea" about the shape of $\Phi_n$ when $N$ gets large. For reasons mathematical more than statistical, we shall assume that the time of censoring is bounded by a certain finite time $T_f$. This assumption is mild since most survival studies are ended after some prespecified time. We shall assume moreover that that time $T_f$ is such that $P[Y > T_f] > 0$.

Equicontinuity of $\{\Phi_n(p)\}$ on a neighbourhood $V(p_0)$ of the true value $p_0$.

We will need the following classical result:

Theorem: If $E$ is a compact metric space and $f_n$ and equicontinuous sequence of real valued functions of $E$ converging pointwise for $x \in E$ in a countable dense subset of $E$ to a continuous function $f$ then $f_n \rightarrow f$ uniformly on $E$. We claim that $\{\Phi_n(p)\}$ is an equicontinuous sequence on a compact neighbourhood of $p_0$.

$$
\Phi_n(p) = \frac{1}{N} \sum_{i=1}^{N} \delta_i \log h(p, z_i) - \frac{1}{N} \sum_{i=1}^{N} \delta_i \log \left[ \frac{1}{N} \sum_{j \in R_i} h(p, z_i) \right]
$$
Let $p$ and $p_1$ be in a neighbourhood of $p_0$.

$$\Phi_n(p) = \Phi_n(p_1) + (p_1 - p) \left( \frac{\partial \Phi_n}{\partial p} \right)_p$$

with $p_*$ laying between $p_1$ and $p$. To prove the equicontinuity of $\{\Phi_n\}$ it is sufficient to prove $\left( \frac{\partial \Phi}{\partial p} \right)$ is bounded in $V(p_0)$.

Let us prove that $\left\| \frac{\partial \Phi_n}{\partial p} \right\|$ is bounded for $p$ close enough to $p_0$:

$$\frac{\partial \Phi_n}{\partial p} = \frac{1}{N} \sum_{i=1}^{N} \delta_i \left[ \frac{\partial h}{\partial p}(p, z_i) \right] - \frac{1}{N} \sum_{i=1}^{N} \delta_i \left( \frac{1}{N} \sum_{j \in R_i} \frac{\partial h}{\partial p}(p, z_j) \right)$$

First consider the 2nd term $B =

$$B = \frac{1}{N} \sum_{i=1}^{N} \delta_i \left( \frac{1}{N} \sum_{j \in R_i} \frac{\partial h}{\partial p}(p, z_j) \right)$$

We prove $B$ is bounded in 2 steps:

1st step:

$$\left\| \frac{1}{N} \sum_{j \in R_i} \frac{\partial h}{\partial p}(p, z_j) \right\|$$

bounded for $N$ large enough in a certain $V(p_0)$. 

2nd step: \( \frac{1}{N} \leq \frac{\partial h(p, z_j)}{\partial z_j} \) bounded for \( N \) large enough in a certain \( V(p_0) \).

First step: We shall assume \( p \) is in hypercube \( H \) of center \( p_0 \) such that \((\forall k) \left| p_k - p_{0k} \right| \leq \varepsilon \). We shall use the hypotheses we made on \( \frac{\partial h}{\partial p_k} \) is a monotone function of \( p_k \) for any \( l \). \( (p \) \( l \)th coordinate of \( p \)).

\[
\left\| \frac{1}{N} \leq \frac{\partial h}{\partial p} (p, z_j) \right\| \leq \frac{1}{N} \leq \left\| \frac{\partial h}{\partial p} (p, z_j) \right\|
\]

The parameter \( p \) has \( p \) dimensions.

\[
\left\| \frac{\partial h}{\partial p} (p, z_j) \right\| = \sqrt{\left[ \frac{\partial h}{\partial p_1} (p, z_j) \right]^2 + \cdots + \left[ \frac{\partial h}{\partial p_p} (p, z_j) \right]^2}
\]

\( \frac{\partial h}{\partial p_i} (p, z_j) \) is a function of \( p \); let \( p_1, p_2, \ldots, p_{q-1}, p_q, \ldots, p_p \) be fixed. We then have a monotone function of \( p_q \). Its maximum in \( [p_q - \varepsilon, p_q + \varepsilon] \) is either at \( p_q - \varepsilon \), or at \( p_q + \varepsilon \). Therefore the maximum of \( \frac{\partial h}{\partial p_i} \) in \( H \) is on one of the vertices: \( p_0 + \delta p \), \( \delta p \) being a vector such that \( \delta p_i = \pm 1 \). There are \( 2^p \) different vectors \( \delta p \), corresponding to the \( 2^p \) vertices of the hypercube. Let \( \Lambda \) be that set of vectors \( \delta p \).

Then obviously:
Then
\[
\left\| \frac{\partial h}{\partial \beta_i} (\beta, z_j) \right\|^2 \leq \sum_{\delta \in \Lambda_r} \left\| \frac{\partial h}{\partial \beta_i} (\beta + \delta, z_j) \right\|^2
\]

Therefore:
\[
\frac{1}{N} \sum_{j \in \mathcal{R}_1} \left\| \frac{\partial h}{\partial \beta} (\beta, z_j) \right\| \leq \sum_{\delta \in \Lambda_r} \left\{ \frac{1}{N} \sum_{j = 1}^{N} \left\| \frac{\partial h}{\partial \beta} (\beta + \delta, z_j) \right\| \right\}
\]

For each \( \delta_r \), \( \beta + \delta \) is a fixed vector, so we can apply the Strong Law of Large Numbers. Therefore there exists \( N_r \) such that:
\[
\frac{1}{N} \sum_{j = 1}^{N} \left\| \frac{\partial h}{\partial \beta} (\beta + \delta, z_j) \right\| \leq \epsilon + \mathbb{E} \left[ \left\| \frac{\partial h}{\partial \beta} (\beta + \delta, z) \right\| \right]
\]

But there exists only a finite number of \( N_r \), then by taking \( N > \text{Max} \{ N_r \} \), we have:
\[
\sum_{\delta_r \in \Lambda_r} \left\{ \frac{1}{N} \sum_{j = 1}^{N} \left\| \frac{\partial h}{\partial \beta} (\beta + \delta, z_j) \right\| \right\} \leq 2^p \epsilon + \mathbb{E} \left[ \left\| \frac{\partial h}{\partial \beta} (\beta + \delta, z) \right\| \right]
\]

We assumed that \( \mathbb{E} \left[ \left\| \frac{\partial h}{\partial \beta} (\beta, z) \right\| \right] \) exists for all \( \beta \).

We therefore have proved that for \( N > \text{Max} \{ N_r \} \), and for \( \beta \) in the hypercube \( H \).
2nd step: \[
\frac{1}{N} \leq h(p,z_j)
\]
is bounded.

Let
\[
c = \frac{1}{N} \leq h(p,z_j) = \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) h(p,z_j)
\]

We assumed \( T_c \leq T_F \) so \( c \geq \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) h(p,z_j) \)

Let us prove that for \( N \) large enough \( \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) h(p,z_j) \)

has a lower bound. Let us consider a compact \( K_\nu \) such that \( \rho[z \in K_\nu] > 0 \)

\[
c \geq \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) 1(z_j \in K_\nu) h(p,z_j)
\]

We could now apply the Strong Law of Large Numbers, but

\[
E \left[ 1(z \in K_\nu) 1(y > T_F) h(p,z) \right]
\]

would be close to

for \( N \) depending on \( p \).

We have to overcome this difficulty:

\[
\frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) 1(z_j \in K_\nu) h(p,z_j) = \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) 1(z_j \in K_\nu) h(p,z_j) + \frac{1}{N} \sum_{j=1}^{N} 1(y_j > T_F) \left[ h(p,z_j) - h(p_0,z_j) \right]
\]

Then there is \( N(p_0) \) depending on \( p_0 \) such that:
\( (\forall N > N(p_0)) \)

\[
\frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) I(z_j \in K_f) h(p_0, z_j) - \mathbb{E}\left[ I\left( z \in K_f \right) I(y \geq T_F) h(p_0, z) \right] \leq \varepsilon_1,
\]

We can make the 2nd term \( \frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) \left[ h(p_0, z_j) - h(p, z_j) \right] \)
small compared to \( \varepsilon_1 \), since:

\[
\frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) \left[ h(p_0, z_j) - h(p, z_j) \right] \leq \sup_{z \in K_f} \left[ h(p_0, z) - h(p, z) \right] \left[ \frac{1}{N} \sum_{j=1}^{N} I(z_j \in K_f) I(y_j \geq T_F) \right]
\]

\[
\frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) I(z_j \in K_f) \quad \text{is close to} \quad \mathbb{E}\left[ I\left( z \in K_f \right) I(y \geq T_F) \right]
\]

for \( N > N_1 \).

And

\[
\sup_{z \in K_f} \left[ h(p_0, z) - h(p, z) \right] \leq \varepsilon_1, \quad \|p - p_0\| < \varepsilon_1
\]

Then for \( p \) such that \( \|p - p_0\| < \varepsilon_2 \), \( N > N_2 \):

\[
\frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) \left[ h(p_0, z_j) - h(p, z_j) \right] \leq \varepsilon_1.
\]

Let

\[
\varepsilon_1 \leq \mathbb{E}\left[ I\left( z \in K_f \right) I(y \geq T_F) h(p_0, z) \right]
\]

Then for \( N \geq \sup\{N_2, N(p_0)\} \), for \( p \) such that

\[
\|p - p_0\| < \varepsilon_2:\quad \frac{1}{N} \leq h(p, z_j) \geq \frac{\mathbb{E}\left[ I\left( z \in K_f \right) I(y \geq T_F) h(p_0, z) \right]}{2}
\]

Hence:

\[
\left\| B_i \right\| \leq \frac{1}{N} \sum_{j=1}^{N} I(y_j \geq T_F) I(z_j \in K_f) \leq M \left\| \frac{1}{N} \sum_{i=1}^{N} S_i \right\| \quad \text{for suitable} \ M
\]
Therefore: B is bounded for a neighbourhood $\forall (p)$ of $p_0$.

Now let us consider the term $A = \sum_{i=1}^{N} \frac{\frac{\partial h}{\partial p}(p, z_i)}{h(p, z_i)}$.

As before

$$\|A\| \leq \sum_{i=1}^{N} \frac{\delta_i}{h(p, z_i)} \left\| \frac{\partial h}{\partial p}(p, z_i) \right\| ; \left\| \frac{\partial h}{\partial p}(p, z_i) \right\| \leq \left\| \frac{\partial h}{\partial p}(p + \delta, \epsilon, z_i) \right\|$$

We have assumed too that $h(p, z)$ is monotone in $p_1$, for $z$ fixed, for any $l$.

Then $\left( \exists \delta_r \in \mathcal{N}_r \right) \frac{1}{h(p, z_i)} \leq \frac{1}{h(p + \delta, \epsilon, z_i)}$.

Therefore

$$\frac{1}{N} \sum_{i=1}^{N} \frac{\left\| \frac{\partial h}{\partial p}(p + \delta, \epsilon, z_i) \right\|}{h(p, z_i)} \leq \left\| \frac{\partial h}{\partial p}(p + \delta, \epsilon, z_i) \right\|$$

There exists $N_{r_1, r_2}$ such that for $(\delta_{r_1}, \delta_{r_2})$

$$\frac{1}{N} \sum_{i=1}^{N} \frac{\left\| \frac{\partial h}{\partial p}(p + \delta_{r_1}, \epsilon, z_i) \right\|}{h(p, z_i)}$$

is bounded by

$$\mathbb{E} \left[ \frac{\left\| \frac{\partial h}{\partial p}(p, \delta_{r}, \epsilon, z) \right\|}{h(p + \delta_{r}, \epsilon, z)} \right] + \epsilon$$
But \( E \left[ \frac{\partial h(\beta + \delta, \varepsilon, z)}{\partial \beta} \right] \leq \sqrt{E \left[ \frac{\partial h(\beta_0 + \delta, \varepsilon, z)}{\partial \beta} \right]^2} \sqrt{E \left[ \frac{1}{h(\beta_0 + \delta, \varepsilon, z)} \right]} \)

Then \( E \left[ \frac{\partial h(\beta + \delta, \varepsilon, z)}{\partial \beta} \right] \) exists.

Therefore, as there is a finite number of \((\delta, \delta)\), it yields that \(\|A\|\) is bounded.

Therefore: \(\left\| \frac{\partial \phi_\nu}{\partial \beta} \right\|\) is bounded for \(\beta\) close enough to \(\beta_0\).

Let us recall what we proved in the general case:

- \(\phi_\nu(\beta)\) converges point-wise in probability to a given function \(\phi(\beta)\).
- The sequence \(\{\phi_\nu(\beta)\}\) is equicontinuous on a compact neighbourhood \(K_1\) of the true value \(\beta_0\).
- \(\beta_0\) is a maximum of \(\phi(\beta)\).
- \(\phi(\beta)\) is concave on a compact \(K_2\).

Let \(K\) be the intersection of \(K_1\) and \(K_2\). An argument similar to the one used on page 49 (but using equicontinuity in place of Rockafellar's theorem) proves that \(\phi_\nu\) has a local maximum on \(K\) which converges to the true value in probability.
We therefore have proved:

The Maximum Partial Likelihood equation has a root that is consistent in probability.

In the case of several roots, further work might extend some results of the classical M.L.E. theory to the Cox partial likelihood technique. For example, we could examine the change in the sign of \( \frac{\partial \phi_n}{\partial \theta} \) from positive to negative and searching the intervals in which these changes occur, to locate, evaluate and compare the maxima.

V.D. Barnett (1966) discusses a systematic method of doing this, using the "Method of false positions". Another method (Le Cam) could be to find a consistent estimator \( \hat{\theta}_n \) preferably easy to compute, then find either a nearby local maximum of Cox's likelihood or to do a one-step Newton Raphson from \( \hat{\theta}_n \) towards the maximum partial likelihood estimate. Some further study might show that as in the case of the maximum likelihood estimate, this new estimator is asymptotically minimum variance unbiased (i.e. fully efficient) when \( \theta \) has one dimension.
Chapter 3: Asymptotic Normality

Let \( \beta \) be the vector of parameters of interest and \( \beta^0 \) the true value of this parameter. Cox's likelihood is proportional to:

\[
\phi_n(\beta) = \sum_{i=1}^{N} \delta_i \log h(\beta, z_i) - \sum_{i=1}^{N} \delta_i \log \left[ \frac{1}{N} \sum_{j \in R_i} h(\beta, z_j) \right]
\]

Let \( \hat{\beta}_n \) be a consistent root of the partial likelihood equation. In this chapter we shall assume that there exists \( f \) such that the times of censoring are bounded by a certain time \( T_f \), that \( P[\gamma > T_f] > 0 \) and that

\[
\frac{\partial h(\beta, z)}{\partial \beta^r}, \frac{\partial^2 h(\beta, z)}{\partial \beta^r \partial \beta^s}, \frac{\partial^3 h(\beta, z)}{\partial \beta^r \partial \beta^s \partial \beta^t}
\]

are monotone functions in \( \beta \) for \( z \) fixed and for any \( r \). This last assumption is verified for the exponential model and more generally for any function \( h \) such that \( h(\beta, z) = g(\beta' z) \) where \( g(x) \) is a function such that \( g(x), g'(x), g''(x) \) are monotone.

For example, \( h(\beta, z) = (1 + \beta' z)^{-1} \), \( h(\beta, z) = 1 + \beta' z \) verify this assumption.

We shall prove that the random vector

\[
\sqrt{n} (\hat{\beta}_n - \beta^0)
\]

is asymptotically distributed as a multivariate normal random variable with mean zero and variance-covariance matrix \( V \). An approach quite similar to the one used in classical M.L.E. theory will be used. Taylor's expansion gives us:
As in the M.L.E. theory, we shall prove in a first step that \( \frac{1}{n} \left( \frac{\partial \Phi_n}{\partial \hat{p}} \right) \) is asymptotically distributed as a multivariate normal random variable. In a second step, we shall prove that \( \left( -\frac{1}{n} \frac{\partial \Phi_n}{\partial \hat{p}} \right) \) has the same limit as \( \left( -\frac{1}{n} \frac{\partial \Phi_n}{\partial \hat{p}} \right) \) and that this term converges to a finite limit. Unfortunately these terms are not averages of i.i.d random variables.

A First Step: \( C_n = \sqrt{n} \left[ \frac{1}{n} \frac{\partial \Phi_n}{\partial \hat{p}} \right] \) is asymptotically distributed as a multivariate normal random variable.

Let us introduce some notation: (following Akiatis)

\[
\hat{\xi}_j(t) = \frac{1}{n} \sum_{j=1}^{n} I(y_j > t) \frac{\partial h}{\partial p}(p \circ Z_j), \quad \xi_j(t) = E \left[ \frac{1}{n} \sum_{j=1}^{n} I(y_j > t) \frac{\partial h}{\partial p} \right]
\]

where \( y_j \) is the time of disappearance of subject having
covariate $z_j$.
\[ \hat{Q}(t) = \frac{1}{n} \sum_{j=1}^{n} I(y_j > t) \cdot h(p_j, z_j) \quad \varepsilon(t) = E[1(y > t) \cdot h(p, z)] \]
\[ Q(t) = \frac{1}{n} \sum_{i=1}^{n} I(y_i > t) \quad Q(t) = E[1(y > t)] \]

$Q(t)$ is the probability of surviving until time $t$ without being censored and eventually dying before being censored so $Q(0) < 1$. In the chapter on consistency, it was proved that
\[ E_z \left[ \frac{\delta}{\delta p} h(p, z) \right] = E_{t, z} \left[ \frac{\delta \varepsilon_z(t)}{\varepsilon(t)} \right] \]
Therefore, $C_n$ can be written as:
\[ \sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^{n} \frac{\delta h(p_i, z_i)}{h(p_i, z_i)} \right] - E_{t, z} \left[ \frac{\delta \varepsilon_z(t)}{\varepsilon(t)} \right] + E_{t, z} \left[ \frac{\delta \varepsilon_z(t)}{\varepsilon(t)} \right] \]

Let us first consider:
\[ F_n = \sqrt{n} \left[ E_{t, z} \left[ \frac{\delta \varepsilon_z(t)}{\varepsilon(t)} \right] \right] - \frac{1}{n} \sum_{i=1}^{n} \frac{\delta \varepsilon_z(t_i)}{\varepsilon(t_i)} \]
We have:
\[ E_{t, z} \left[ \frac{\delta \varepsilon_z(t)}{\varepsilon(t)} \right] = \int_{[0, T_F]} (-dQ) \frac{\varepsilon_z(t)}{\varepsilon(t)} \]

Similarly
\[ \frac{1}{n} \sum_{i=1}^{n} \frac{\delta \varepsilon_z(t_i)}{\varepsilon(t_i)} = \int_{[0, T_F]} (-dQ) \frac{\hat{\varepsilon}_z(t)}{\varepsilon(t)} \]

Hence we are thinking of $Q$ as the cumulative distribution function of a signed finite measure.

Therefore
\[ F_n = \sqrt{n} \left[ \int_{[0, T_F]} (-dQ) \frac{\varepsilon_z(t)}{\varepsilon(t)} - \int_{0}^{T_F} (-dQ) \frac{\hat{\varepsilon}_z(t)}{\varepsilon(t)} \right] \]
Then $C_n$ can be expressed as:

\[
C_n = \sqrt{n} \left\{ \frac{1}{n} \sum_{i=1}^{n} \left[ \frac{\delta_i}{h(\rho_0, z_i)} \frac{\partial h(\rho_0, z_i)}{\partial \rho} - E \left[ \frac{\delta}{h(\rho_0, z)} \frac{\partial h(\rho_0, z)}{\partial \rho} \right] \right] + \int_{[0,T_F]} \frac{(-dQ) \epsilon_z(t)}{\epsilon(t)} - \int_{[0,T_F]} \frac{(-d\hat{Q}) \hat{\epsilon}_z(t)}{\epsilon(t)} \right\}
\]

The term \( \int_{[0,T_F]} \frac{(-dQ) \epsilon_z(t)}{\epsilon(t)} - \int_{[0,T_F]} \frac{(-d\hat{Q}) \hat{\epsilon}_z(t)}{\epsilon(t)} \) is similar to an expression of the form $ab-\hat{a}b$ where $a, b$ are two theoretical functions and $\hat{a}, \hat{b}$ the empirical corresponding functions. A classical approach is to write $ab-\hat{a}b = a(b-\hat{b}) + b(a-\hat{a}) + (\hat{a}-a)(b-\hat{b})$. In our case $(a-\hat{a}) (b-\hat{b})$ will be a quantity of order $\frac{1}{\sqrt{n}}$, therefore "negligible", and the terms $(a-\hat{a}), (b-\hat{b})$ will be asymptotically normal variables. More formally it will be shown in the appendix that $C_n$ can be expressed as:

\[
C_n = C_{1n} + C_{2n} + C_{3n} + C_{4n} + C_{5n} + C_{6n} + R_{1n} + R_{2n} + R_{3n} + R_{4n}
\]

where

\[
C_{1n} = \sqrt{n} \left[ \frac{1}{n} \sum_{i=1}^{n} \delta_i \frac{\partial h(\rho_0, z_i)}{\partial \rho} - E \left[ \frac{\delta}{h(\rho_0, z)} \frac{\partial h(\rho_0, z)}{\partial \rho} \right] \right]
\]

\[
C_{2n} = -\sqrt{n} \left[ \hat{Q}(0) - Q(0) \right] \frac{\epsilon_z(0)}{\epsilon(0)}
\]

\[
C_{3n} = -\sqrt{n} \int_{[0,T_F]} \frac{\hat{Q}(0) \epsilon_z}{\epsilon} d\epsilon
\]
We shall prove that $C_n$ is asymptotically distributed as a multivariate normal random variable in two steps:

**First step:** Let us consider the sum $S$ of the random terms in $D_n$.

\[
C_{4n} = \int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon^2} \, d\varepsilon \quad ; \quad C_{5n} = \int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d\varepsilon \\
C_{6n} = -\int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d\varepsilon
\]

\[
R_{1n} = \int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d(\hat{Q} - Q) \\
R_{2n} = -\int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d\varepsilon \\
R_{3n} = -\int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d(\hat{Q} - Q) \\
R_{4n} = \int_{[0,T_F]} \frac{\sqrt{n} (\hat{Q} - Q) \varepsilon_z}{\varepsilon} \, d\varepsilon
\]

$C_{4n}$ is asymptotically distributed as a multivariate normal random variable with covariance matrix $\Sigma$ and mean 0.

**2nd step:** $R_{1n}, R_{2n}, R_{3n}, R_{4n}$ go to 0 in probability.

**First step:** Let us consider the sum $S$ of the random terms in $D_n$. 
Rewriting this we have:

\[ S = \sqrt{n} \left\{ \frac{1}{n} \sum_{i=1}^{n} \frac{\partial}{\partial \rho_i} h(\rho_i, z_i) \right. \left. - \frac{1}{n} \sum_{i=1}^{n} \frac{\partial h(\rho_i, z_i)}{\partial \rho_i} \right\} \varepsilon(z) + \int_{0}^{T_F} \frac{\hat{Q}}{\varepsilon} \, d\varepsilon_z + \int_{0}^{T_F} \frac{\hat{Q}}{\varepsilon} \, d\varepsilon - \int_{0}^{T_F} \frac{\varepsilon}{\varepsilon^2} \, d\varepsilon \right\} \]

Therefore \( S \) is a sum of independent, identically distributed random vectors.

Then \( S \) is asymptotically distributed as a M.V.N \((0, \Sigma)\).

2nd step: \( R_{ln}, R_{2n}, R_{3n}, R_{4n} \), go to 0 in probability:

In the following we shall consider only the kth coordinate of \( R_{ln} \), \((k = 1, \ldots p)\).

1) Let us consider \( R_{2n} \):

\[ R_{2n} = -\sqrt{n} \left( \frac{\hat{\varepsilon}_2 - \varepsilon_2}{\hat{\varepsilon}_2} \right) d\varepsilon \]

When \( N \) goes to \( +\infty \), \( \hat{\varepsilon} (T_f) \) converges to \( \varepsilon (T_f) \). We assumed that \( \varepsilon (T_f) > 0 \). Let \( \varepsilon_1 \) be given such that \( 0 < \varepsilon_1 < \varepsilon (T_f) \).

Then there exists \( N_1 \) such that for any \( N > N_1 \), \( \hat{\varepsilon}(T_f) \geq \varepsilon (T_f) - \varepsilon_1 \).
Since for any $t$ such that $t \leq T_F$ we have

$$\mathcal{E}(t) \geq \mathcal{E}(T_F) \quad ; \quad \mathcal{E}'(t) \geq \mathcal{E}'(T_F).$$

Lemma 5 proved that

$$\sup_{t} n^{1/4} \left( \hat{\mathcal{E}}_z(t) - \mathcal{E}_z(t) \right) \quad , \quad \sup_{t} n^{1/4} \left( \hat{\mathcal{E}}(t) - \mathcal{E}(t) \right)$$

go to 0 in probability.

Therefore

R2n goes to 0 in probability

2) A similar argument shows that R4n goes to 0 in probability.

3) Consider R1n = \[ \int_{[0,T_F]} \sqrt{n} \left[ \hat{\mathcal{E}}_z(t) - \mathcal{E}_z(t) \right] d(\hat{\mathcal{Q}} - Q) \]

As in lemma 5, let Zn(t) = \[ \sqrt{n} \left[ \hat{\mathcal{E}}_z(t) - \mathcal{E}_z(t) \right] \] and let Z(t) be the Gaussian process limit of Zn(t).

Therefore

\[ R_{1n} = \int_{[0,T_F]} \frac{Z_n(t)}{\hat{\mathcal{E}}(t)} d(\hat{\mathcal{Q}} - Q) \]
\[ R_{1n} = \int_{[0,T_F]} \frac{Z_n(t)-Z(t)}{\hat{\mathcal{E}}} d(\hat{\mathcal{Q}} - Q) + \int_{[0,T_F]} Z \left( \frac{1}{\hat{\mathcal{E}}} - \frac{1}{\mathcal{E}} \right) d(\hat{\mathcal{Q}} - Q) + \int_{[0,T_F]} \frac{Z}{\mathcal{E}} d(\hat{\mathcal{Q}} - Q) \]
Since we have proved the weak convergence of \( Z_n(t) \) to \( Z(t) \) for \( \rho \) fixed, it is possible (Skorokhod (1956)) to construct processes \( X_n(t, \omega, \rho) \) and \( X(t, \omega, \rho) \), possibly on a new probability space, such that the finite dimensional distributions of \( X_n(t, \omega, \rho) \) and \( Z_n(t, \omega, \rho) \), of \( Z(t, \omega, \rho) \) and \( X(t, \omega, \rho) \) are the same, such that \( X_n(t, \omega, \rho) \) and \( X(t, \omega, \rho) \) belong to \( \mathcal{D} \) for every \( \omega \) in a subspace \( \Omega_\rho(\rho) \) depending on \( \rho \) such that \( \mathbb{P}[\Omega_\rho(\rho)]=1 \) and such that \( X_n(t, \omega, \rho) \) converges to \( X(t, \omega, \rho) \) for every \( \omega \) in \( \Omega_\rho(\rho) \).

\[
A = \int_0^{\tau_F} \frac{Z_n(t) - Z(t)}{\hat{\xi}} \, d(\hat{\mathbb{Q}} - \mathbb{Q}) \\
B = \int_0^{\tau_F} Z(t) \frac{\xi - \hat{\xi}}{\hat{\xi} \xi} \, d(\hat{\mathbb{Q}} - \mathbb{Q}) \\
C = \int_0^{\tau_F} Z \, d(\hat{\mathbb{Q}} - \mathbb{Q})
\]
Therefore \( Z_n(t,w) \) converges almost surely to \( Z(t,w) \) with the Skorokhod topology in \( D \), (after the Skorokhod construction). Billingsley (1968) shows that the convergence to a continuous limit, as \( Z(t) \) is, in the Skorokhod topology is equivalent to uniform convergence. Therefore if \( p_T(Z_n,Z) = \sup_t p(Z_n,Z) \), 
\( p_T(Z_n,Z) \) converges to 0. As before there exists \( N_1 \) such that, for any \( N > N_1 \), \( \hat{E}(T_F) \geq E(T_F) - \varepsilon \).

First term:

\[
A = \int_{[0,T_F]} \frac{Z_n(t) - Z(t)}{\varepsilon} d(\hat{Q} - Q)
\]

|A| \leq \frac{p_T(Z_n,Z)}{(E(T_F) - \varepsilon)} \left[ \left| \int_{[0,T]} d\hat{Q} \right| + \left| \int_{[0,T_F]} dQ \right| \right]

\[
\left| \int_{[0,T]} d\hat{Q} \right| + \left| \int_{[0,T_F]} dQ \right| \leq 2
\]

Therefore \( |A| \) converges to 0.

Second term: 

\[
B = \int_{[0,T_F]} Z(t) \frac{\varepsilon - \hat{E}}{\varepsilon} d(\hat{Q} - Q)
\]

By the same arguments as before:

\[
|B| \leq \frac{p_T(Z,0)}{E(T_F)} \frac{p_T(\varepsilon,\hat{E})}{(E(T_F) - \varepsilon)} \left| \int_{[0,T_F]} d(\hat{Q} - Q) \right|
\]
But as before

\[ \left| \int_{[0,T_f]} \frac{Z(t)}{\varepsilon} d(\hat{Q} - Q) \right| \leq 2 \]

Lemma 5 yields that \( r_\varepsilon (\varepsilon, \hat{\varepsilon}) \) converges to 0 in probability.

Therefore \( B \) converges to 0 in probability.

Third term: \( C = \int_{[0,T_f]} \frac{Z(t)}{\varepsilon} d(\hat{Q} - Q) \)

Consider a subset \( \Omega_0 \) of the underlying probability space such that:

1. \( P[\Omega_0] = 1 \)
2. for \( \omega \in \Omega_0 \), \( Z \) is uniformly continuous in \((0, T_f)\)

Choose a partition (depending on \( \omega \)) of \([0, T_f]\) into \( K_0 \) intervals \( I_k = \left[ \xi_{k-1}, \xi_k \right] \) such that

\[
\sup_{t \in I_k} \left| \frac{Z(t)}{\varepsilon(t)} - \frac{Z(\xi_k)}{\varepsilon(\xi_k)} \right| < \varepsilon \quad (k = 1, \ldots, K_0)
\]

\( K_0 \) is fixed given \( \varepsilon \).

Then:

\[
C = \int_{[0,T_f]} \frac{Z(t)}{\varepsilon(t)} \left( \int_{[0,T_f]} \frac{Z(t)}{\varepsilon(t)} \frac{d(\hat{Q} - Q)}{\varepsilon(\xi_k)} \right)
\]
But we have the inequalities:

\[
\frac{k^{-1}}{k=0} Z(\xi_{k+1}) \int_{\xi_k}^{\xi_{k+1}} d(\hat{Q} - Q) \leq \varepsilon \int_{\xi_k}^{\xi_{k+1}} \sup_{t \in I_{k+1}} \left( \frac{Z}{\varepsilon} - \frac{Z(\xi_{k+1})}{\varepsilon(\xi_{k+1})} \right) d(\hat{Q} - Q) \leq A
\]

and

\[
C \leq \frac{k^{-1}}{k=0} Z(\xi_{k+1}) \left[ \hat{Q}(\xi_{k+1}) - Q(\xi_{k+1}) - (\hat{Q}(\xi_k) - Q(\xi_k)) \right]
+ \frac{k^{-1}}{k=0} \int_{\xi_k}^{\xi_{k+1}} \sup_{t \in I_{k+1}} \left( \frac{Z}{\varepsilon} - \frac{Z(\xi_{k+1})}{\varepsilon(\xi_{k+1})} \right) d(\hat{Q} - Q)
\]

The second term is bounded by \(2 \varepsilon\).

The first term can be rewritten as:

\[
\frac{Z(\xi_k)}{\varepsilon(\xi_k)} \left[ \hat{Q}(\xi_k) - Q(\xi_k) \right] + \frac{\varepsilon}{Z} \left[ \frac{Z(\xi_k)}{\varepsilon(\xi_k)} - \frac{Z(\xi_{k-1})}{\varepsilon(\xi_{k-1})} \right] \left[ \hat{Q}(\xi_{k-1}) - Q(\xi_{k-1}) \right]
+ \frac{Z(\xi_1)}{\varepsilon(\xi_1)} \left[ \hat{Q}(0) - Q(0) \right]
\]

Therefore the first term is bounded by

\[
(k^{-1}) \varepsilon \rho_T(\hat{Q}, Q) + 2 \rho_T(\frac{Z}{\varepsilon}, 0) \rho_T(\hat{Q}, Q)
\]

Hence \(|C|\) is bounded by:

\[
2 \varepsilon + \left[ (k^{-1}) \varepsilon + 2 \rho_T(\frac{Z}{\varepsilon}, 0) \right] \rho_T(\hat{Q}, Q)
\]
Lemma 5 implies that $p_n(Q, Q)$ converges to 0 when $N$ goes to $+\infty$. As $\xi$ was arbitrary, this implies $C$ converges to 0 in probability. Therefore:

\[ R_{ln} \text{ goes to 0 in probability } \]

4) $R_{3n}$ goes to 0 in probability by the same arguments as before.

We therefore have proved that:

\[ C_n = \sqrt{n} \left[ \frac{1}{n} \frac{\partial \phi_n}{\partial \beta} \right]_{\beta_0} \text{ is asymptotically distributed} \]
\[ \text{as a multivariate normal random variable.} \]

\[ B \text{ Second Step: Consider } \hat{\beta} = \frac{1}{n} \frac{\partial \phi_n}{\partial \beta_0} \]
\[ \hat{\beta} \text{ lies between } \hat{\beta}_n \text{ and } \beta_0. \]

We shall prove that $M$ converges to a finite limit in two steps:

First step: $\hat{M}_o = \frac{1}{n} \frac{\partial \phi_n}{\partial \beta_0}$ converges in probability to a finite limit $M_o$.

Second step:

The sequence \[ \left\{ \frac{1}{n} \frac{\partial \phi_n}{\partial \beta_0} \right\} \]

is equicontinuous in a neighbourhood of $\beta_0$.

It will therefore imply that $\hat{M}$ converges to $M_o$. 
First Step: convergence of $\hat{M}_o$.

$\hat{M}_o$ is equal to:

$$\hat{M}_o = \frac{1}{N} \sum_{i=1}^{N} \left\{ \frac{\frac{\partial^2 h}{\partial \theta^2}(\theta_0, z_i)}{h(\theta_0, z_i)} - \frac{\frac{\partial h}{\partial \theta}(\theta_0, z_i)}{h(\theta_0, z_i)} \right\}$$

$$+ \frac{1}{N} \sum_{i=1}^{N} \delta_i \left\{ \frac{\frac{1}{N} \sum_{j \in \mathcal{E}_i} \frac{\partial h}{\partial \theta}(\theta_0, z_j)}{\frac{1}{N} \sum_{j \in \mathcal{E}_i} h(\theta_0, z_j)} - \frac{\left[ \frac{1}{N} \sum_{j \in \mathcal{E}_i} \frac{\partial h}{\partial \theta}(\theta_0, z_j) \right]^2}{\left[ \frac{1}{N} \sum_{j \in \mathcal{E}_i} h(\theta_0, z_j) \right]^2} \right\}$$

An application of strong law of large numbers gives that the first term converges almost surely to

$$E \left[ \delta \left\{ \frac{\frac{\partial h}{\partial \theta}(\theta_0, z)}{h(\theta_0, z)^2} - \frac{\frac{\partial h}{\partial \theta}(\theta_0, z)}{h(\theta_0, z)} \right\} \right]$$

Now let us consider the second term.

We claim that

$$\hat{A} = \frac{1}{N} \sum_{i=1}^{N} \delta_i \frac{\frac{1}{N} \sum_{j \in \mathcal{E}_i} I(y_j \geq T_i) \frac{\partial h}{\partial \theta}(\theta_0, z_j)}{\frac{1}{N} \sum_{j \in \mathcal{E}_i} I(y_j \geq T_i) h(\theta_0, z_j)}$$

converges to:

$$M_A = E \left[ \delta \frac{E[I(y \geq t) \frac{\partial h}{\partial \theta}(\theta_0, z)]}{E[I(y \geq t) h(\theta_0, z)]} \right]$$

in probability.

Let us introduce some further notation:
\[ \hat{x}_n(t) = \sum_{j=1}^{n} \frac{\delta^j}{\delta \beta^j}(\beta_0, z) \]

\[ \bar{x}_n(t) = \mathbb{E} \left[ \frac{1}{n} \sum_{j=1}^{n} \frac{\delta^j}{\delta \beta^j}(\beta_0, z) \right] \]

\[ A = \frac{1}{N} \sum_{i=1}^{N} \frac{\epsilon_i(T_i)}{\hat{\epsilon}(T_i)} \]

Therefore

\[ \hat{A} = A = \frac{1}{N} \sum_{i=1}^{N} \left[ \frac{\hat{\epsilon}_i(T_i)}{\hat{\epsilon}(T_i)} - \frac{\epsilon_i(T_i)}{\epsilon(T_i)} \right] \]

Let us first prove the following lemma:

**Lemma:** \( a = \sup \left\{ \frac{\hat{x}_n(t)}{x(t)} - \frac{x_n(t)}{x(t)} \right\} \) converges in probability to 0.

We have

\[ \frac{\hat{x}_n(t)}{x(t)} - \frac{x_n(t)}{x(t)} = \frac{\hat{x}_n(t) - x_n(t)}{x(t)} + \frac{x_n(t)}{x(t)} \cdot \frac{x(t) - x_n(t)}{x(t)} \]

As we have seen in the preceding pages, for \( n \) large enough, \( \hat{x}(t) \geq x(T_F) - \epsilon_l \)

Therefore

\[ a \leq \frac{1}{(x(T_F) - \epsilon_l)} \sup \left\{ \frac{x_n(t) - x_n(t)}{x(t)} \right\} + \frac{\sup \epsilon_i(t)}{x(T_F)(x(T_F) - \epsilon_l)} \sup \left\{ \hat{x}(t) - x(t) \right\} \]

**Lemma 5** yields that \( \sup \left\{ \frac{x_n(t) - x_n(t)}{x(t)} \right\} \) and
\[
\sup_t |\hat{\varepsilon}(t) - \varepsilon(t)| \quad \text{converges in probability to 0.}
\]

Therefore a converges in probability to 0.

We have then

\[
\left\| \hat{A} - A \right\| \leq \alpha \left( \frac{1}{n} \sum_{i=1}^{n} \delta_i \right)
\]

The strong law of large numbers yields that \( \left( \frac{1}{n} \sum_{i=1}^{n} \delta_i \right) \) converges almost surely to \( E(\delta) \).

Therefore \( \hat{A} \) converges to \( A \) in probability.

Another application of the strong law of large numbers gives us that \( A \) converges to \( M \).

Now let us consider

\[
\hat{B} = \frac{1}{N} \sum_{i=1}^{N} \delta_i \frac{\hat{\varepsilon}_z(T_i)}{E(T_i)}
\]

Let us prove that has the same limit as \( B = \frac{1}{N} \sum_{i=1}^{N} \delta_i \frac{\varepsilon_z(T_i)}{E(T_i)} \).

\[
\hat{B} - B = \frac{1}{N} \sum_{i=1}^{N} \delta_i \left[ \frac{\hat{\varepsilon}_z(T_i)}{E(T_i)} - \frac{\varepsilon_z(T_i)}{E(T_i)} \right] \left[ \frac{\hat{\varepsilon}_z(T_i)}{E(T_i)} + \frac{\varepsilon_z(T_i)}{E(T_i)} \right]
\]

Therefore

\[
\left\| \hat{B} - B \right\| \leq \sup_t \left| \frac{\hat{\varepsilon}_z(t)}{E(t)} - \frac{\varepsilon_z(t)}{E(t)} \right| \frac{1}{N} \sum_{i=1}^{N} \delta_i \left| \frac{\hat{\varepsilon}_z(T_i)}{E(T_i)} + \frac{\varepsilon_z(T_i)}{E(T_i)} \right|
\]

By arguments similar to those of the preceding paragraph,
it can be proved that $\sup_{t} \left| \frac{\hat{E}_2(t)}{E(t)} - \frac{E_2(t)}{E(t)} \right|$ converges to

$0$ and $\frac{1}{N} \sum_{i=1}^{N} \left| \frac{\hat{E}_2(T_i)}{E(T_i)} + \frac{E_2(T_i)}{E(T_i)} \right|$ converges to a finite limit. Therefore $\hat{B}$ and $B$ have the same limit. The strong law of large numbers yields that $B$ converges almost surely to $E \left[ \delta \frac{E_2(t)}{E(t)^2} \right]$.

Therefore $M$ converges in probability to:

$$M_0 = E \left[ \delta \left( \frac{\partial h(p,z)}{\partial p} \frac{\partial^2 h(p,z)}{\partial p^2} \right) \right] + E \left[ \delta \frac{E \left[ 1(y \geq t) \frac{\partial h(p,z)}{\partial p} \right]^2}{E \left[ 1(y \geq t) h(p,z) \right]^2} \right]$$

$$- E \left[ \delta \frac{E \left[ 1(y \geq t) \frac{\partial^2 h(p,z)}{\partial p^2} \right]^2}{E \left[ 1(y \geq t) h(p,z) \right]^2} \right]$$

2nd step: \[\left\{ - \frac{1}{N} \frac{\partial^3 \phi_n}{\partial p^3} \right\} \] are equicontinuous functions of $p$ in a neighbourhood of $p_0$. In order to demonstrate this we prove that $\frac{\partial \phi_n}{\partial p^3}$ is bounded in a neighbourhood of $p_0$.\]
First let us compute \( A = \frac{\partial^3 \Phi_n}{\partial \beta^3} \)

\[
A = \frac{1}{n} \sum_{i=1}^{n} \left\{ \frac{\frac{1}{n} \sum_{j \in i} \frac{\partial^3 h}{\partial \beta^3}(\beta, z_j)}{\frac{1}{n} \sum_{j \in i} h(\beta, z_j)} - 3 \left[ \frac{\frac{1}{n} \sum_{j \in i} \frac{\partial h}{\partial \beta}(\beta, z_j)}{\frac{1}{n} \sum_{j \in i} h(\beta, z_j)} \right]^2 \right. \\
+ 2 \left( \frac{\frac{1}{n} \sum_{j \in i} \frac{\partial h}{\partial \beta}(\beta, z_j)}{\frac{1}{n} \sum_{j \in i} h(\beta, z_j)} \right)^3 \left\} \right.
\]

In the chapter on consistency we prove there was a neighbourhood of \( \beta^* \) in which, for \( n \) large enough, \( \frac{1}{n} \sum_{j \in i} h(\beta, z_j) \) was bounded for each risk set \( R_i \) by a constant \( m \).

In this chapter on Asymptotic Normality, we assumed that \( \frac{\partial h}{\partial \beta}, \frac{\partial^2 h}{\partial \beta^2}, \frac{\partial^3 h}{\partial \beta^3} \) were monotone functions in \( \beta \) for \( z \) fixed for any \( i \).

We therefore can prove by arguments similar to those we used to prove that \( \{ \Phi_n(\beta) \} \) was an equicontinuous sequence for \( n \) large enough, that

\[
\left\| \frac{\partial \Phi_n}{\partial \beta} \right\|, \left\| \frac{\partial^2 \Phi_n}{\partial \beta^2} \right\|, \left\| \frac{\partial^3 \Phi_n}{\partial \beta^3} \right\|
\]

are bounded in a neighbourhood of \( \beta^* \). This then implies that

\[
\left\| \frac{\partial^3 \Phi_n}{\partial \beta^3} \right\| \text{ is bounded in a neighbourhood of } \beta^* .
\]
Therefore the sequence \( \left\{ -\frac{1}{N} \frac{\partial^2 \Phi_n}{\partial \beta^2} \right\} \) is an equicontinuous sequence.

This proves that the matrix

\[
\hat{M} = -\frac{1}{N} \frac{\partial^2 \Phi_n}{\partial \beta^2}
\]

converges to:

\[
M_0 = E \left[ \int \frac{\left( \frac{\partial h}{\partial \beta}(\beta, z) \right)^2}{h(\beta, z)} \right]
\]

\[
+ E \left[ \left( \frac{E[i(y > t) h(\beta, z)] E[i(y > t) \frac{\partial h}{\partial \beta}(\beta, z)]}{E[i(y > t) h(\beta, z)]^2} \right) \right]
\]

C Covariance structure:

The variance-covariance matrix of \( \left( \frac{\partial \Phi_n}{\partial \beta} \right)_{\beta_0} \) is the variance-covariance matrix of the random vector \( x \) where:

\[
X = \int \frac{\partial h}{\partial \beta}(\beta, z) z - \int \frac{\partial \epsilon}{\partial \epsilon}(\epsilon) \int \frac{1(y > t)}{\epsilon} d\epsilon
\]

\[
+ \int \frac{\epsilon}{\epsilon^2} \left( \frac{1(y > t)}{\epsilon} \right) d\epsilon + \frac{\partial h}{\partial \beta}(\beta, z) \int \frac{1(y > t)}{\epsilon} dQ
\]

\[
- h(\beta, z) \int \frac{\epsilon}{\epsilon^2} \left( \frac{1(y > t)}{\epsilon} \right) d\epsilon
\]
Therefore

\[
X = \frac{\delta}{h(\beta_0, z)} \frac{\partial h(\beta_0, z)}{\partial \beta} + \frac{\delta \varepsilon_2(y)}{\varepsilon(y)} - h(\beta_0, z) \int_{[0, T_F]} \frac{\varepsilon_2 1(y \geq t) d \varepsilon}{\varepsilon(y)} + \frac{\partial h(\beta_0, z)}{\partial \beta} \int_{[0, T_F]} \frac{1(y \geq t) d \varepsilon}{\varepsilon(t)}
\]

Provided that \( M \) is regular, the variance-covariance matrix \( V \) of \( \sqrt{n} (\hat{\beta}_n - \beta_0) \) is then:

\[
V = (M_0^{-1})' \Phi^2(M_0^{-1})
\]

A consistent estimator of \( M \) is given by

\[
M = \left( \int_{[0, T_F]} dQ \right) \text{Var}(\varepsilon | \varepsilon(t)) = \left( \int_{[0, T_F]} dQ \right) \left[ \frac{E[\varepsilon^2 e^{i(y \geq t)}]}{E[e^{i(y \geq t)}]^2} - \frac{E[\varepsilon e^{i(y \geq t)}]}{E[e^{i(y \geq t)}]} \right]^2
\]

In this case \( \sqrt{n} (\hat{\beta}_n - \beta_0) \) converges in distribution to a normal random variable with mean 0 and variance
equal to \( \left[ \int_{(0,T_F)} (\omega Q) \, \text{Var}(z \mid \alpha(t)) \right]^{-1} \). As a consistent estimator of that variance is available, the construction of confidence intervals is straightforward. Unfortunately in our multiparameter general case some further work is needed to find a consistent estimator of \( \xi \).
Chapter 4: Extension and Problems:

In the first part of the chapter, we shall outline the proof of the asymptotic normality when the covariates are given constants. In the second part a problem encountered during the simulation studies will be discussed.

Part A: Consistency of Cox's estimate when the covariates are given constants.

In this case our arguments will be conditional on the covariates. $z_1, z_2, \ldots z_n$ are given constants. Let us introduce the notation $E_i(f(t,z)) = E(f(t,z)|z_i)$. For reasons of simplicity, we shall only consider the exponential case. Hence the Cox likelihood can be written:

$$\phi_n(\lambda) = \frac{1}{N} \sum_{i=1}^{N} p^i z_i - \frac{1}{N} \sum_{i=1}^{N} \log \left[ \frac{1}{N} \sum_{j=1}^{N} 1(y_j > \tau_i) e^{\lambda z_i} \right]$$

Recall Kolmogorov's proposition: if the r.v.'s $X_n$ are independent, then

$$\frac{1}{n^2} \leq \text{Var} X_n < +\infty$$

entails

$$\frac{1}{n} \left( \pm X_n - \pm E X_n \right) \xrightarrow{a.s.} 0$$

Hence if

$$f_n(T) = \frac{1}{N} \sum_{j=1}^{N} I(y_j > T) e^{\lambda z_j}$$

almost surely to

$$\tilde{f}_n(T) = \frac{1}{N} \sum_{j=1}^{N} E_i [I(y > T) e^{\lambda z}]$$

where the index $j$ means expectation conditional on $z_j$. 
By a method similar to the one used in chapter 2, we hope to prove that we can replace \( f_n(T_i) \) by \( \tilde{f}_n(T_i) \) in \( \Phi_n(\beta) \) under some assumptions. More precisely if

\[
\Phi_n^*(\beta) = \frac{1}{n} E \left[ \frac{1}{N} \sum_i E_i \left( \frac{1}{n} \sum_{j=1}^n E_j \left[ I(y \geq T_i) e^{\beta z} \right] \right) \right]
\]

\[
\Phi_n^*(\beta) - \Phi_n(\beta) \text{ converges a.s. to } 0.
\]

The random variables \( \tilde{X}_i = \frac{1}{n} \sum_{j=1}^n E_j \left[ I(y \geq T_i) e^{\beta z} \right] \) are independent but depend on \( n \). Hopefully if:

\[
\tilde{\Phi}_n(\beta) = \frac{1}{n} \frac{1}{N} \sum_i E_i \left( \frac{1}{n} \sum_{j=1}^n E_j \left[ I(y \geq T_i) e^{\beta z} \right] \right)
\]

\[
\tilde{\Phi}_n(\beta) - \Phi_n(\beta) \text{ will converge a.s. to } 0.
\]

The notation used is the same as in the preceding chapters. Therefore \( \tilde{\Phi}_n(\beta) - \Phi(\beta) \) will converge a.s. to 0.

A) The true value \( \beta_0 \) is a maximum of \( \tilde{\Phi}_n(\beta) \):

This paragraph is an actual proof of \( \left( \frac{\partial \tilde{\Phi}_n}{\partial \beta} \right)_{\beta_0} = 0 \)

when \( \beta \) is of dimension 1. This proof can easily be extended to the case where \( \beta \) is a vector.
For reasons similar to the ones in chapter 2:

\[ E_i \left[ \sum_{j=1}^{n} \frac{1}{n} E_j \left[ (y > T_i) z e^{p_0^2} \right] \right] = \lim_{t \to \infty} \int_{t=0}^{t=+\infty} \lambda_0(t) E_i \left[ (y > t) z e^{p_0^2} \right] dt \]

Therefore:

\[ E_i \left[ S^i[z] \right] = \int_{t=0}^{t=+\infty} \lambda_0(t) E_i \left[ z e^{p_0^2 - 1(y > t)} \right] dt \]

Hence:

\[ \left( \frac{d \Phi_n}{d \beta} \right)_{p_0} = \int_{t=0}^{t=+\infty} \lambda_0(t) \left( \frac{1}{n} \sum_{j=1}^{n} E_j \left[ z e^{p_0^2 - 1(y > t)} \right] \right) dt \]

Therefore:

\[ \left( \frac{d \Phi_n}{d \beta} \right)_{p_0} = 0. \text{ The true value is a local maximum of } \Phi_n. \]

B) Concavity of Cox's likelihood:

The same arguments as when the covariates are i.i.d gives that:

\[ \frac{\gamma \Phi_n}{\gamma \beta^2} = \sum_{i=1}^{s_i} (\text{Variance-Covariance matrix of } z \text{ given } R_i) \]

Therefore \( \Phi_n \) is concave everywhere.
C) Consistency of Cox's estimate:

Our lemma 8 does not apply here as the function \( \hat{\phi}_n(p) \) depends on \( n \). Nevertheless it is not too hard to modify this lemma to prove that point wise convergence of \( (\phi_n - \hat{\phi}_n) \) to 0 implies uniform convergence on compacts for \( \phi_n, \hat{\phi}_n \) concave. If \( \hat{\phi}_n \) is asymptotically strictly concave it will be possible to prove that \( \hat{\beta}_n \) converges to the true value \( \beta_0 \) in probability.

Part B: Infinite Cox estimate of \( \beta \)

In this short chapter we would like to emphasize the dependance of the efficiency of the estimate on the variance of the covariates. A problem we encountered frequently in our simulation studies was that the estimate was infinite, especially when the variance of the covariate was large.

For simplicity let us consider the exponential case without censoring and the parameter having dimension 1. Let \( Z(i) \) be the covariate of the \( i \)th dying subject.

The Cox likelihood is built up by multiplying terms of the form

\[
\prod_{\kappa \in R_i} \frac{e^{pZ(i)}}{e^{\beta Z(k)}}
\]

The derivative of the log of this term is:

\[
\sum_{\kappa \in R_i} \left( \frac{Z(i) - Z(k)}{e^{pZ(k)}} \right) e^{pZ(k)}
\]
Therefore if we have the ordering

\[ Z(1) \succ Z(2) \ldots \ldots \succ Z(n) \]

Cox's likelihood is monotone and the estimate is infinite. The greater the difference between \( Zi = Z(k) \) and \( Zj = Z(l) \), is, the most probable it is that \( k < l \). Therefore if the variance of \( z \) is small the probability of the troublesome ordering happening is low, but if the variance is large this probability becomes close to 1, (at least for \( \beta \neq 0 \)).

Our simulation studies confirmed this heuristic argument. This gives an interesting insight on the result of Kalbfleisch (1974) mentioned on page 8. He shows that an approximate expression of the efficiency of the estimate is

\[
\exp\left\{ -\beta \text{Var}(z) \right\}
\]

valid near \( \beta = 0 \). The efficiency depends on \( \text{Var}(z) \).
A 1: Proof of lemma 1

\[ E[S|z] = E_t[E[S|z,t]] \quad \text{but} \quad E[S|z,t] = P[t \leq S|z,t] \]

and \( P[t \leq S|z,t] = G(t|z) \).

Hence

\[ E[S|z] = E_t[G(t|z)] \]

A 2: Proof of lemma 2

\[ f(w) = E[h(p,z) 1(y > w)] = E[h(p,z) E[1(\text{Min}(t,s) > w)|z]] \]

meanwhile

\[ E[1(\text{Min}(t,s) > w)|z] = \text{Prob}[\text{Min}(t,s) > w|z] \]

\( t \) and \( s \) are independent given \( z \). Therefore:

\[ P[\text{Min}(t,s) > w|z] = P[t > w|z] P[s > w|z] = G(w|z)(\exp-\int_0^w \lambda(u) h(p,z) du) \]

Hence:

\[ f(w) = E_z[h(p,z) G(w|z)(\exp-\int_0^w \lambda(u) h(p,z) du)] \]

A 3: Proof of lemma 3

\[ E[\delta \log f(t)] = E_{z,t,s}[\delta \log f(t)] = E_{z,t}[E_s[\delta \log f(t)|t,z]] \]

\[ E[\delta \log f(t)] = E_{z,t}[\log f(t) E_s[\delta|t,z]] \]

meanwhile \( E_s[\delta|t,z] = P[s > t|z] = G(t|z) \). Hence:

\[ E[\delta \log f(t)] = E_{z,t}[\log f(t) G(t|z)] \]
A 4: Proof of lemma 4

\[ g(w) = E[ S(\gamma > w) \big| z] = P[T(\tau > w) \big| z] \]

As \( \gamma = \min(\tau, s) = \tau \) when \( \tau < s \), \( g(w) = P[T(\tau > w) \big| z] \).

Meanwhile

\[ P[T(\tau > w) \big| z] = E_{\tilde{t}} \left[ P[t(\tau > w) \big| z, \tilde{t}] \right] \]

Hence:

\[ E[S \gamma > w \big| z] = \int_{t=0}^{\infty} \lambda_0(t) h(p, z) G(t|z) \left( \exp - \int_0^t \lambda(u) h(p, z) du \right) dt \]

A 5: Proof of

\[ M(t) = \int_{x=-\infty}^{\infty} \int_{z=x}^{z=+\infty} \left[ \frac{\partial h(p, z)}{h(p, z)} - \frac{\partial h(p, x)}{h(p, x)} \right] d\mu(t, z, x) \]

We have \( M(t) = A_1(t) - A_2(t) \) where

\[ A_1(t) = \int E_z \left[ h(p, z) \left( \exp - \int_0^t \lambda(u) h(p, z) du \right) G(t|z) \right] \cdot E_z \left[ \frac{\partial h}{\partial p} \right] G(t|z) \exp - \int_0^t \lambda(u) h(p, z) du \]

\[ A_2(t) = \int E_z \left[ \frac{\partial h}{\partial p} \right] G(t|z) \exp - \int_0^t \lambda(u) h(p, z) du \right] \]

Recall \( \xi(z) \) is the density of \( z \).

Let \( a(t, x) = G(t|x) \left( \exp - \int_0^t \lambda(u) h(p, x) du \right) \xi(x) \)

Hence:
$$A_i(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \frac{\partial h(p_0,z)}{\partial p} \right\} \left\{ h(p_0,x) a(t,x) h(p_0,z) a(t,z) \right\} \, dx \, dz.$$ 

Let 
$$d\nu(t,z,x) = a(t,x) h(p_0,x) a(t,z) h(p_0,z) \, dx \, dz$$

Then, 

$$A_i(t)$$ can be written as 
$$A_i(t) = K_i(t) + K_2(t)$$

where 

$$K_i(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \frac{\partial h(p_0,z)}{\partial p} \right\}^2 \, d\nu(t,z,x)$$

and

$$K_2(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \frac{\partial h(p_0,z)}{\partial z} \right\}^2 \, d\nu(t,z,x)$$

But 

$$K_2(t)$$ can be written as:

$$K_2(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \frac{\partial h(p_0,z)}{\partial z} \right\}^2 \, d\nu(t,z,x)$$

As 

$$d\nu(t,z,x) = d\nu(t,z,x)$$,

$$A_i(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \left[ \frac{\partial h(p_0,z)}{\partial p} \right]^2 + \left[ \frac{\partial h(p_0,z)}{\partial z} \right]^2 \right\} \, d\nu(t,z,x)$$

Similarly it can be proved that:

$$A_2(t) = \int_{x=-\infty}^{x=+\infty} \int_{z=-\infty}^{z=+\infty} \left\{ \left[ \frac{\partial h(p_0,z)}{\partial p} \right] \left( \frac{\partial h(p_0,z)}{\partial p} \right) + \left[ \frac{\partial h(p_0,z)}{\partial z} \right] \left( \frac{\partial h(p_0,z)}{\partial z} \right) \right\} \, d\nu(t,z,x)$$
Proof of
\[ E \left[ \left( Z_n(t) - Z_n(t) \right)^2 \left( Z_n(t_1) - Z_n(t) \right)^2 \right] \leq c_4 \left[ F(t_1) - F(t) \right]^{4/3} \]

where
\[ F(t) = P[Y \leq t] \quad \text{and} \quad 0 \leq t_1 \leq t \leq t_2. \]

Let \( p_1 = F(t) - F(t_1) \) and \( p_2 = F(t_2) - F(t) \), it yields \( F(t_2) - F(t_1) = p_1 + p_2 \).

As \( F \) is monotone, \( 0 \leq p_1, p_2 \leq (p_1 + p_2)^{1/3} \).

\[ Z_n(t_1) - Z_n(t) = \frac{1}{\sqrt{n}} \sum_{j=1}^{n} \left[ h(\rho, z_j) \left[ 1(y_j > t_1) - 1(y_j > t) \right] - E \left[ 1(y_j > t_1) - 1(y_j > t) \right] h(\rho, z_j) \right] \]

But \( 1(y_j > t_1) - 1(y_j > t) = 1(y_j \in [t_1, t]) \).

Consider
\[ U_{i_1} = h(\rho, z) 1(y_i \in [t_1, t]) - E \left[ 1(y \in [t_1, t]) h(\rho, z) \right] \]
\[ U_{i_2} = h(\rho, z) 1(y_i \in [t, t_2]) - E \left[ 1(y \in [t, t_2]) h(\rho, z) \right] \]

Therefore \[ Z_n(t_1) - Z_n(t) = \frac{1}{\sqrt{n}} \sum_{j=1}^{n} U_{i_1} , \quad Z_n(t) - Z_n(t_2) = \frac{1}{\sqrt{n}} \sum_{j=1}^{n} U_{i_2} \]

It yields that:
\[ E \left[ \left( Z_n(t_1) - Z_n(t) \right)^2 \left( Z_n(t_1) - Z_n(t) \right)^2 \right] \leq \frac{1}{n^2} E \left[ \sum_{i=1}^{n} U_{i_1}^2 \right] \left( \sum_{i=1}^{n} U_{i_2}^2 \right) \]

The random vectors \( (U_{i_1}, U_{i_2}) \) are independent and
\[ E[U_{i_1}] = 0. \] It can be proved that
\[ E \left[ \left( \frac{1}{\sqrt{n}} U_{i_1} \right) \left( \frac{1}{\sqrt{n}} U_{i_2} \right) \right] = \frac{1}{n} E[U_{i_1}^2] + \frac{1}{n(n-1)} E[U_{i_1}^2] E[U_{i_2}^2] + \frac{2}{n(n-1)} E[U_{i_1} U_{i_2}]. \]
let $\mathcal{I}_t=\{Y_i \in [t,t+\epsilon]\}$ and $\mathcal{I}_z=\{Y_i \in [t,t+\epsilon]\}$.

\[
U_{i,t} = \left[ h(\beta, z_i) \mathcal{I}_t - E[h(\beta, z_i) \mathcal{I}_t] \right]^2 = \left[ h(\beta, z_i) - E[h(\beta, z_i) | \mathcal{I}_t] \right]^2 \mathcal{I}_t + E[h(\beta, z_i) | \mathcal{I}_t] \mathcal{I}_t
\]

Recall Holder's inequality: $E[XY] \leq E[X^r]^\frac{1}{r} E[Y^s]^\frac{1}{s}$ where $\frac{1}{r} + \frac{1}{s} = 1$. Here let $r=\frac{3}{2}$ and $s=3$. Then,

\[
E[h(\beta, z) | \mathcal{I}_t] \leq E[\mathcal{I}_t]^{\frac{2}{3}} E[h(\beta, z)]^\frac{1}{3}
\]

but $\mathcal{I}_t = \mathcal{I}_t$. Let $p_1 = E[\mathcal{I}_t]^{\frac{1}{3}}$ and $c_1 = E[h(\beta, z)]$, then

\[
E[h(\beta, z) | \mathcal{I}_t] \leq c_1 p_1^{\frac{1}{3}}
\]

\[
E[h(\beta, z) | \mathcal{I}_z] \leq c_1 p_2^{\frac{2}{3}}
\]

Now

\[
E[U_{i,t} U_{i,z}^*] \leq c_1^{\frac{4}{3}} p_1^{\frac{2}{3}} E[\mathcal{I}_t \mathcal{I}_z] + c_1^{\frac{4}{3}} p_1^{\frac{2}{3}} E[(h(\beta, z) - E[h(\beta, z) | \mathcal{I}_t])^2 | \mathcal{I}_t, \mathcal{I}_z] + c_1^{\frac{4}{3}} p_2^{\frac{2}{3}} E[(h(\beta, z) - E[h(\beta, z) | \mathcal{I}_z])^2 | \mathcal{I}_z, \mathcal{I}_z]
\]

\[
E[\mathcal{I}_t \mathcal{I}_z] = 1 - p_1 - p_2
\]

\[
E[h(\beta, z) | \mathcal{I}_t] = \mathbb{E}[h(\beta, z) | \mathcal{I}_t]
\]

\[
E[h(\beta, z) | \mathcal{I}_z] = \mathbb{E}[h(\beta, z) | \mathcal{I}_z]
\]

\[
E[U_{i,t}^* U_{i,z}] \leq m p_1^{\frac{2}{3}} p_2^{\frac{2}{3}}
\]

m being a suitable constant.
Similarly:

\[ E[u_1^2] E[u_2^2] \leq c_3 p_1^{2/3} p_2^{2/3} \]

Thus being a suitable constant

\[ E[u_1 u_2] = E[h(\alpha, \beta \xi_1 - E[h(\alpha, \beta \xi_2)](h(\alpha, \beta \xi_1 - E[h(\alpha, \beta \xi_2)]) \]

Therefore

\[ E[u_1 u_2] = -E[h(\alpha, \beta \xi_1)] E[h(\alpha, \beta \xi_2)] \leq c_1 p_1^{2/3} p_2^{2/3} \]

But:

\[ E[(Z_n(t) - Z_n(t_1))^2 (Z_n(t_2) - Z_n(t_2))^2] \leq E[u_1^2 u_2^2] + E[u_1^2] E[u_2^2] + 2 E[u_1 u_2]^2 \]

Hence for a suitable constant \( C_4 \)

\[ E[(Z_n(t) - Z_n(t_1))^2 (Z_n(t_2) - Z_n(t_2))^2] \leq C_4 \left[ F(t_2) - F(t_1) \right]^{4/3} \]

A 7: Proof of lemma 7:

First step: for \( N \) large enough, \( (\Phi_n(p)) \)

have a common lower-bound on a hypercube

included in the compact \( K \).

Let us consider a hypercube \( C \) included in \( K \):

\[ C = \left\{ \beta \in \mathcal{K} : (V_k = 1, \ldots, p) | \beta - \beta^* | \leq d \right\} \]

where \( \beta^* \) is the kth coordinate of \( \beta \). Define the hull

\[ \bar{C} = \left\{ \beta : (V_k = 1, \ldots, p) | \beta - \beta^* | = d \right\} \]

Let \( S_e \) be the set of extreme points of \( \bar{C} \). \( S_e \) has \( 2^p \) elements. Let \( \varepsilon \) be fixed. For each point \( x_i \) belonging
to be \( \left( \exists N_i \right) \left( \forall N > N_i \right) \left| \Phi_n(x_i) - \Phi(x_i) \right| < \xi \). Then for \( N > N_0 = \sup N_i \), for each point \( x_i \) of \( S_\infty \), \( \Phi_n(x_i) \) has a lower-bound \( m \) independent of \( x_i \).

Now let us consider \( y \in (x_i, x_j) \) where \( x_i \) and \( x_j \) are two extreme points. Let \( A \) be the set of all such points \( y \). \( \Phi_n(x) \) is concave on the line \( (x_i, x_j) \). Therefore

\[ \Phi_n(y) \geq \inf \{ \Phi_n(x_i), \Phi_n(x_j) \} > m \]

For each point \( y \) of \( A \), \( \Phi_n(y) \geq m \).

Consider \( x \in \overline{C} \), \( x \) is on the line joining \( y_k \), point of \( A \), to \( y_l \), another point of \( A \). \( \Phi_n \) is concave on the line \( (y_k, y_l) \). Therefore

\[ \Phi_n(x) \geq \inf \{ \Phi_n(y_k), \Phi_n(y_l) \} > m \]

For each point \( x \) of \( \overline{C} \), \( \Phi_n(x) \geq m \).

Now consider \( x \in C \); \( x \) is on the line joining \( z_i \in \overline{C} \) to \( z_k \in \overline{C} \). Then by the reasons as before,

\( \Phi_n(x) \) is lower-bounded by \( m \) for \( N > N_0 \).

As \( \Phi_n \) is concave on \( C \), \( \Phi_n \) has one local maximum on \( C \): \( \hat{x}_n \) (maybe on the frontier). We shall prove \( \hat{x}_n \) converges to \( p_* \). Then for \( N \) large enough, \( \hat{x}_n \) is inside \( C \), \( \hat{x}_n \) is not on the frontier \( \overline{C} \). It yields that \( \hat{x}_n \) is the local maximum of \( \Phi_n \) not only on \( C \) but on \( K \). We shall then have proved that \( \Phi_n(p) \) has a maximum inside \( K \) and that that maximum converges to \( p_* \).

2nd step: \( \hat{x}_n \) converges to \( p_* \).

Let us prove it by contradiction: let us assume that \( \hat{x}_n \) does not converge to \( p_* \).

Let \( \xi \) be fixed.
There is a subsequence \( \{ \hat{x}_{n'} \} \) such that \((\forall n') \| \hat{x}_{n'} - p_0 \| > \varepsilon \)

Let us define \( y_{n'} \) such that:

\[
\begin{align*}
y_{n'} &= \lambda_{n'} \hat{x}_{n'} + (1 - \lambda_{n'}) p_0 \\
\| y_{n'} - p_0 \| &= \varepsilon
\end{align*}
\]

C is a compact. Then the sequence \( \{ y_{n'} \} \) has an accumulation point \( y_o \) in the compact C. Let us define a subsequence \( \{ y_{n_k} \} \) of \( \{ y_{n'} \} \) such that \( y_{n_k} \) converges to \( y_o \).

As \( p_0 \) is a local maximum of \( \Phi \), \( \Phi(p_0) > \Phi(y_o) \)

let \( \Phi(p_0) = \Phi(y_o) + \delta \). As \( \Phi_n(y_o) \) converges to \( \Phi(y_o) \)
and \( \Phi_n(p_0) \) converges to \( \Phi(p_o) \), we have

\[
(\exists N^*)(\forall n > N^*) \quad \begin{cases} 
\Phi(y_o) - \frac{\delta}{4} \leq \Phi_n(y_o) \leq \Phi(y_o) + \frac{\delta}{4} \\
\Phi(p_0) - \frac{\delta}{4} \leq \Phi_n(p_0) \leq \Phi(p_0) + \frac{\delta}{4}
\end{cases}
\]

\((\forall n) \Phi_n(y_o) > \Phi_n(p_0)\) as \( \hat{x}_n \) is maximum of \( \Phi_n \) concave

and \( y_n = \lambda_n \hat{x}_n + (1 - \lambda_n) p_0 \). Then

Let \( A = \{ u : \| y_o - u \| = d_2 \} \). We can choose \( d_2 \) such that

\( A \subset C \), as \((\forall n') \| y_{n'} - p_0 \| = \varepsilon \). Let \( u_n \in A \) such that

\[
\| u_n - y_o \| = d_2 = \| y_o - y_n \| 
\]

then \( \rho_n = \frac{d_2}{\| y_o - y_n \|} \to +\infty \)

\[
y_o = \frac{u_n}{1 + \rho_n} + \frac{\rho_n}{1 + \rho_n} y_n
\]

But \( y_o \in [u_n, y_n] \),

then from the concavity of \( \Phi_n \) :
\[
\frac{1}{1+\mu_n} \phi_n(u_n) + \frac{\mu_n}{1+\mu_n} \phi_n(y_n) \leq \phi_n(y_0) \leq \phi(y_0) + \frac{\delta}{4}
\]

Then

\[
\phi_n(u_n) \leq (1+\mu_n) \left[ \phi(y_0) + \frac{\delta}{4} \right] - \mu_n \phi_n(y_n)
\]

\[
\phi_n(u_n) \leq \phi(y_0) + \frac{\delta}{4} + \mu_n \left[ \phi(y_0) - \phi(p_0) + \frac{\delta}{2} \right]
\]

\[
\phi_n(u_n) \leq \phi(y_0) + \frac{\delta}{4} - \mu_n \frac{\delta}{2}
\]

But \(\mu_n \to \infty\); we then have a contradiction as \(\phi_n(u_n)\)
is bounded by \(m\) Then:

\[
\hat{\chi}_n \quad \text{converges to} \quad \hat{p}_0
\]

A8 Decomposition of \(C_n\) (page 62)

\[
A = \int_{[0,T_F]} d\hat{Q} \frac{\hat{\varepsilon}_z}{\hat{\varepsilon}} = \int_{[0,T_F]} d(Q-Q) \frac{\hat{\varepsilon}_z}{\hat{\varepsilon}} + \int_{[0,T_F]} dQ \frac{\hat{\varepsilon}_z}{\hat{\varepsilon}}
\]

We have:

\[
\frac{\hat{\varepsilon}_z}{\hat{\varepsilon}} = \frac{\varepsilon_z}{\varepsilon} + \frac{\hat{\varepsilon}_z - \varepsilon_z}{\hat{\varepsilon}} + \frac{\varepsilon_z [\varepsilon - \hat{\varepsilon}]}{\hat{\varepsilon} \varepsilon}
\]

Hence:

\[
A = \int_{[0,T_F]} \frac{\varepsilon_z}{\varepsilon} d(Q-Q) + \int_{[0,T_F]} \frac{\hat{\varepsilon}_z - \varepsilon_z}{\hat{\varepsilon}} d(Q-Q) + \int_{[0,T_F]} \frac{\varepsilon_z (\varepsilon - \hat{\varepsilon})}{\hat{\varepsilon} \varepsilon} d(Q-Q)
\]

\[
+ \int_{[0,T_F]} dQ \frac{\hat{\varepsilon}_z}{\hat{\varepsilon}}
\]
Now:
\[
\int_{[0,T_F]} \frac{\mathcal{E}_z}{\mathcal{E}} \, d(\mathcal{Q} - \mathcal{Q}) = \left[ \frac{\mathcal{E}_z}{\mathcal{E}} (\mathcal{Q} - \mathcal{Q}) \right]_{0}^{\mathcal{F}} - \int_{[0,T_F]} (\mathcal{Q} - \mathcal{Q}) \, d(\mathcal{E}_z)
\]

\[
= - \frac{\mathcal{E}_z(0)}{\mathcal{E}(0)} \left[ \mathcal{Q}(0) - \mathcal{Q}(0) \right] - \int_{[0,T_F]} (\mathcal{Q} - \mathcal{Q}) \, d\mathcal{E}_z + \int_{[0,T_F]} (\mathcal{Q} - \mathcal{Q}) \mathcal{E}_z \, d\mathcal{E}
\]

as \(Q(T_F) = Q(T_F) = 0\)

Moreover
\[
\int_{[0,T_F]} \frac{dQ}{\mathcal{E}} \frac{\mathcal{E}_z}{\mathcal{E}} = \int_{[0,T_F]} \frac{dQ}{\mathcal{E}} \mathcal{E}_z + \int_{[0,T_F]} \frac{(\mathcal{E}_z - \mathcal{E}_z)}{\mathcal{E}} \, dQ + \int_{[0,T_F]} \frac{\mathcal{E}_z [\mathcal{E} - \mathcal{E}]}{\mathcal{E}} \, dQ
\]

where
\[
\int_{[0,T_F]} \frac{\mathcal{E}_z - \mathcal{E}_z}{\mathcal{E}} \, dQ = \int_{[0,T_F]} \frac{\mathcal{E}_z - \mathcal{E}_z}{\mathcal{E}} \, dQ + \int_{[0,T_F]} \frac{(\mathcal{E}_z - \mathcal{E}_z)(\mathcal{E} - \mathcal{E})}{\mathcal{E} \mathcal{E}} \, dQ
\]

and
\[
\int_{[0,T_F]} \frac{\mathcal{E}_z [\mathcal{E} - \mathcal{E}]}{\mathcal{E} \mathcal{E}} \, dQ = \int_{[0,T_F]} \frac{\mathcal{E}_z [\mathcal{E} - \mathcal{E}]}{\mathcal{E} \mathcal{E}} \, dQ + \int_{[0,T_F]} \frac{\mathcal{E}_z [\mathcal{E} - \mathcal{E}]^2}{\mathcal{E} \mathcal{E} \mathcal{E}} \, dQ
\]

It therefore implies:

\[
C_n = C_{1n} + C_{2n} + C_{3n} + C_{4n} + C_{5n} + C_{6n} + R_{1n} + R_{2n} + R_{3n} + R_{4n}
\]


BIBLIOGRAPHY


